

LINEAR MOTION SYSTEMS



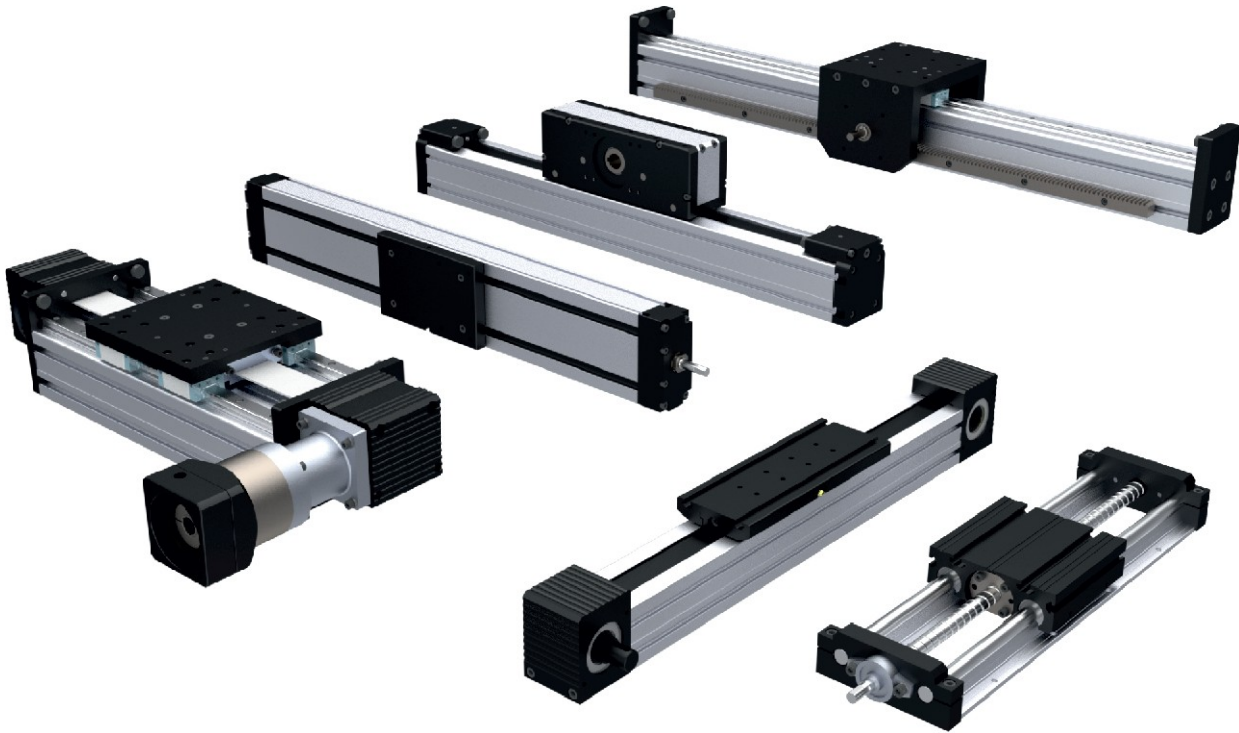
Mekatronik



Robotic



Machine



Linear Driven Systems
Axial Movements
Positioning

13 PRODUCT CATALOGUE

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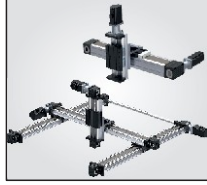
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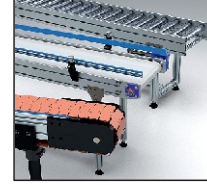
These Products Are Each **Doğuş Kalıp** Brand.



MECHATRONICS MARKET®



ROBOTIC MARKET®



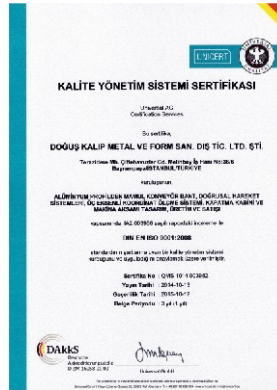
CONVEYOR MARKET®



SIGMA Profile® MARKET



MACHINE MARKET®





Company Profile

Doğuş Kalıp Metal ve Form San. Tic. A.Ş. which started business in 1994 and made name by manufacturing cutting and plastering mould, progressive mould for different sectors, has improved its experience by carrying out activities in production and spare part manufacturing since 1998.

Doğuş Kalıp has started producing Aluminium Industrial Profilees, fastening-connecting parts and their accessories on conveying and automation systems after 2002.

It has contributed to national labour force by manufacturing the equipments which were imported products.

Since 2006, Dogus Kalip has focused on research and development on linear motion systems and multi-axis motion systems and produced world-ranking technological systems by using its own resources.

Today, there is a great competition in both quality and speed by using cutting-edge technological systems and newly developed products in production process and manufacturing industries .

Doğuş Kalıp is a manufacturer of the products which used in serial manufacturing of mechatronics and automation technology applications. We are proud with our research and development department facilities on developing the necessary products in mechatronic sector.

Our main target is improving the systems and equipments in necessity of our sector with our expanding quantity of staff and background.

We have partnership with lots of manufacturer in mechatronics and automation sector due to our product range expanding day by day.

Our marketing strategy is almost completed in domestic market with Dogus Kalip's regional and local dealers and Doğuş Kalıp is to be continue to trading with foreign countries.

We know our responsibility to giving best service and high quality to our customer and partners. We wish to share our experience and develop your business in close future.....

Strong
Stock

High
Quality

Engineering
Service



Innovation

Fast
Service

CRM



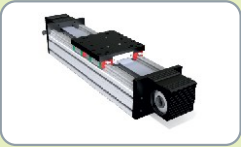
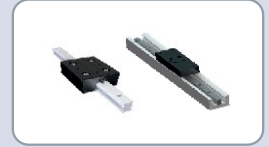
Applications



Manuel Guidance

Blok Bearding

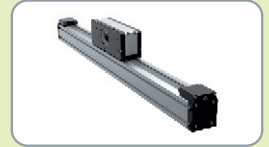
Profile Bearding



Timing Belt Drive Systems

Sigma Series
Dktm Series

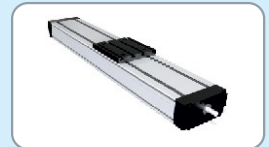
Lineer Series
Kompakt Series



Ball Screw Drive Systems

Dkvm Series
Dkzm Series

Kompakt Series
Spot Series



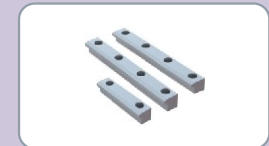
Rack Drive Systems

Bridge Series

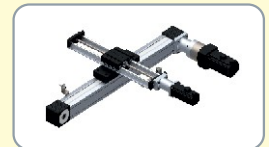
Profile Series



Assembly Connection Equipments



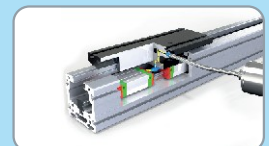
Axis Automation Panels



CNC Plate Bodies



Maintenance and Lubrication Guides



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LINEAR MOTION SYSTEM

Any kind of process in mechanic and automatization systems is ensured via progressive circular and linear motions. In order for the renewed movement to be stable and accurate, it must be ensured that the operation to be performed is in an axial guide and bearing.

For any kind of loading and speed implementation, abrasion should be avoided in order to keep bearing sensitivity and tolerance figures. Regardless of the procedure to be performed, it must be in an axial guide and bearing so that the renewed movement can be deployed in a healthy and stable manner. In order for the renewed movement to be stable and accurate results ensure that the operation to be performed is in an axial guide and bearing. For this reason bedding materials are made of hardened and ground steel. Bearing surfaces are covered with felt shield and protective bellows in order to ensure a long-lasting operation quality. To maintain bearing precision should be prevented and tolerance values in all types of loading and speed applications.

Doğuş Kalıp, Produced in accordance with the specifications mentioned above, provides optional designs to be implemented in various operation environments and for different amounts of loading.

The moment and the stimulation alternatives needed for the axial motions are composed in accordance with the units in which they are used. The bearing materials placed on the Aluminum Profilee frames provides practical implementation and avoid unnecessary loading on the system. The canal structures on the current surfaces ensure that any kind of additional part is included during the process and facilitates adjustment.

It is possible to direct axial coordination motions via the controller and control board in accordance with the process due to the integration of various engines in linear motion systems.

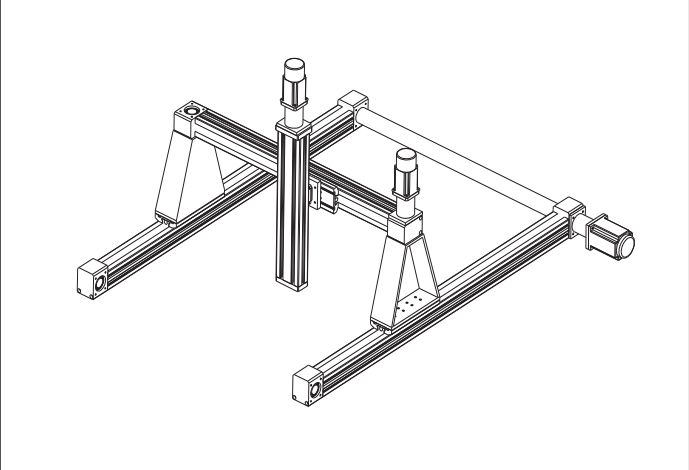
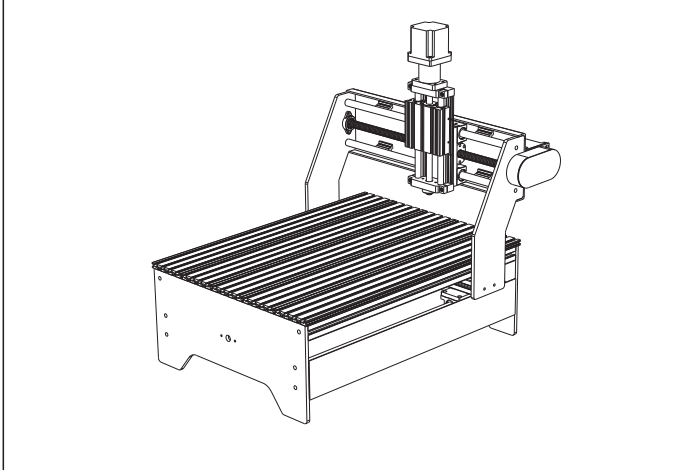
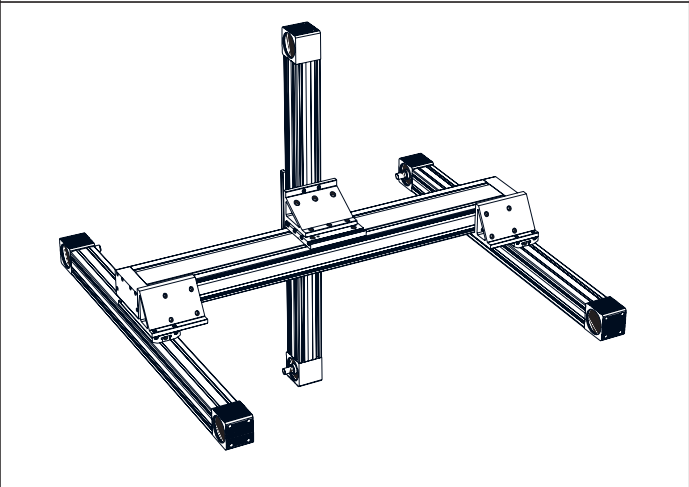
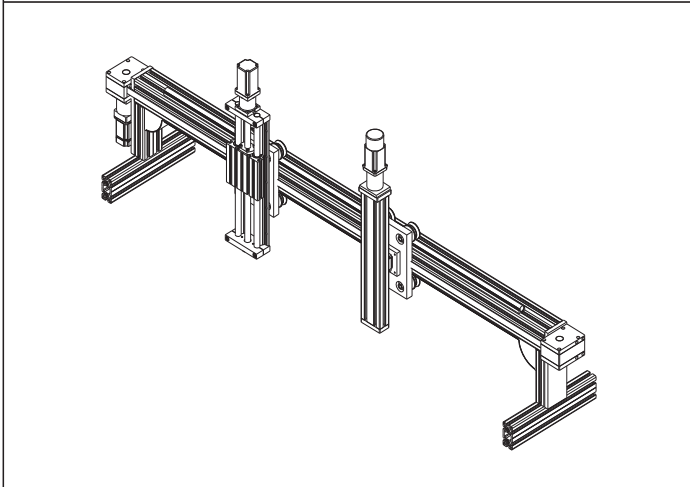
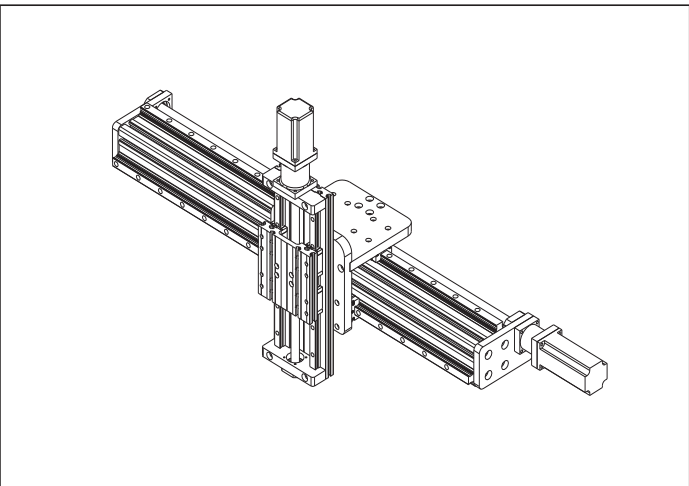
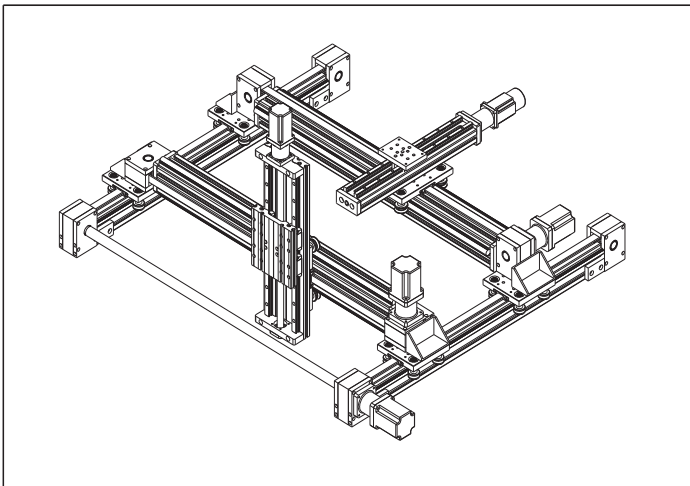
The bearing units produced in difficult conditions and at high-costs formerly are produced By Doğuş Kalıp as instans high-tech units. These instant system provide axial solutions under the scope of multi optional categories.

While these units provide standart options in the category of Linicar Motion System, they also make specific various sizes and additional options available.

The reason why these systems are favored most is that they are version of in practical and they provide appropriate options .



linear motion systems provide ideal solutions for your industrial designs.



3 Axial CNC Machine Coordinates



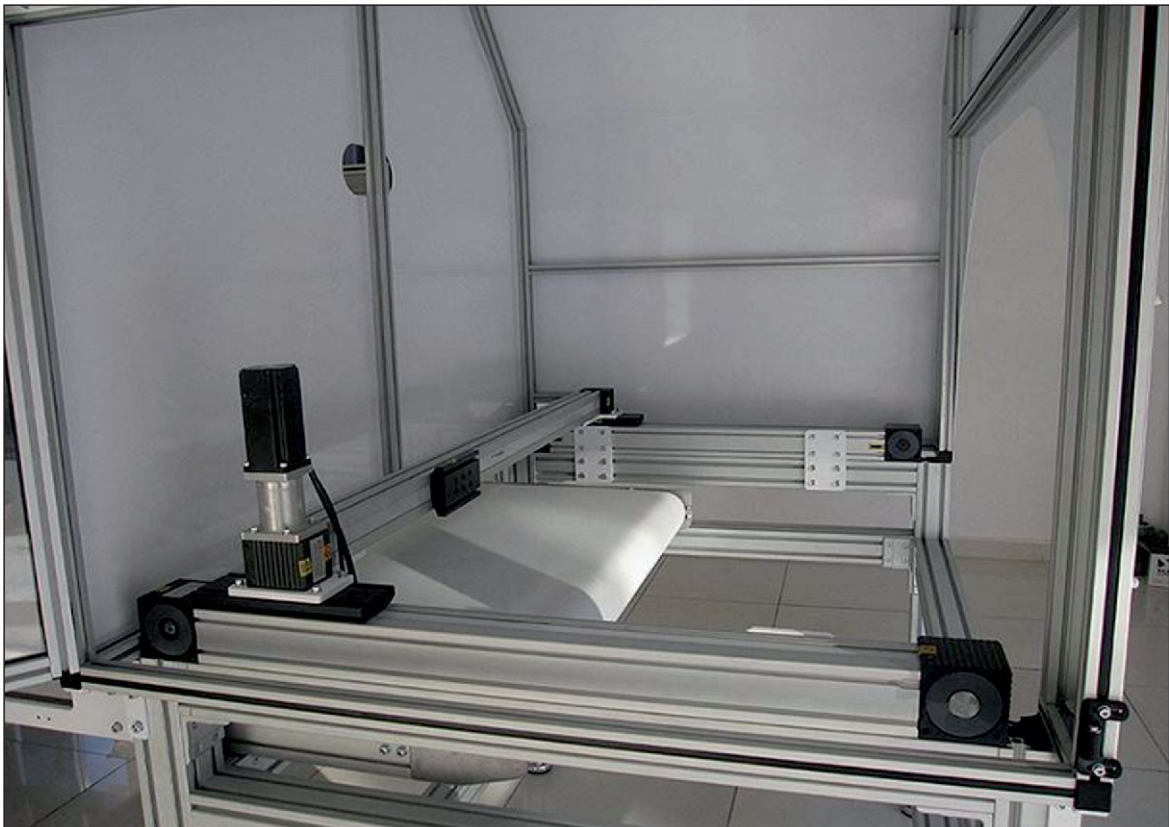
Cartesian Robot Coordinates



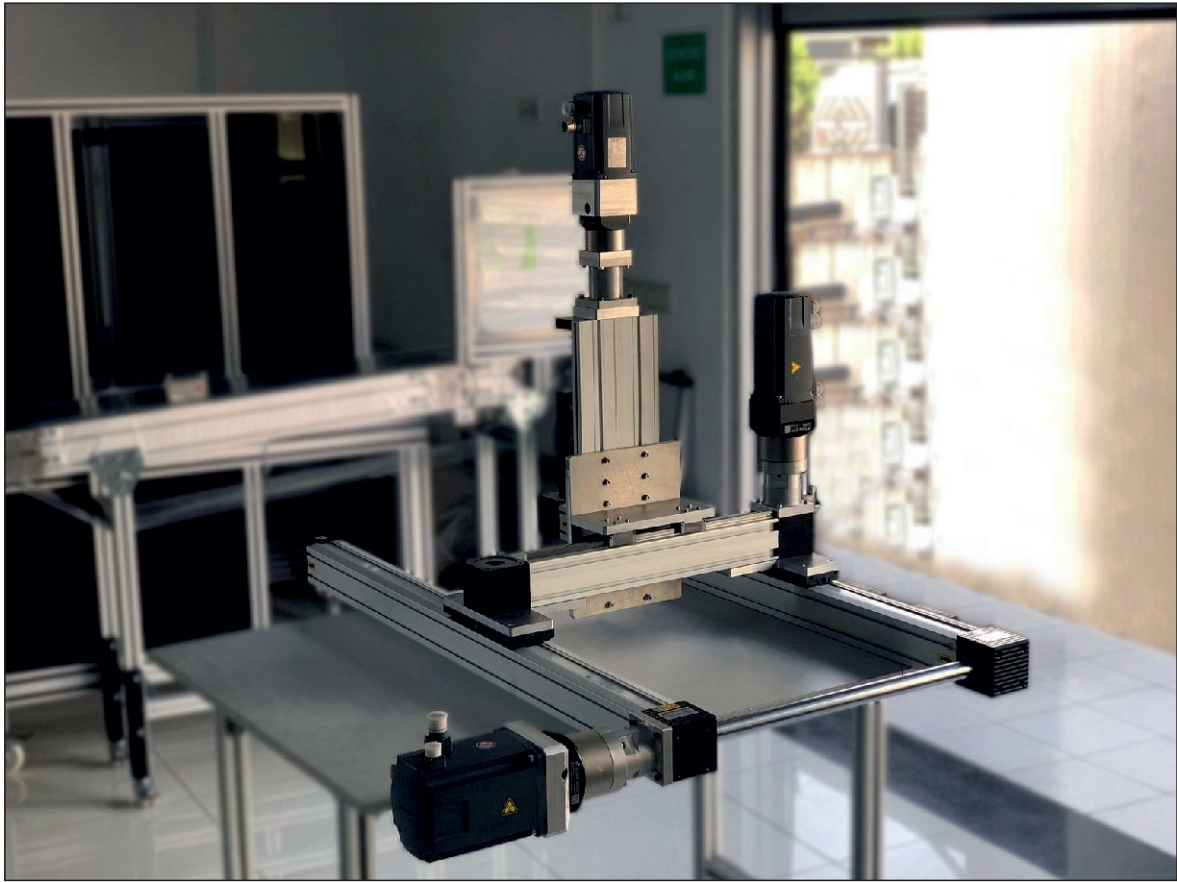
Emprime Print Machine



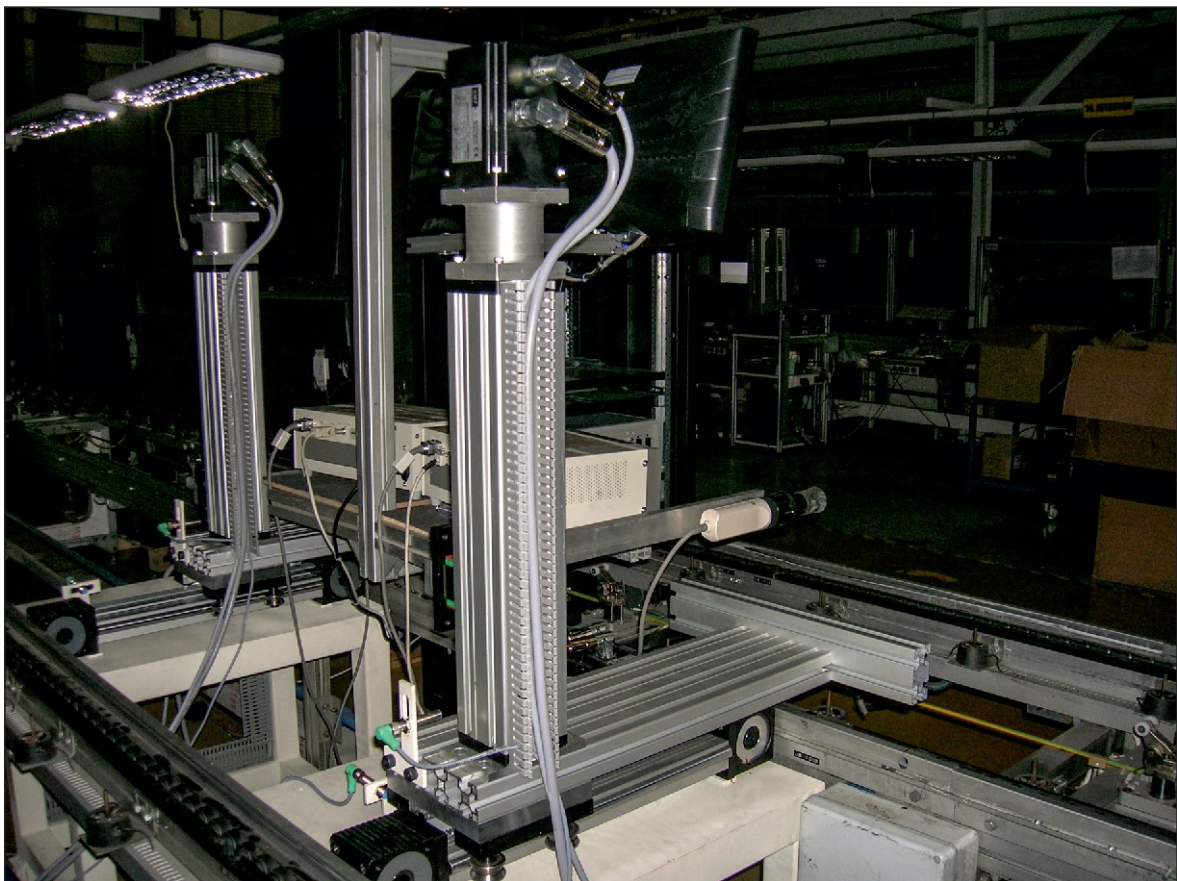
Label Printing System



CNC Machine Coordinates



3 Axial CNC Machine Coordinates



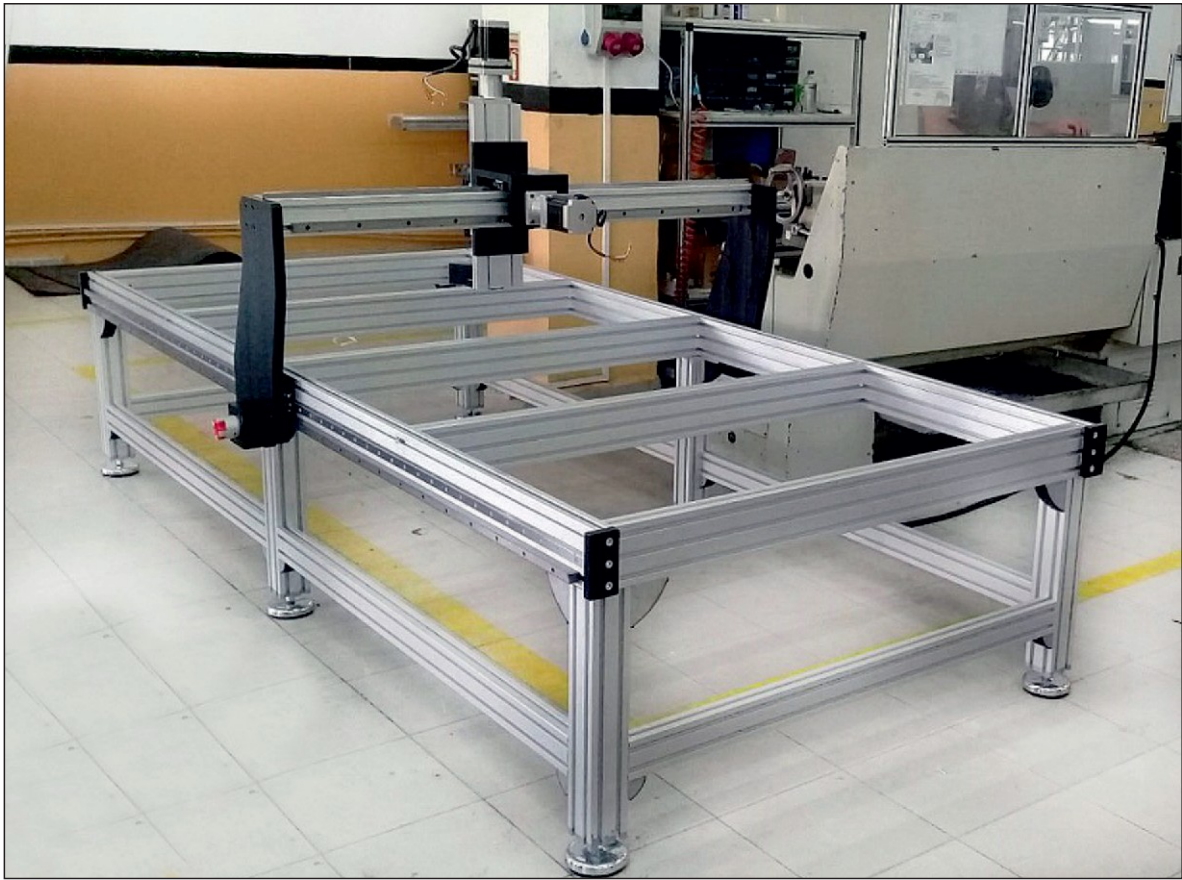
Robotic Automation Line



Label Reading System



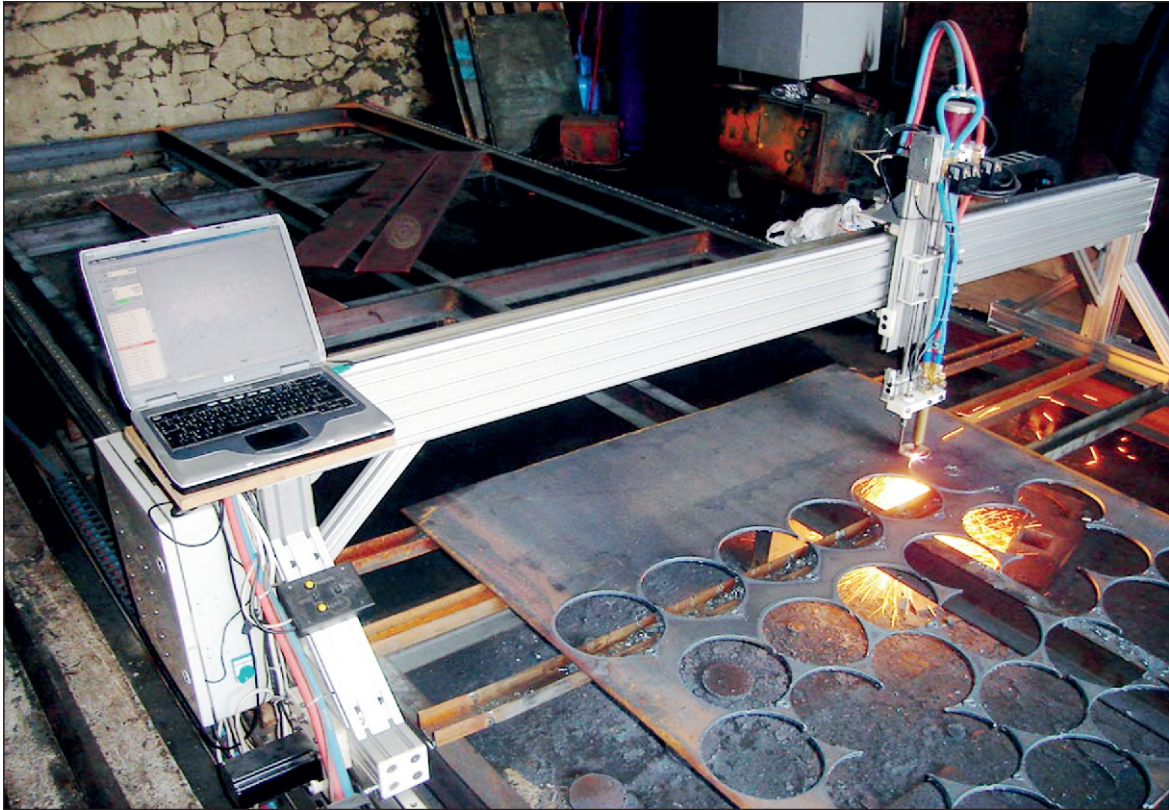
Wood Processing Bench Body



Barcode Otomation



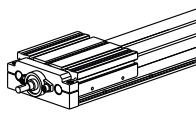

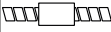

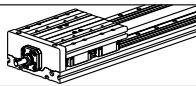
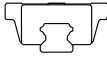
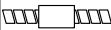

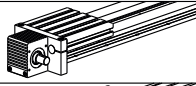



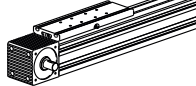
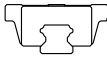

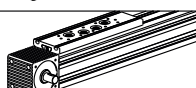

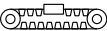

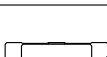


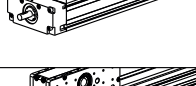


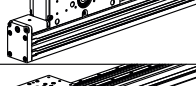
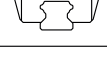







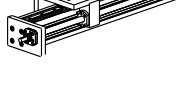



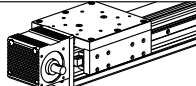

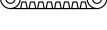

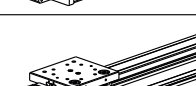



Plasma Cutting Automation



CNC Machine Chassis



LINEAR MODULE SELECTION TABLE

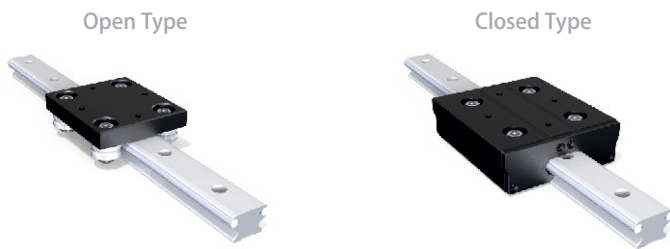
REFERENCE		SECTION		DRIVING			PROTECTION BELLOWS SYSTEM
FAMILY	PRODUCT	LINEAR GUIDE	BEARING	TOOTHED BELT	BALL SCREW	RACK AND PINION	
DKVM MODULE							
DKZM MODULE							
DKTM MODULE							
LINEAR COMPACT MODULE							
							
							
							
SPOT MODULE							
RACK AND PINION RACK AND BALL SCREW BRIDGE MODULES							
LINEAR TIMING BELT MODULES							
ROLLER TIMING BELT MODULES							
RACK AND PINION MODULES							

* You can use the table to choose the type of bedding you want. Bellows systems optionally optional is implemented.

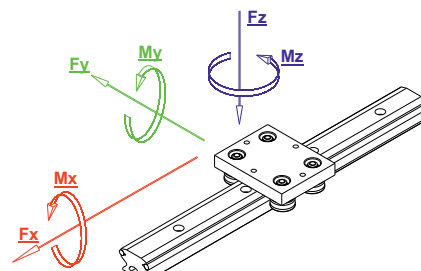
LINEAR MODULE SELECTION TABLE

SIZE	MAX. LOAD CAPACITY PER CARRIAGE (N)			MAX. STATIC MOMENT PER CARRIAGE (Nm)			MAX. TRAVEL SPEED (MT/S)	MAX. ACCELERATION (M/S ²)	REPEATABILITY ACCURACY (mm)	MAX. TRAVEL OR STROKE (PER SYSTEM) (mm)
	Fx	Fy	Fz	Mx	My	Mz				
12	385	910	1215	125	95	110	0,09	0,85	±0,15	1000
16	505	1205	1512	167	126	146	0,12-0,038			
20	618	1744	2180	228	195	204	0,13-0,52			
25	713	2323	2904	360	234	224	0,17-0,34-0,85			
30	912	2950	3450	410	290	280	0,46			
15	2020	2080	3020	410	290	440	0,12-0,38	0,5	±0,03	2000
20	3680	4400	5760	650	320	690	0,13-0,52			
20	618	1744	2180	228	195	204	4	2	±0,2	6000
64	2200	2460	4240	385	415	540	5	5 8	±0,1	6000
80	2400	2760	7260	412	465	580	5			
100	3600	3180	10870	697	780	710	4			
64	1400	1150	1260	430	510	470	8	5	±0,1	6000
80	1650	1320	1440	650	720	680	8			
50	8600	5400	9200	510	1120	2350	0,12	0,5	±0,03	2000
65	9800	6200	13500	620	1340	1340	0,13-0,17-0,52			
80	12300	9600	18700	840	1870	3200	0,17-0,34-0,52-0,85			
100	5500	4700	10870	3360	5740	8220	0,17-0,34-0,52			
64	2200	2460	4240	385	415	540	5			
80	2400	2760	7260	415	480	570	5	5	±0,1	6000
45	725	878	1157	110	70	75	0,10	0,15	±0,03	1750
90	975	878	1157	140	80	95	0,12			
90	1480	2125	2125	230	1613	1613	3	0,95 2	±0,03 ±0,2	6000
180	1650	2450	3850	390	1613	2470	3			
90	950	2785	3863	690	435	435	4	5 8	±0,1	7300
135	1350	3215	4560	690	540	540	3			
180	1650	4300	12600	1447	1613	1613	4			
38	320	600	800	70	85	65	5	3/5/6	±0,2	3000
45	615	810	1000	75	70	86	6-8			
60	640	1760	1505	120	125	162	6			
80	780	2100	1880	150	165	175	6-8			
90	915	1295	2460	102	172	195	6-8			
80	780	2100	1880	150	165	175	4	1	±0,2	6000

* You can use the table to choose the type of bedding in the option you want. Bellows systems are optional as an option is implemented.



Upload Values



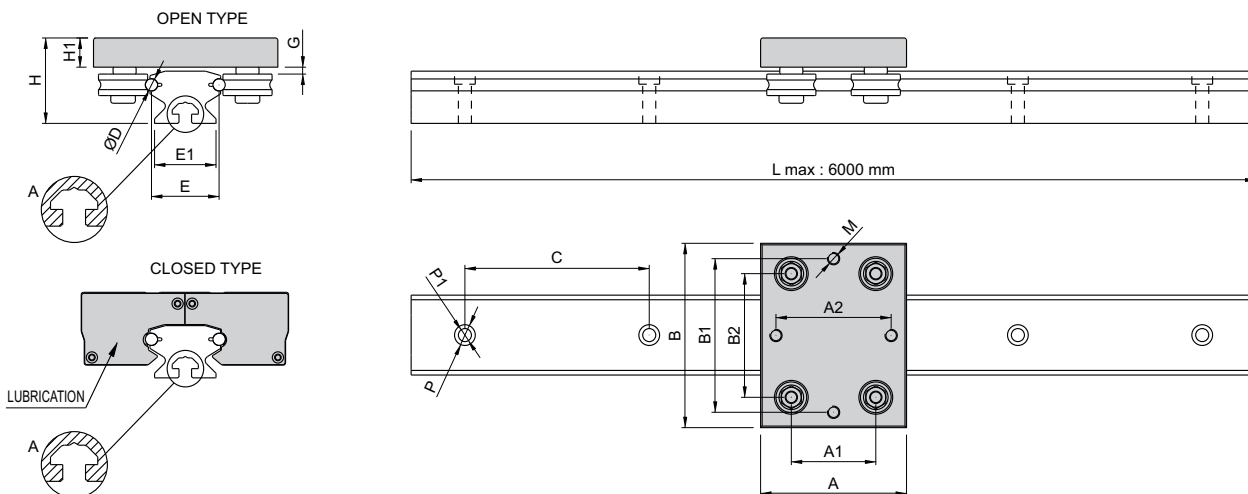
Load	Static	Ø4 Blok	Ø6 Blok	Ø8 Blok
■ Fx (N)	(N)	120	180	320
■ Fy (N)	(N)	240	280	640
■ Fz (N)	(N)	360	410	760
Moment				
■ Mx (Nm)	(Nm)	60	80	120
■ My (Nm)	(Nm)	48	84	126
■ Mz (Nm)	(Nm)	64	96	132

Closed Types: Provides protection against dust and particles. thanks to their lubricating seals they are long-lasting

Technical Specifications

Body	:	12x17 - 20x24 - 40x34 Profilee (Aluminum 6063)
Movement Speed	:	5 mt/sn - 6 mt/sn - 8 mt/sn
Wedge	:	(M4x20,5) - (M6x30) - (M8x41,5) Straight and Eccentric
Induction Shaft	:	Ø4 - Ø6 - Ø8 Chrome Plated Induction Shaft
Linear Block	:	LFR 50/5-4 / LFR 50/8-6 / RV 200-8

Technical Details



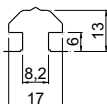
Roller Block Guide Body

CODE	STOCK NAME	ØD	C	P	P1	E	E1
5.1.01.012017.01.04	Ø4 Block Bearding	4	60	7.5	4.5	16	17
5.1.01.020024.01.06	Ø6 Block Bearding	6	60	10.5	6.5	26	24
5.1.01.034040.01.08	Ø8 Block Bearding	8	120	13.5	8.5	44	40

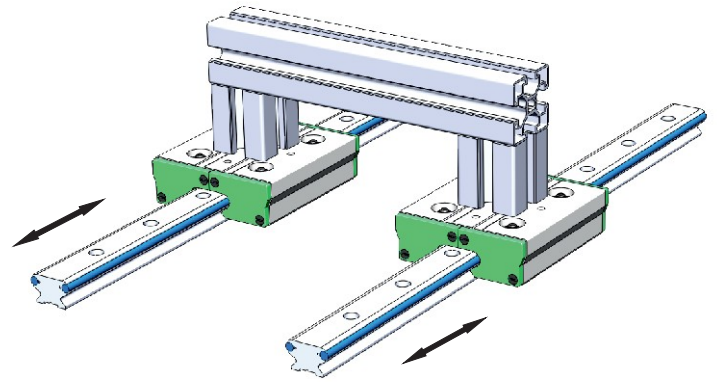
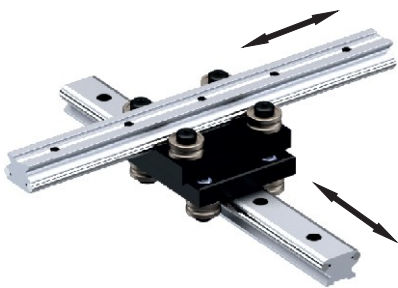
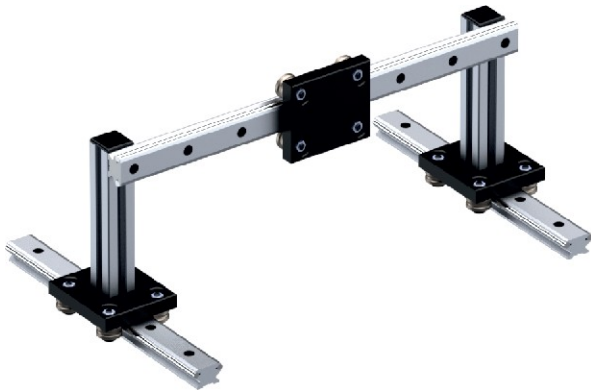
Linear block

CODE	STOCK NAME	ØD	B	B1	B2	A	A1	A2	M	G	H	H1
6.1.01.012017.055055.1.04	Ø4 Block	4	55	40	34	50	31	40	M5	0.5	23	9.5
6.1.01.020024.090080.1.4	Ø6 Block	6	80	60	53.5	90	64	70	M6	1	35.5	14
6.1.02.020024.115100.1.4	Ø6 Block (Closed)	6	100	60	53.5	115	64	70	M6	1	35.5	14
6.1.01.034040.095100.1.4	Ø8 Block	8	120	100	80.5	95	55	75	M8	4.5	55.6	19
6.1.02.034040.095100.1.4	Ø8 Block (Closed)	8	135	100	80.5	115	55	75	M8	4.5	55.6	19

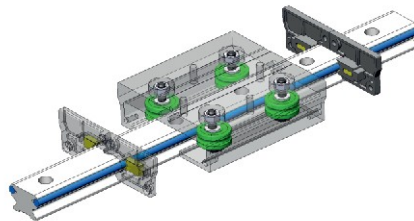
A (Ø8 M6 CHANNEL DETAIL)



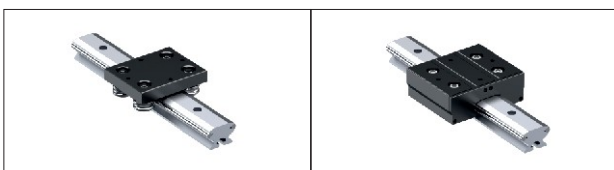
Applications



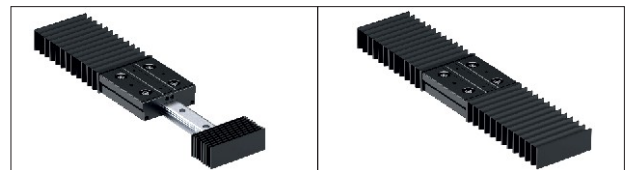
Option Types



Lubrication System And Bearing Protecting Shield



System Protector (bellows)



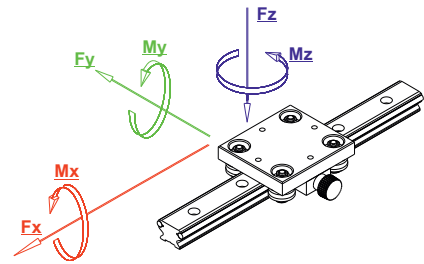


Single Lock

Double Lock



Upload Values

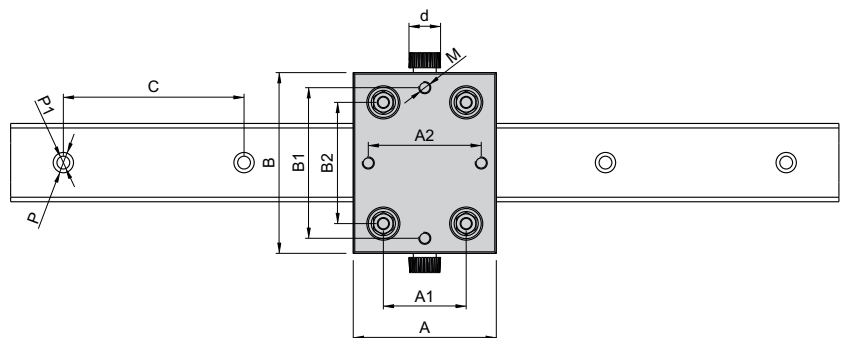
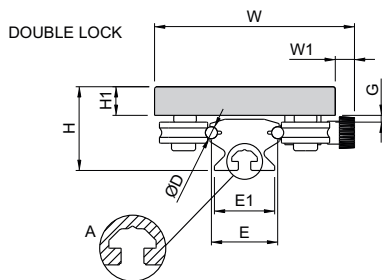
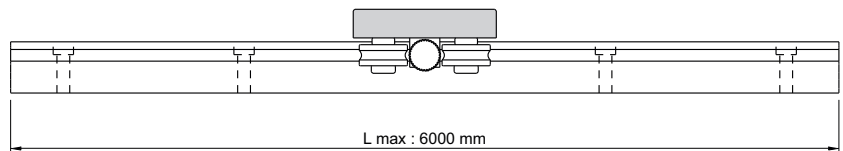
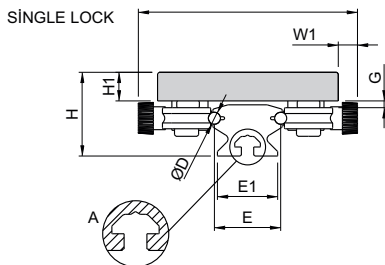


Load	Static	Ø6Single-Ø6Double	Ø8Single-Ø8Double
■ Fx (N)	(N)	180	320
■ Fy (N)	(N)	280	640
■ Fz (N)	(N)	410	760
Moment			
■ Mx (Nm)	(Nm)	80	120
■ My (Nm)	(Nm)	84	126
■ Mz (Nm)	(Nm)	96	132

Technical Specifications

Body	:	20x24 - 40x34 Profile (Aluminum 6063)
Movement Speed	:	6 m/sn - 8 m/sn
Wedge	:	(M6x30) - (M8x41,5) Straight and Eccentric
Induction Shaft	:	Ø6 - Ø8 Chrome Plated Induction Shaft
Linear Block	:	LFR 50/8-6 / RV 200-8.32.14

Technical Details



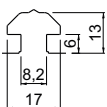
Roller Block Guide Body

CODE	STOCK NAME	ØD	C	P	P1	E	E1
5.1.01.020024.01.06	Ø6 Roller Block Guide	6	60	10.5	6.5	26	24
5.1.01.034040.01.08	Ø8 Roller Block Guide	8	120	13.5	8.5	44	40

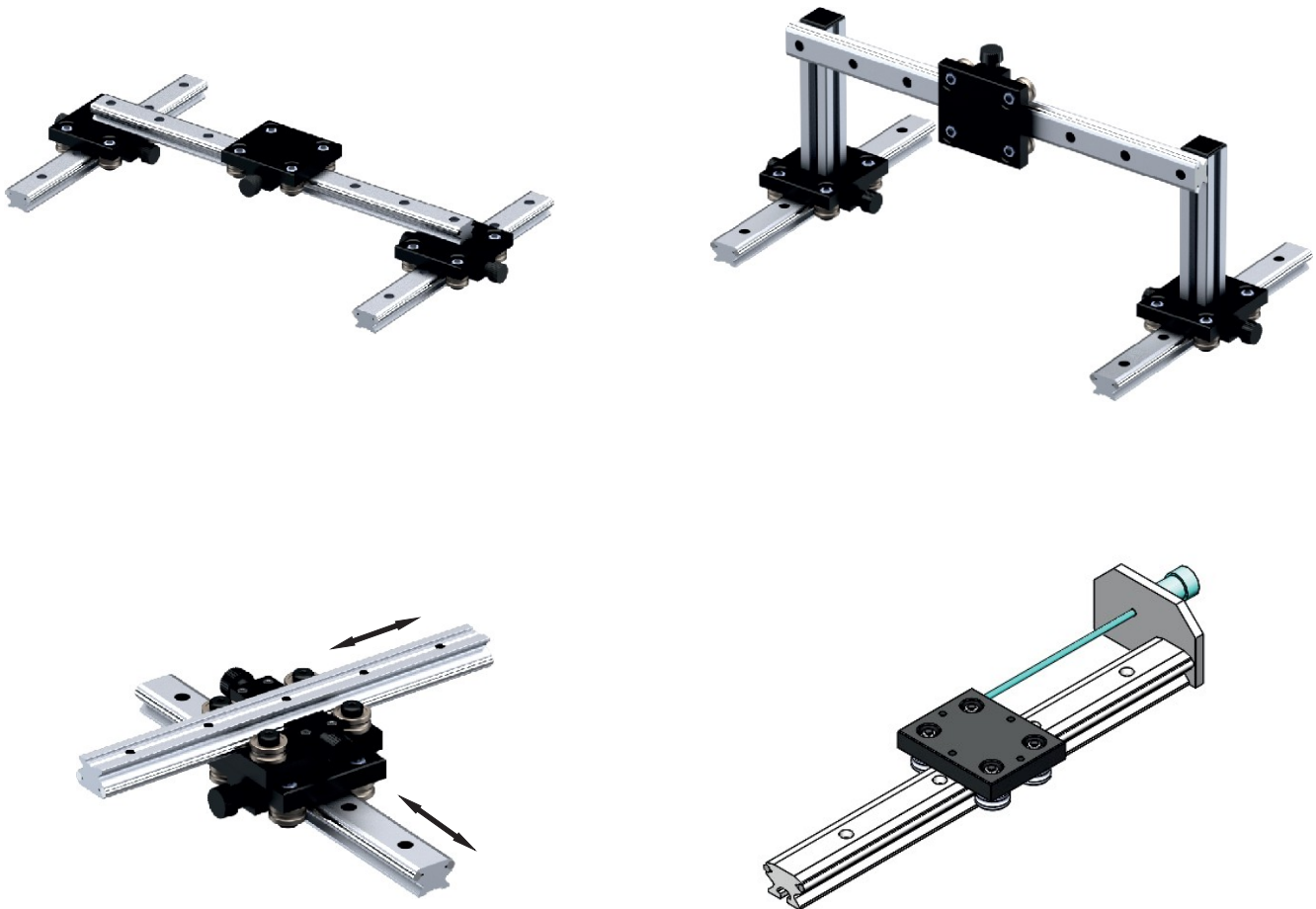
Linear Block

CODE	STOCK NAME	Ød	B	B1	B2	A	A1	A2	M	G	H	H1	W	W1	d
6.1.01.020024.090080.2.4	Ø6 Block Guide Carriage with Single Lock	6	80	60	53,5	90	64	70	M6	1	35,5	14	100	20	20
6.1.01.020024.090080.3.4	Ø6 Block Guide Carriage with Double Lock	6	80	60	53,5	90	64	70	M6	1	35,5	14	120	20	20
6.1.02.034040.115135.2.4	Ø8 Block Guide Carriage with Single Lock	8	120	100	80,5	95	55	75	M8	4,5	55,6	19	134	14	20
6.1.02.034040.115135.3.4	Ø8 Block Guide Carriage with Double Lock	8	120	100	80,5	95	55	75	M8	4,5	55,6	19	148	14	20

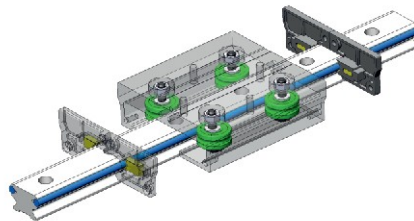
A (Ø8 M6 CHANNEL DETAIL)



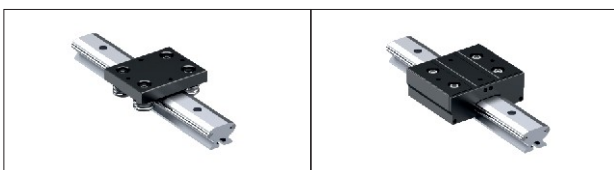
Applications



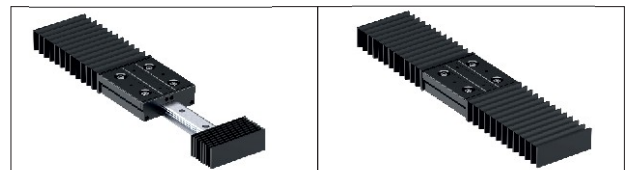
Option Types



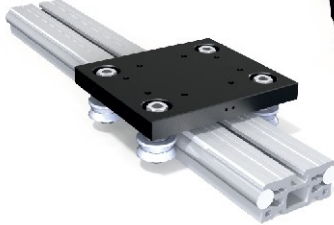
Lubrication System And Bearing Protecting Shield



System Protector (bellows)



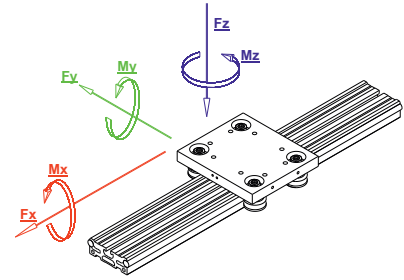
Open Type



Closed Type



Upload Values



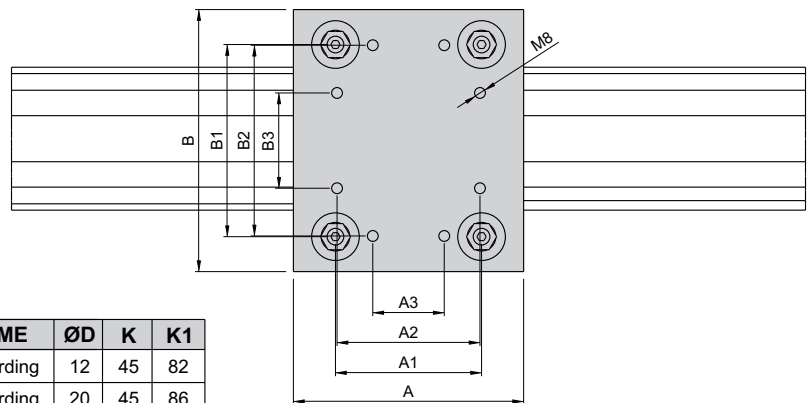
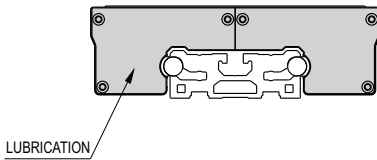
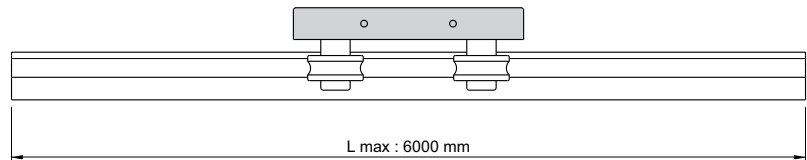
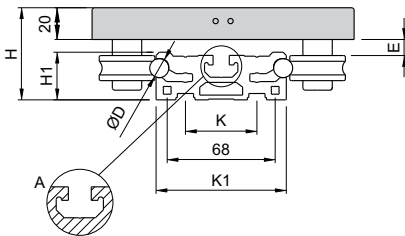
Load	Static	Ø12 Blok	Ø20 Blok
■ Fx	(N)	440	760
■ Fy	(N)	870	1260
■ Fz	(N)	1100	1870
Moment			
■ Mx	(Nm)	142	180
■ My	(Nm)	156	186
■ Mz	(Nm)	162	192

Closed Types: Provides protection against dust and particles. They have a long life thanks to their lubricating seals.

Technical Specifications

Body	:	30x82 - 40x86 Profilee (Aluminum 6063)
Movement Speed	:	8 mt/sn
Wedge	:	(M10X51) - (M12X60) Straight and Eccentric
Induction Shaft	:	Ø12 - Ø20 Chrome Plated Induction Shaft
Linear Block	:	RV 201-12 / RV 202-15 / RV 203-17

Technical Details



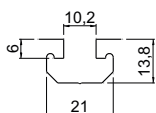
Roller Block Guide Body

CODE	STOCK NAME	ØD	K	K1
5.1.01.030082.01.12	Ø12 Blok Bearding	12	45	82
5.1.01.040086.01.20	Ø20 Blok Bearding	20	45	86

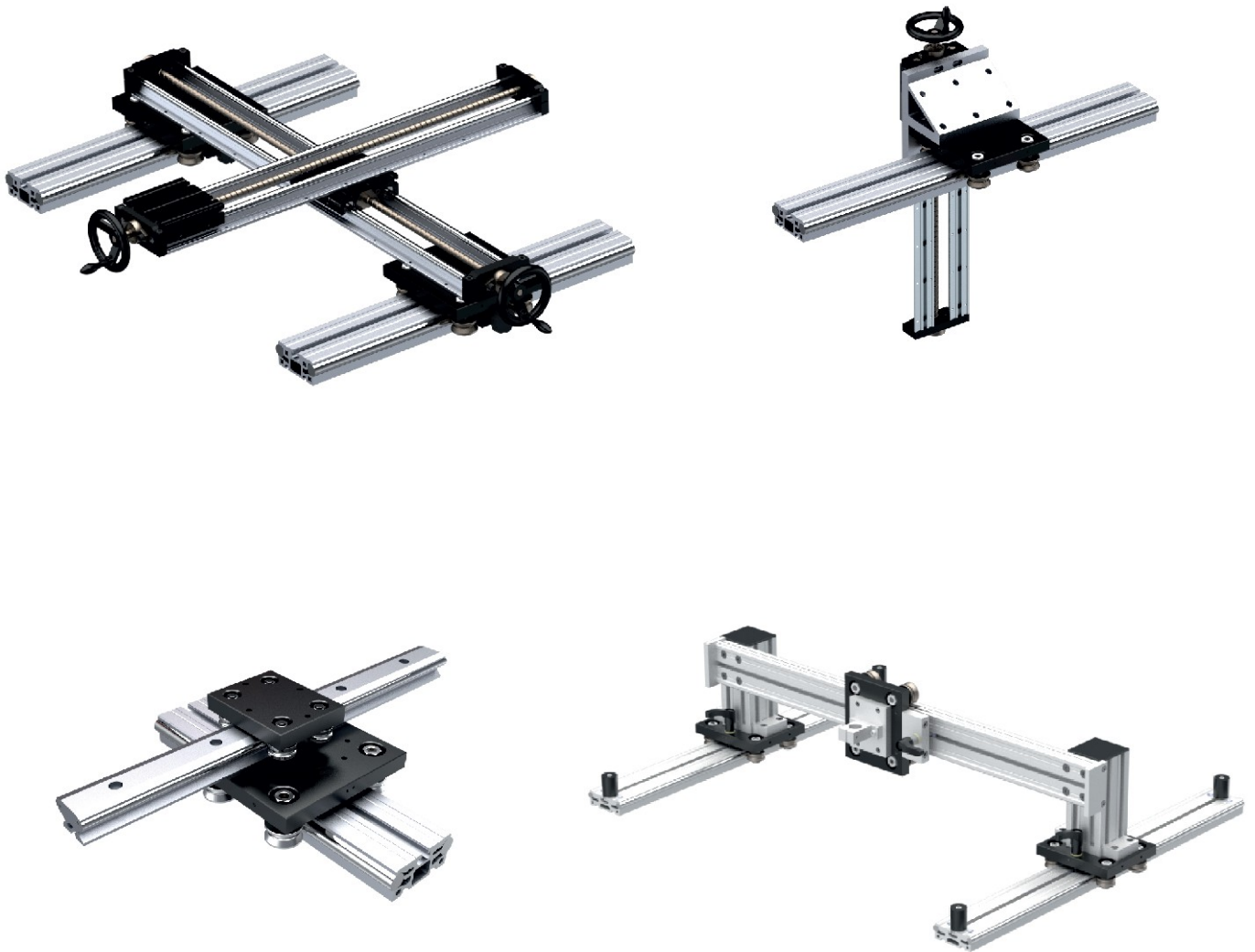
Linear block

CODE	STOCK NAME	ØD	A	A1	A2	A3	B	B1	B2	B3	C	C1	E	H	H1
6.1.01.030082.145165.1.4	Ø12 Blok RV 201	12	145	92	90	45	92	121	120	45	165	121	10	58	30
6.1.02.030082.145165.1.4	Ø12 Blok LFR 5201 (KAPALI)	12	155	92	90	45	92	121	120	45	182	121	10	58	30
6.1.01.040086.165185.1.4	Ø20 Blok RV202	20	165	105	90	45	105	135.4	120	45	185	135	14	69	40.5
6.1.02.040086.165185.1.4	Ø20 Blok RV202 (KAPALI)	20	175	105	90	45	105	135.4	120	45	202	135	14	69	40.5

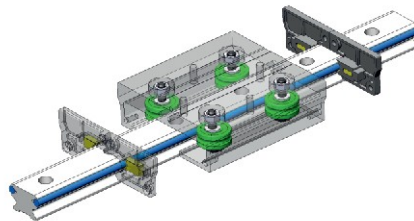
A (CHANNEL DETAIL)



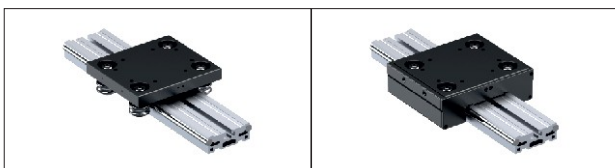
Applications



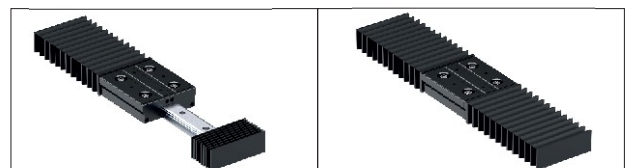
Option Types



Lubrication System And Bearing Protecting Shield



System Protector (bellows)



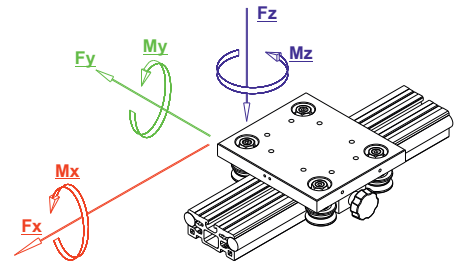


Single Lock

Double Lock



Upload Values

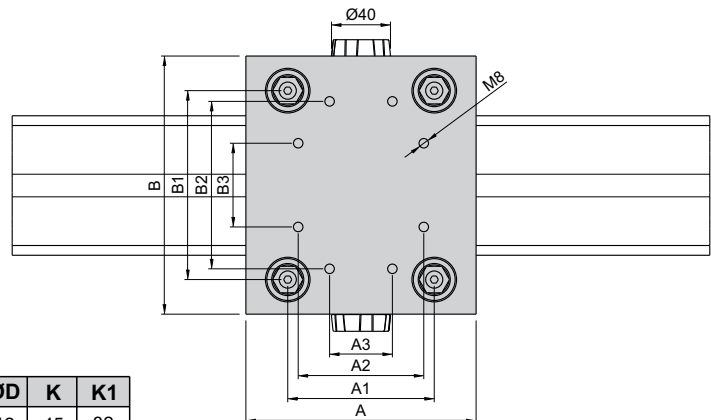
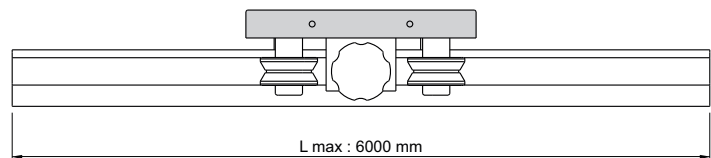
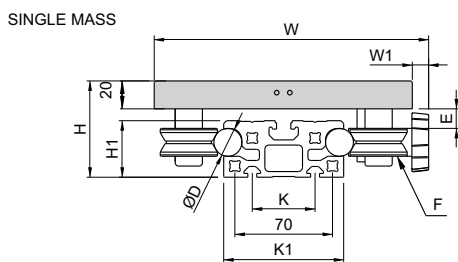
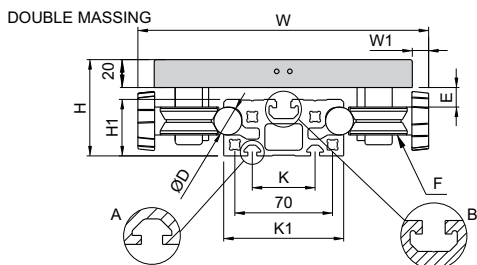


Load	Static	Ø12Single-Ø12Double	Ø20Single-Ø20Double
■ Fx (N)		440	760
■ Fy (N)		870	1260
■ Fz (N)		1100	1870
Moment			
■ Mx (Nm)		142	180
■ My (Nm)		156	186
■ Mz (Nm)		162	192

Technical Specifications

Body	:	30x82 - 40x86 Profile (Aluminum 6063)
Movement Speed	:	6 mt/sn - 8 mt/sn
Wedge	:	(M10X51) - (M12X60) Straight and Eccentric
Induction Shaft	:	Ø12 - Ø20 Chrome Plated Induction Shaft
Linear Block	:	RV 201-12.35.16 / RV 202 15.41.20 / RV 203 17

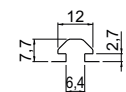
Technical Details



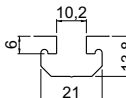
Roller Block Guide Body

CODE	STOCK NAME	ØD	K	K1
5.1.01.030082.01.12	Ø12 Block Bearding	12	45	82
5.1.01.040086.01.20	Ø20 Block Bearding	20	45	86

A (CHANNEL DETAIL)



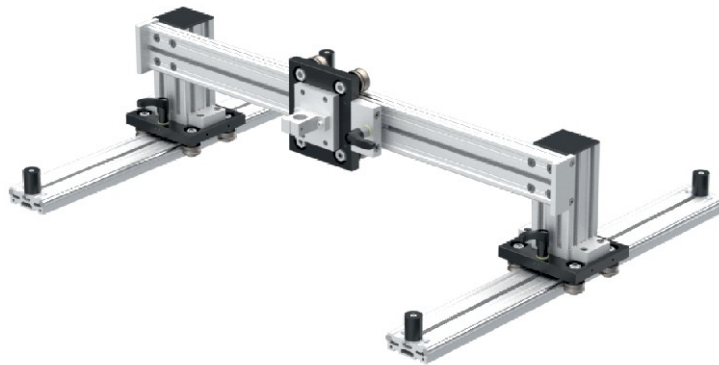
B (CHANNEL DETAIL)



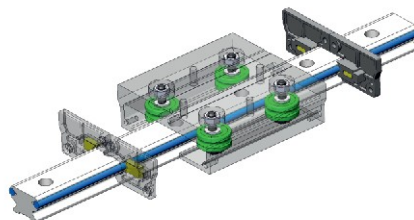
Linear block

CODE	STOCK NAME	ØD	A	B	C	C1	E	H	H1	W	W1
6.1.01.030082.145165.3.4	Ø12 Block Guide Carriage with Single Lock	12	145	92	165	121	10	58	30	185	20
6.1.01.030082.145165.4.4	Ø12 Block Guide Carriage with Double Lock	12	145	92	165	121	10	58	30	205	20
6.1.01.040086.165185.3.4	Ø20 Block Guide Carriage with Single Lock	20	165	105	185	135	14	69	40.5	201	16
6.1.01.040086.165185.4.4	Ø20 Block Guide Carriage with Double Lock	20	165	105	185	135	14	69	40.5	217	16

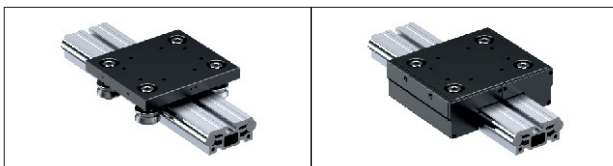
Applications



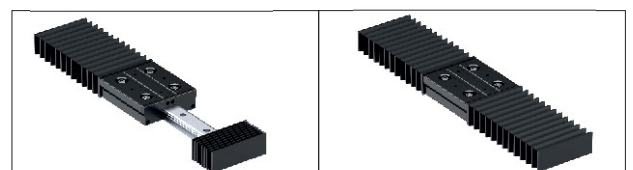
Option Types



Lubrication System And Bearing Protecting Shield



System Protector (bellows)

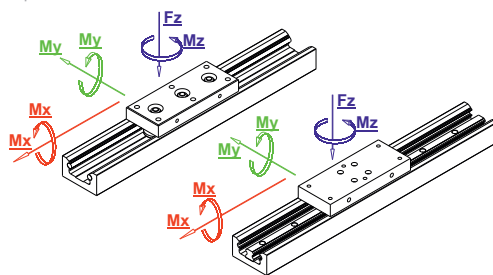




Roller

Linear Rail

Upload Values

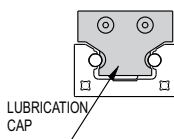
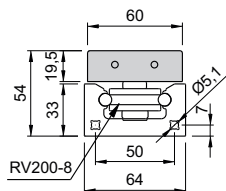
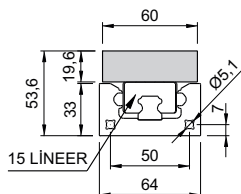


Load	Static	ROLLER	LİNEAR
■ Fx	(N)	460	460
■ Fy	(N)	720	1080
■ Fz	(N)	916	1260
Moment			
■ Mx	(Nm)	82	120
■ My	(Nm)	96	170
■ Mz	(Nm)	108	210

Technical Specifications

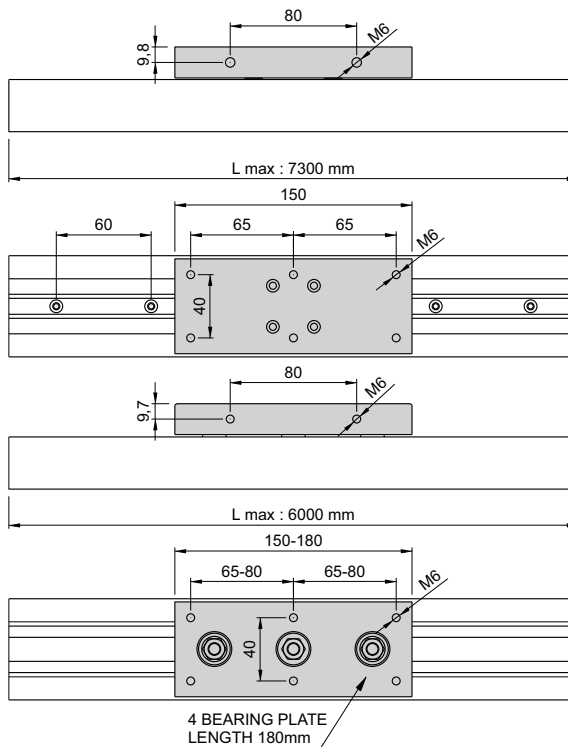
Body	:	64x33 Profilee (Aluminum 6063)
Movement Speed	:	Makara 8 mt/sn - Linear 3 mt/sn
Wedge	:	(M8x41,5) Straight and Eccentric
Induction Shaft	:	Ø8 Chrome Plated (20 - 30 µm) Induction Spindle 60-62 HRC h7
Bearing Block	:	RV200 - 8 KDD
Linear Rail	:	15 lik Linear Rail
Linear Block	:	15 Narrow Low Linear Car

Technical Details



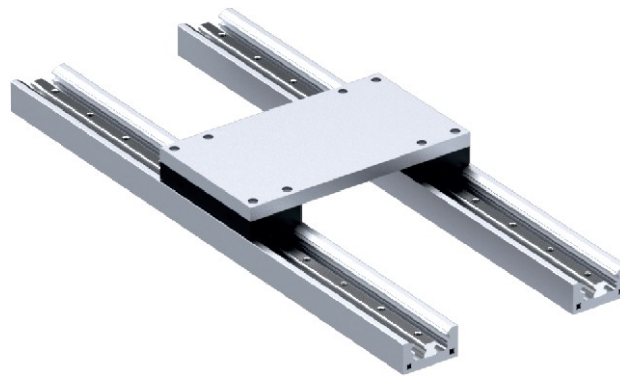
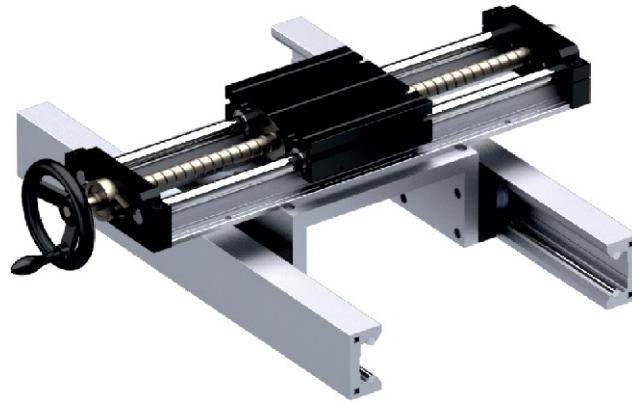
Note: Lubrication is optional

Body



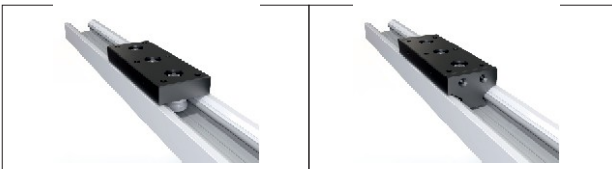
CODE	CODE	STOCK NAME
5.1.01.033064.02.08	6.1.01.033064.060150.1.3	Block Guide Carriage with 3 Bearings (Open Type)
	6.1.02.033064.0 60150.1.3	Block Guide Carriage with 3 Bearings (Closed Type)
	6.1.01.033064.060150.1.4	Block Guide Carriage with 4 Bearings (Open Type)
	6.1.02.033064.060150.1.4	Block Guide Carriage with 4 Bearings (Closed Type)
5.1.01.033064.02.15	6.1.03.033064.060150.1.3	Closed Linear Block Guide

Applications

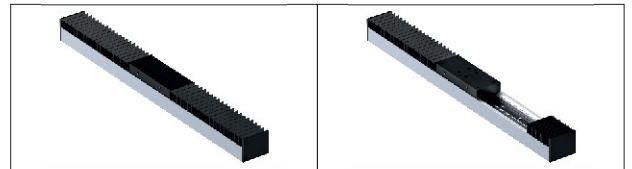


Option Types

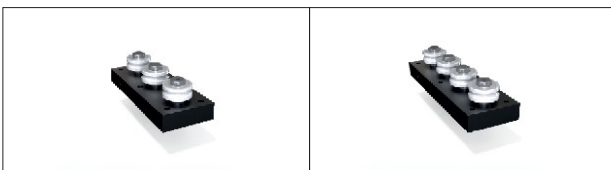
Lubrication System And Bearing Protecting Shield



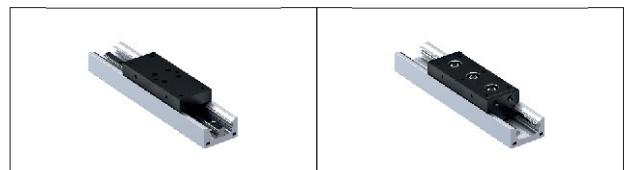
System Protector (bellows)



Top Plates with 3 or 4 Bearings

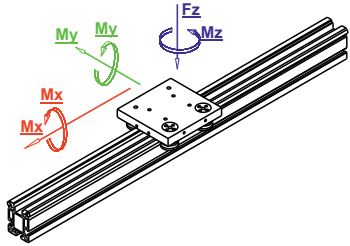


1 or 2 Linear Trolley Top Plates





Upload Values

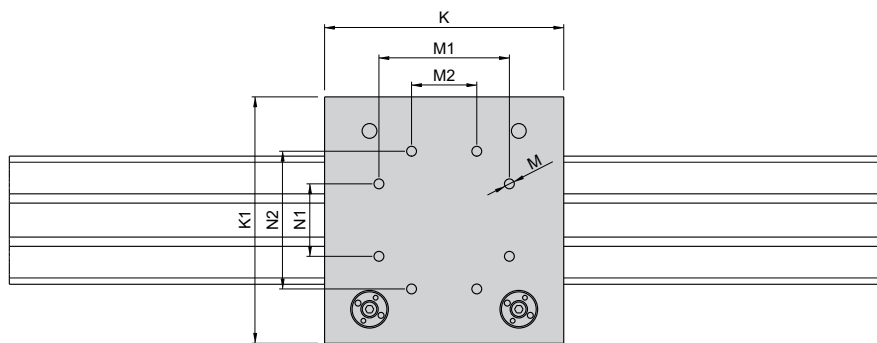
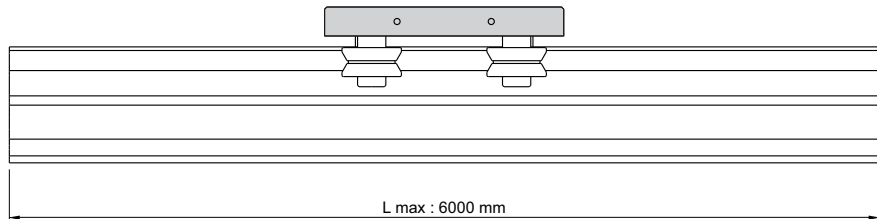
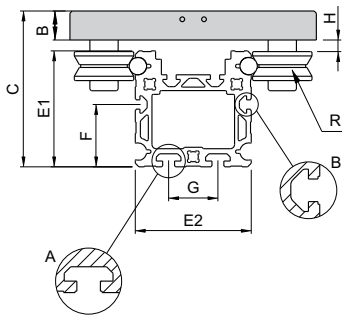


Load	Static	38X50	60X80	80X80
■ Fx	(N)	320	640	780
■ Fy	(N)	600	1760	2100
■ Fz	(N)	800	1505	1880
Moment				
■ Mx	(Nm)	70	120	150
■ My	(Nm)	85	125	165
■ Mz	(Nm)	65	162	175

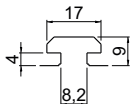
Technical Specifications

Body	:	38x50 / 60x80 / 80x80 Profilee (Aluminum 6063)
Movement Speed	:	5 mt/sn / 6 mt/sn / 8 mt/sn
Wedge	:	(M6x32) (M10x49,5) (M12x54) Straight and Eccentric
Induction Shaft	:	Ø6 / Ø10 / Ø12 Chrome Plated Induction Shaft 60-62 HRC h7
Bearing Block	:	LFR 50/8-6 / RV 201-12

Technical Details

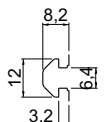


A (CHANNEL DETAIL)



38*50 Profilee Channel
80*80 Profilee Channel

B (CHANNEL DETAIL)



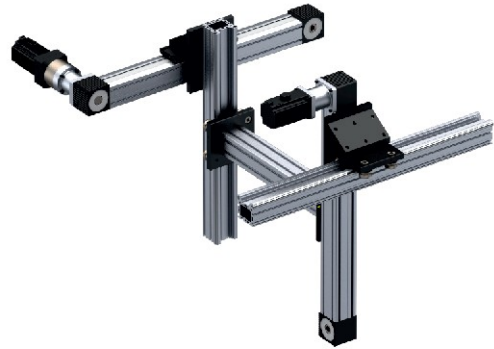
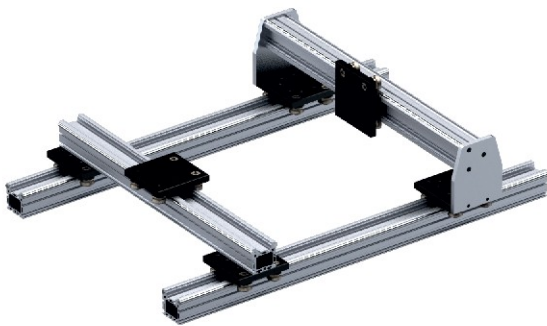
38*50 Profilee Channel
60*80 Profilee Channel
80*80 Profilee Channel

Car

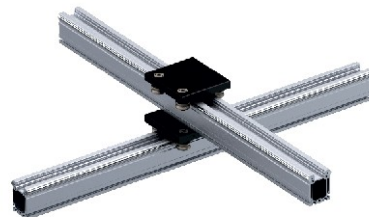
CODE	STOCK NAME
6.1.01.038050.100100.1.4	38X50 Car
6.1.01.060080.150150.1.4	60X80 Car
6.1.01.080080.165165.1.4	80X80 Car

CODE	STOCK NAME	B	C	ØD	E1	E2	F	G	H	K	K1	M	M1	M2	N1	N2
5.1.01.038050.01.06	38x50 Bearding	14,5	69	6	50	38	15	----	4	100	95	5	45	----	30	----
5.1.01.060080.01.10	60x80 Bearding	19,5	107	10	80	60	12	32	8,5	150	140	8	90	45	45	90
5.1.01.080080.01.12	80x80 Bearding	20	107,5	12	80	80	43	34	8	165	170	8	90	45	50	95

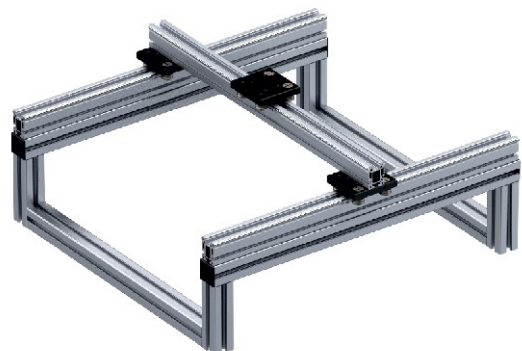
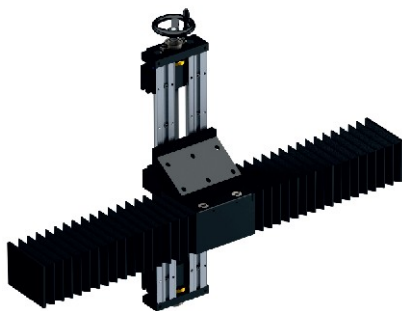
Applications



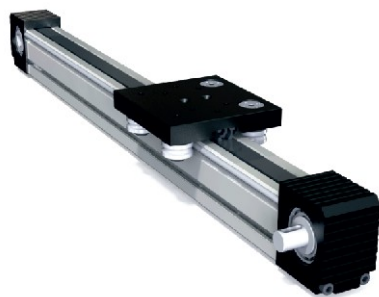
It is possible to create units suitable for the desired torque and at the specified stroke in Profilee guides.



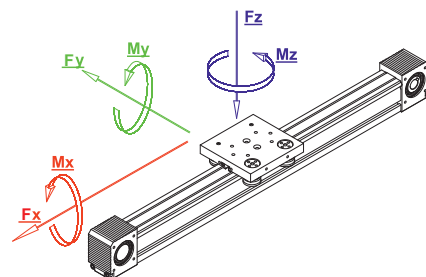
Different axial options can be provided according to the needs.



It is possible to benefit from special assembly elements for motion transmission in any direction.



Upload Values



Load		Dynamic
■ Fx	(N)	320
■ Fy	(N)	800
■ Fz	(N)	500
Moment		
■ Mx	(Nm)	90
■ My	(Nm)	80
■ Mz	(Nm)	80

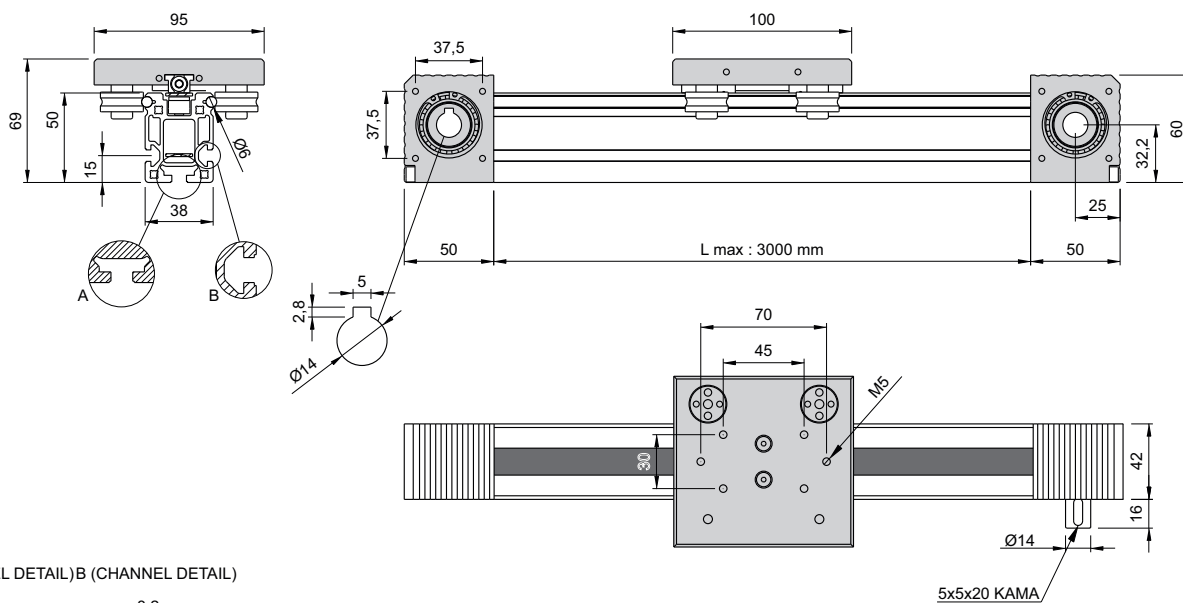
Product code : 5.3.03.038050.1.01.2.Strok

Technical Specifications

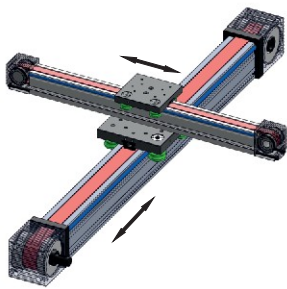
Body	:	38x50 Profilee (Aluminum 6063)
Movement Speed	:	5 mt/sn
Wedge	:	(M6x32) Straight and Eccentric
Movement Distance Per Tour	:	105 mm
Timing Belt	:	5M-15 Steel Wire Polyurethane NFT Diapered
Timing Pulley	:	Z21-5M-16F
Induction Shaft	:	Ø6 Chrome Plated Induction h7 mil
Bearing	:	LFR 50/8-6
Belt Tensile Force	:	1500 N
Timing Belt Pitch	:	5 mm
Positioning Accuracy	:	0,2 mm
Basic Weight With Zero Strok	:	1,62 kg
Weight 1000mm Stroke	:	4 kg
Automation Control System	:	400 Watt Omron Servo + PLC + Pano

Note: Depending on the operating sensitivity, Asynchronous, Step, Induction, etc. It can be driven by motors.

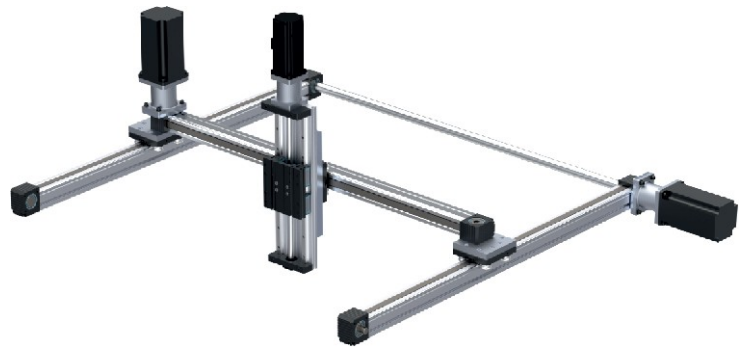
Technical Details



Applications

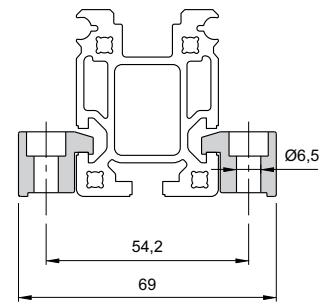
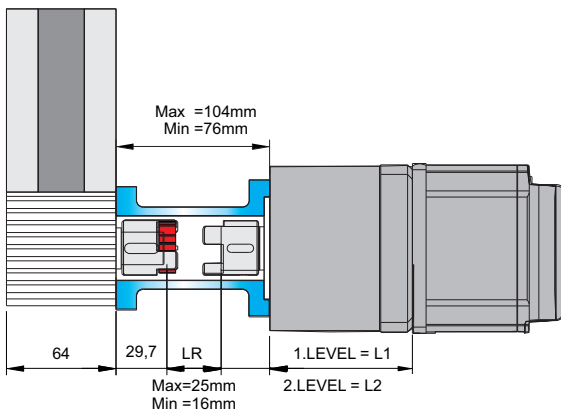


Reducer Connection Detail



Connection Dimensions

Timing Belt Driven Systems

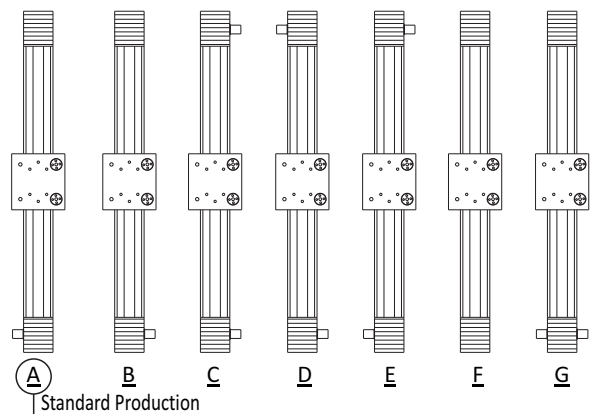


SESAME REDUCER TYPE	L1	L2
PEC 50 (200W For use)	50 mm	76 mm
PEC 70 (400W For use)	64 mm	92 mm

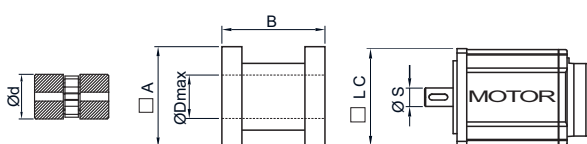
Planetary Gearbox Cycle Rates

1.LEVEL : 3-4-5-7-10
 2.LEVEL : 15-20-25-30-35-40-50-70-100
 Maximum Tork PEC 50 : 25 Nm
 Maximum Tork PEC 70 : 79 Nm
 Maximum Transfer : 6000 rpm

Drive Direction Options



Coupling & Flange Selection

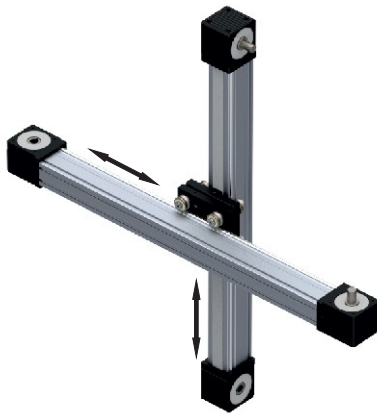


KAPLIN	Ød	ØS	FLANŞ	A	B	ØDmax	LC
JM 40	40	8 - 22	85 x 85	65 - 85	80 - 90	47	65 - 85
JM 55	55	8 - 28	95 x 95	80 - 95	94 - 104	60	70 - 95

Types of Acupulation



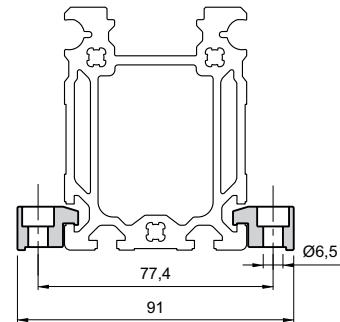
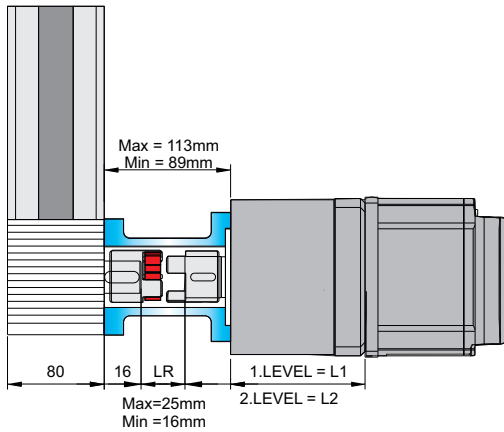
Applications



Reducer Connection Detail



Connection Dimensions

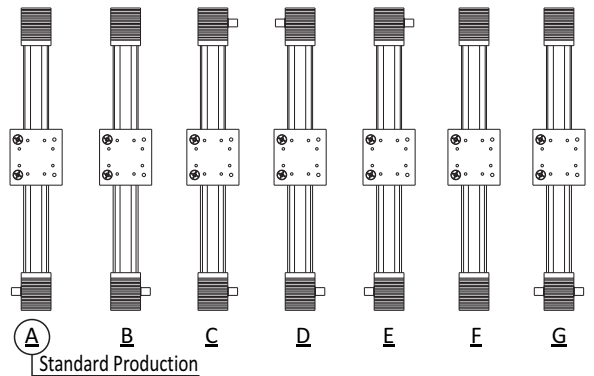


SESAME REDUCER TYPE	L1	L2
PEC 70 (400W For use)	64 mm	92 mm
PEC 90 (750W -1kW - For use)	75 mm	115 mm

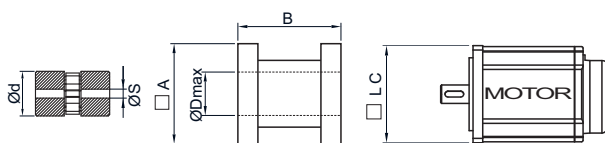
Planetary Gearbox Cycle Rates

1.LEVEL : 3-4-5-7-10
 2.LEVEL : 15-20-25-30-35-40-50-70-100
 Maximum Tork PEC 70 : 79 Nm
 Maximum Tork PEC 90 : 171 Nm
 Maximum Transfer : 6000 rpm

Drive Direction Options



Coupling & Flange Selection



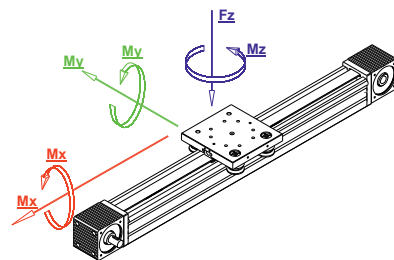
Types of Acupulation



KAPLIN	Ød	ØS	FLANŞ	A	B	ØDmax	LC
JM 40	40	8 - 22	85x 85	65 - 85	80 - 90	47	65 - 85
JM 55	55	8 - 28	95 x 95	80 - 95	94 - 104	60	70 - 95



Upload Values



Load		Dynamic
■ Fx	(N)	780
■ Fy	(N)	2100
■ Fz	(N)	1880
Moment		
■ Mx	(Nm)	150
■ My	(Nm)	165
■ Mz	(Nm)	175

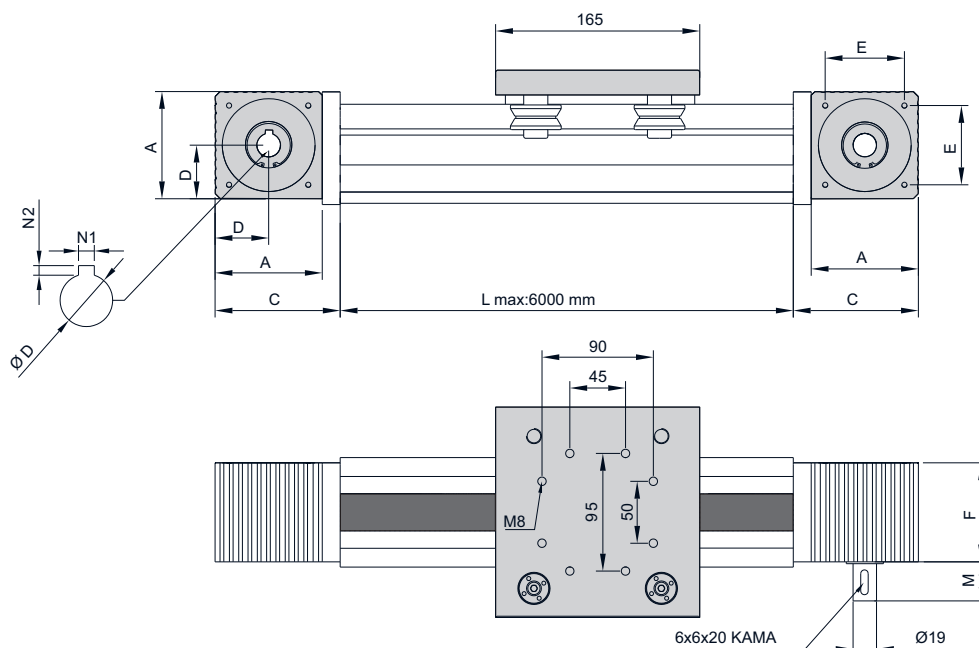
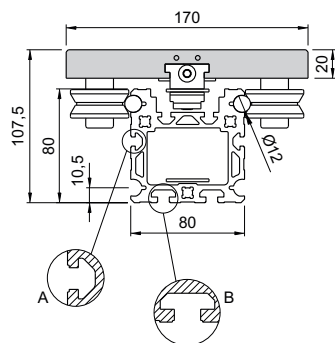
Product code : 5.3.03.080080.1.02.2.Strok

Technical Specifications

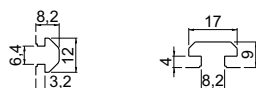
Body	:	80x80 Profilee (Aluminum 6063)
Movement Speed	:	6 mt/sn - 8 mt/sn
Wedge	:	(M12x54) Straight and Eccentric
Movement Distance Per Tour	:	192 mm - 200 mm
Timing Belt	:	5M-30 & 8M-50 Steel Wire Polyurethane NFT Diapered
Timing Pulley	:	Z40-5M-30F & Z24-8M-50F
Induction Shaft	:	Ø12 Chrome Plated Induction h7 mil
Bearing	:	RV201 - 12 / RV202 - 15
Belt Tensile Force	:	2000 - 3000 N
Timing Belt Pitch	:	5 mm - 8 mm
Positioning Accuracy	:	0,2 mm
Basic Weight With Zero Strok	:	7,81 kg
Weight 1000mm Stroke	:	14,25 kg
Automation Control System	:	400 / 750 / 1kw Omron Servo + PLC + Pano

Note: Depending on the operating sensitivity, Asynchronous, Step, Induction, etc. It can be driven by motors.

Technical Details

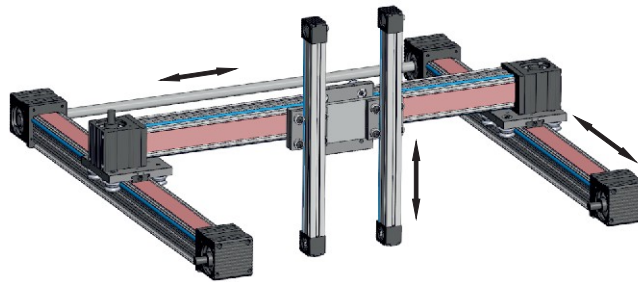


A (CHANNEL DETAIL) B (CHANNEL DETAIL)



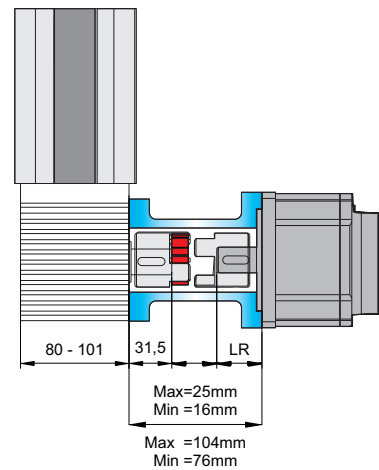
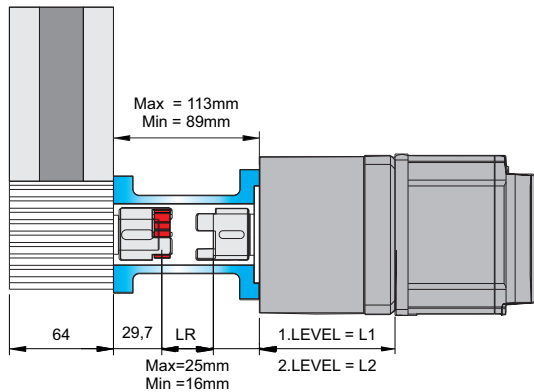
CODE	MODEL	A	C	D	E	F	M	N1	N2	ØD
5.3.03.080080.1.02.2.Strok	5M-30	86,6	101,1	43,3	64	80	31,5	6	3,3	19
5.3.03.080080.1.03.2.Strok	8M-50	100	114,5	50	70,7	101	33,7	8	4	25

Applications



Reducer Connection Detail

Motor Connection Detail

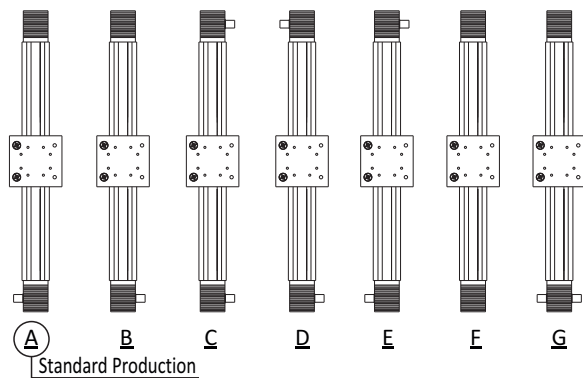


SESAME REDUCER TYPE	L1	L2
PEC 70 (400W For use)	64 mm	92 mm
PEC 90 (750W -1kW - For use)	75 mm	115 mm
PEC 120 (1W -1.5kW - For use)	88 mm	136 mm

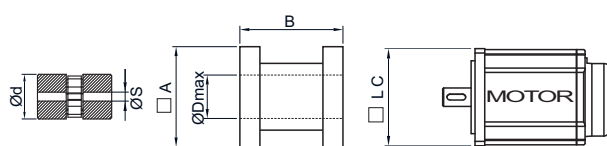
Planetary Gearbox Cycle Rates

- 1.LEVEL : 3-4-5-7-10
- 2.LEVEL : 15-20-25-30-35-40-50-70-100
- Maximum Tork PEC 70 : 79 Nm
- Maximum Tork PEC 90 : 171 Nm
- Maximum Tork PEC 120 : 509 Nm
- Maximum Transfer : 6000 rpm

Drive Direction Options



Coupling & Flange Selection

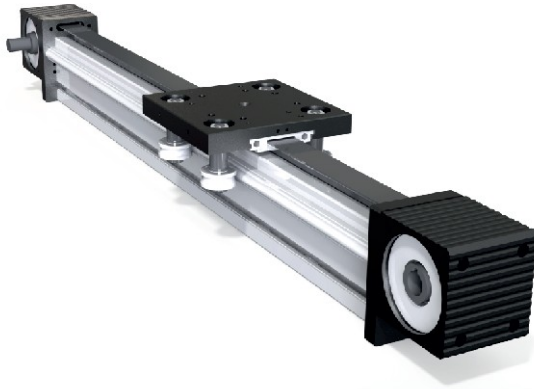


KAPLİN	Ød	ØS	FLANŞ	A	B	ØDmax	LC
JM 40	40	8 - 22	85x 85	65 - 85	80 - 90	47	65 - 85
JM 55	55	8 - 28	95 x 95	80 - 95	94 - 104	60	70 - 95
JM 65	65	10 - 38	120 x 120	85 - 120	90 - 100	65	85 - 120

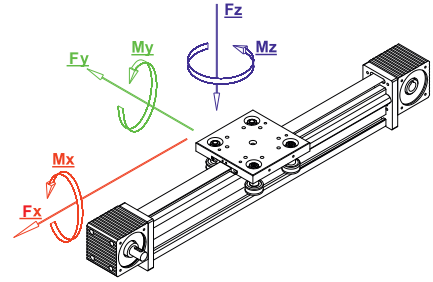
Types of Acupulation



Timing Belt Driven Systems



Upload Values



Load		Dynamic
■ Fx	(N)	615
■ Fy	(N)	860
■ Fz	(N)	1000
Moment		
■ Mx	(Nm)	75
■ My	(Nm)	70
■ Mz	(Nm)	86

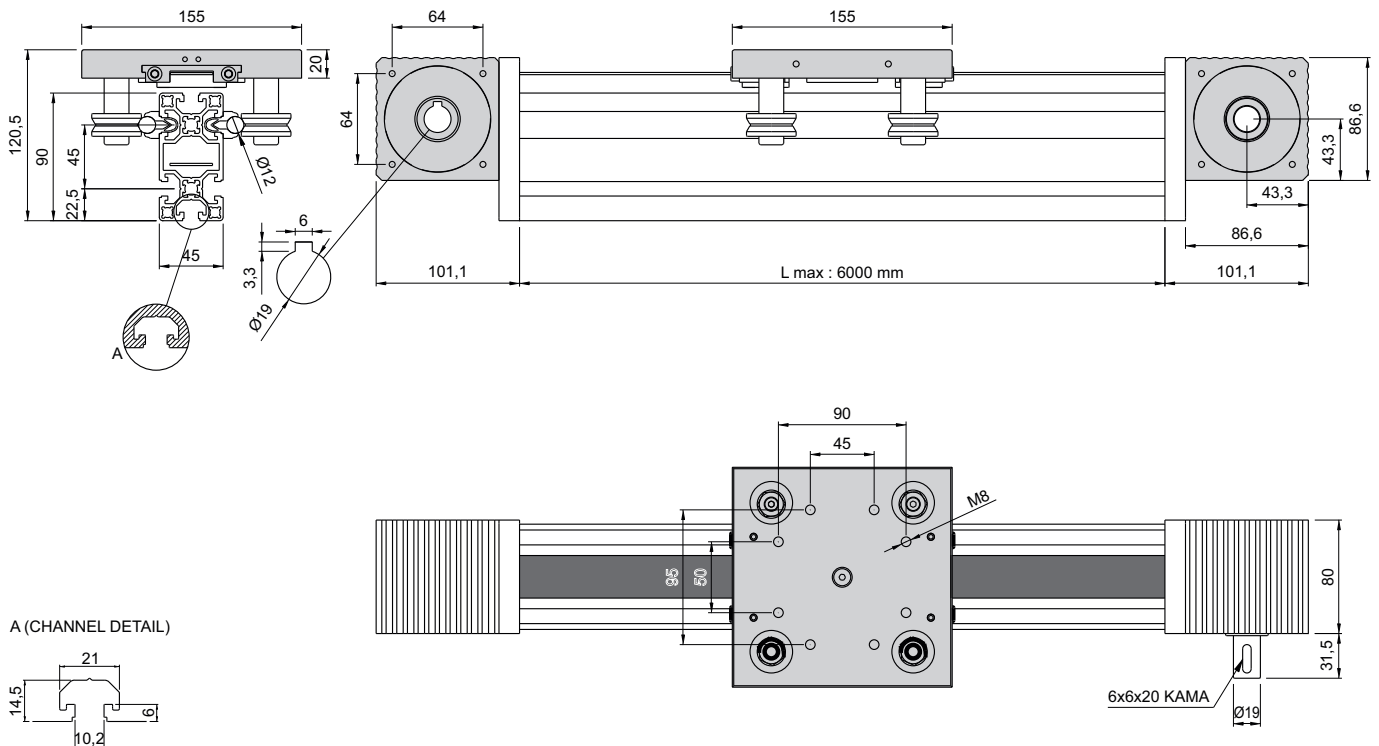
Product code : 5.3.02.045090.1.02.2.Strok

Technical Specifications

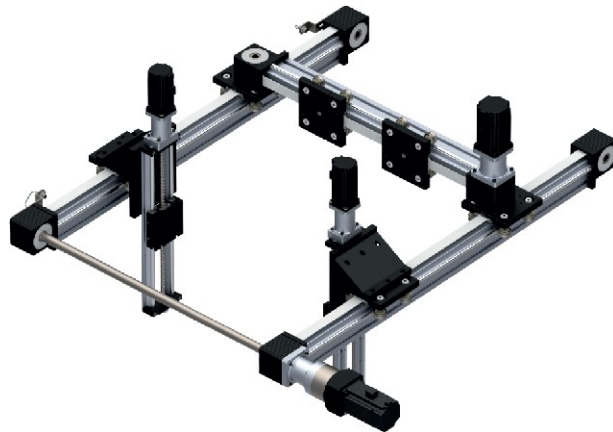
Body	:	45x90 Profile (Aluminum 6063)
Movement Speed	:	6 mt/sn - 8 mt/sn
Wedge	:	(M10x66) Straight and Eccentric
Movement Distance Per Tour	:	200 mm
Timing Belt	:	5M - 30F Çelik Telli NFT Diapered
Timing Pulley	:	Z40-5M-30F
Induction Shaft	:	Ø12 İndüksiyonlu Krom Kaplı h7 mil / HRC 60-62
Bearing	:	RV 201-12 KDD
Belt Tensile Force	:	2000 N
Timing Belt Pitch	:	5 mm
Positioning Accuracy	:	0,2 mm
Basic Weight With Zero Strok	:	7,17 kg
Weight 1000mm Stroke	:	13,3 kg
Automation Control System	:	400 / 750 Watt Omron Servo + PLC + Pano

Note: Depending on the operating sensitivity, Asynchronous, Step, Induction, etc. It can be driven by motors.

Technical Details

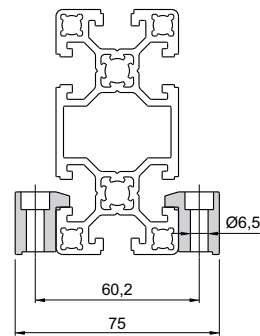
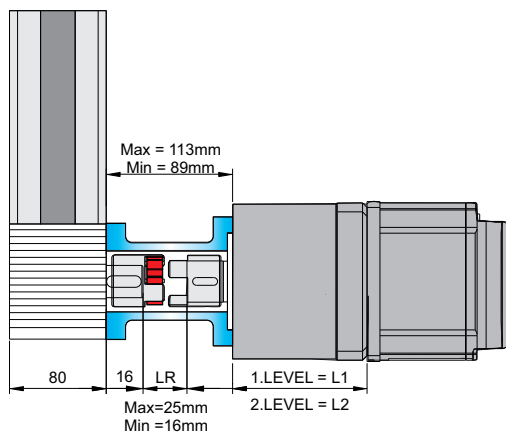


Applications



Reducer Connection Detail

Connection Dimensions

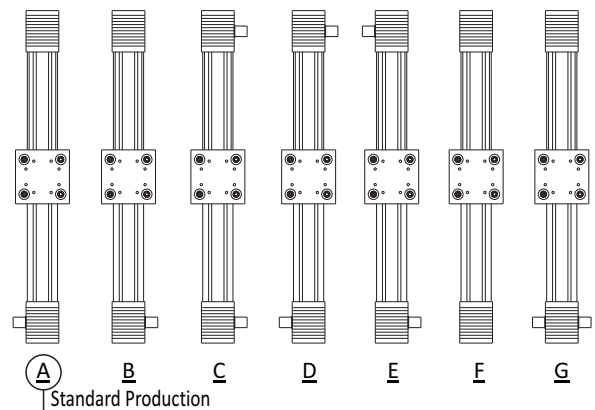


SESAME REDUCER TYPE	L1	L2
PEC 70 (400W For use)	64 mm	92 mm
PEC 90 (750W -1kW - For use)	75 mm	115 mm

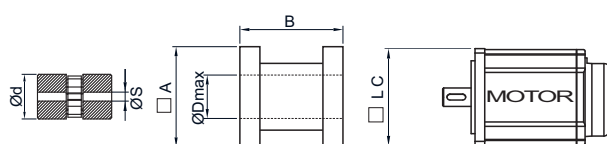
Planetary Gearbox Cycle Rates

- 1.LEVEL : 3-4-5-7-10
- 2.LEVEL : 15-20-25-30-40-50-70
- Maximum Tork PEC 70 : 78 Nm
- Maximum Tork PEC 90 : 171 Nm
- Maximum Transfer : 6000 rpm

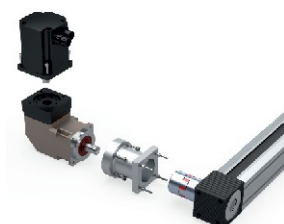
Drive Direction Options



Coupling & Flange Selection

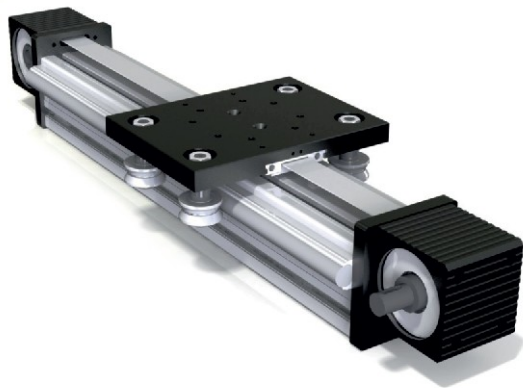


Types of Acupulation

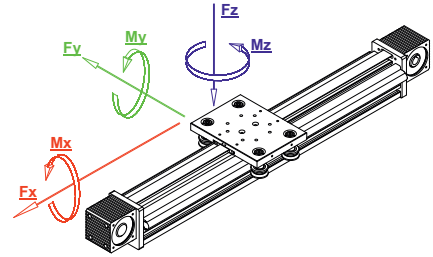


KAPLIN	Ød	ØS	FLANŞ	A	B	ØDmax	LC
JM 40	40	8 - 22	85x 85	65 - 85	80 - 90	47	65 - 85
JM 55	55	8 - 28	95 x 95	80 - 95	94 - 104	60	70 - 95

Driven Belt
Driven Systems



Upload Values



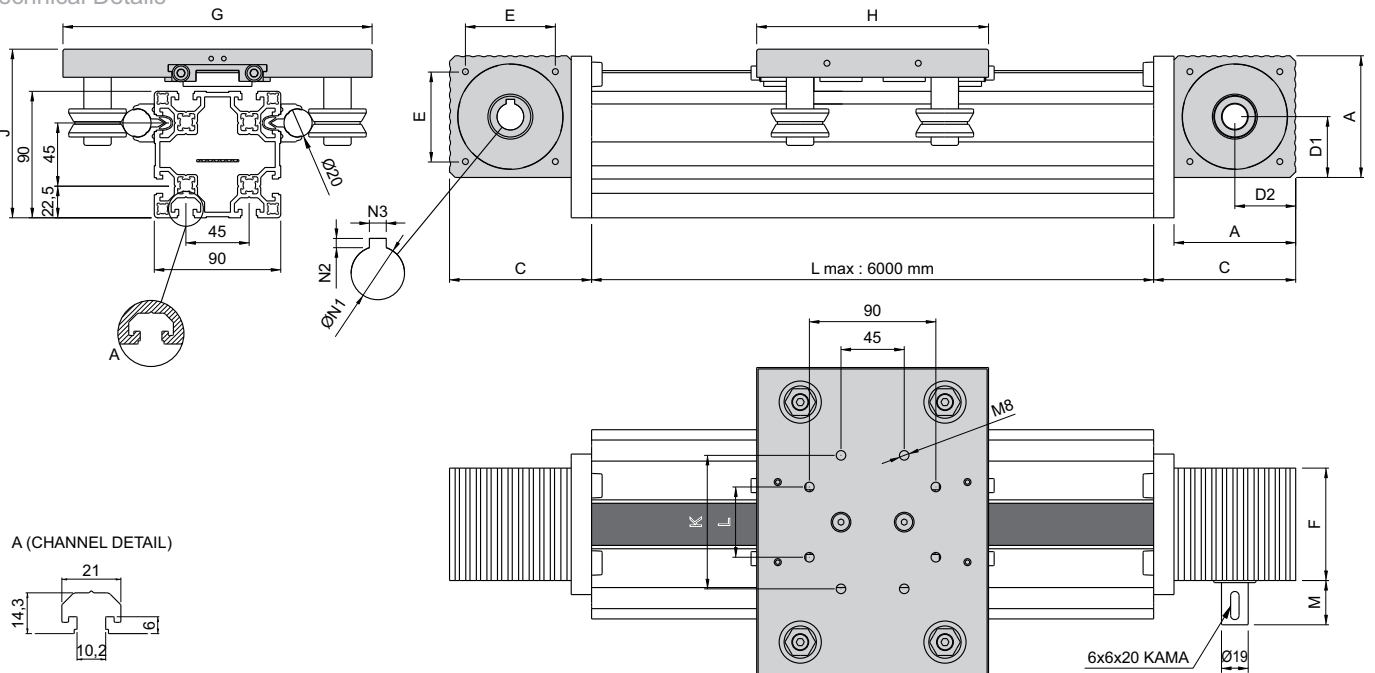
Load		Dynamic
■ Fx	(N)	915
■ Fy	(N)	1295
■ Fz	(N)	2460
Moment		
■ Mx	(Nm)	102
■ My	(Nm)	172
■ Mz	(Nm)	195

Technical Specifications

Body	:	90x90 Profilee (Aluminum 6063)
Movement Speed	:	6 mt/sn - 8 mt/sn
Wedge	:	(M12x68) Straight and Eccentric
Movement Distance Per Tour	:	200 mm / 192 mm
Timing Belt	:	5M-30F & 8M-50F Steel Wire Polyurethane NFT Diapered
Timing Pulley	:	Z40-5M-30F & Z24-8M-50
Induction Shaft	:	Ø20 İndüksiyonlu Krom Kaplı h7 mil / HRC 60-62
Bearing	:	RV 202-15 & RV 203-17
Belt Tensile Force	:	2000 N / 3000 N
Timing Belt Pitch	:	5 mm / 8 mm
Positioning Accuracy	:	0,2 mm
Basic Weight With Zero Strok	:	9,81 kg
Weight 1000mm Stroke	:	23,74 kg
Automation Control System	:	750 / 1kw Omron Servo + PLC + Pano

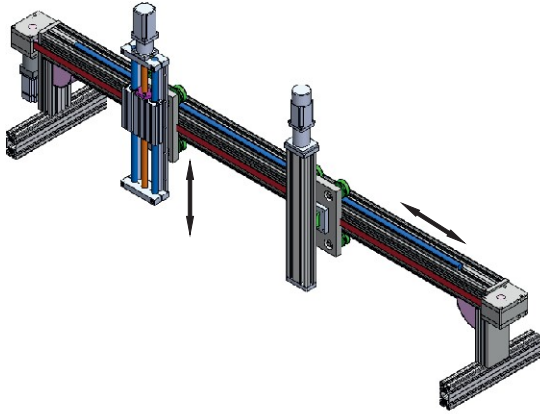
Note: Depending on the operating sensitivity, Asynchronous, Step, Induction, etc. It can be driven by motors.

Technical Details

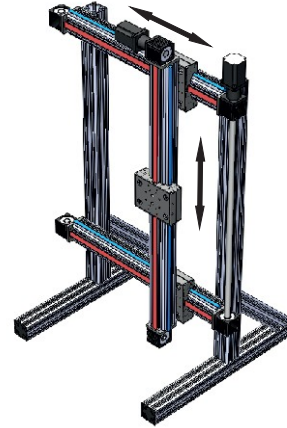


CODE	MODEL	A	C	D1	D2	E	F	G	H	J	K	L	M	N1	N2	N3
5.3.02.090090.1.02.2.Strok	5M-30	86,6	101,1	43,3	43,3	64	80	220	165	120	95	50	31,5	19	3,3	6
5.3.02.090090.1.03.2.Strok	8M-50	100	114,5	41,5	45	70,7	101	250	185	126,6	140	45	33,75	25	4	8

Applications

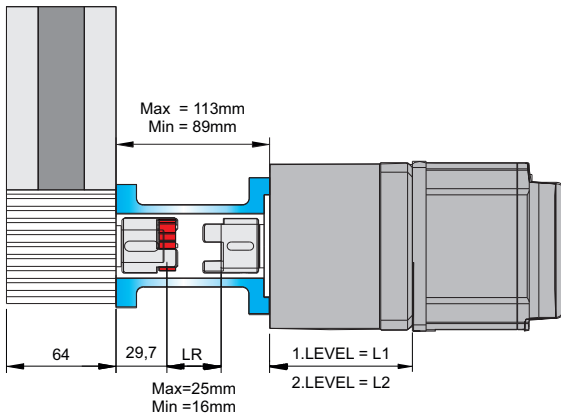


Reducer Connection Detail



Connection Dimensions

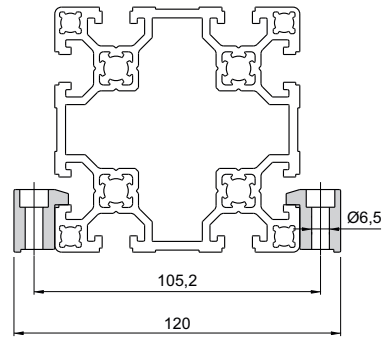
Timing Belt Driven Systems



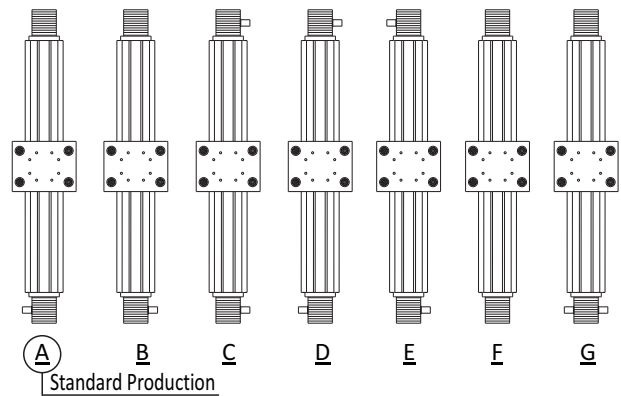
SESAME REDUCER TYPE	L1	L2
PEC 90 (750W -1kW - For use)	75 mm	115 mm
PEC 120 (1W -1.5kW - For use)	88 mm	136 mm

Planetary Gearbox Cycle Rates

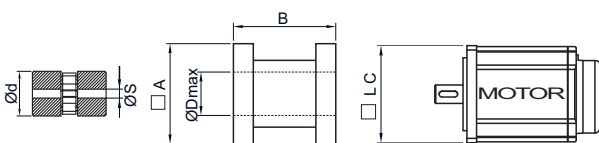
- 1.LEVEL : 3-4-5-7-10
- 2.LEVEL : 15-20-25-30-35-40-50-70-100
- Maximum Tork PEC 90 : 171 Nm
- Maximum Tork PEC 120 : 509 Nm
- Maximum Devir : 6000 rpm



Drive Direction Options



Coupling & Flange Selection



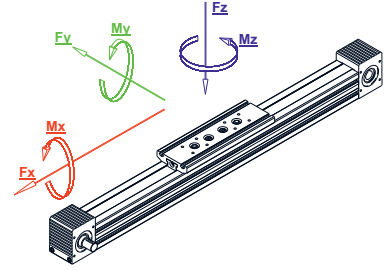
KAPLIN	Ød	ØS	FLANŞ	A	B	ØDmax	LC
JM 40	40	8 - 22	85x 85	65 - 85	80 - 90	47	65 - 85
JM 55	55	8 - 28	95 x 95	80 - 95	94 - 104	60	70 - 95
JM 65	65	10 - 38	120 x 120	85 - 120	90 - 100	65	85 - 120

Types of Acupulation





Upload Values



Load		Dynamic
■ Fx	(N)	1400
■ Fy	(N)	1150
■ Fz	(N)	1260
Moment		
■ Mx	(Nm)	430
■ My	(Nm)	510
■ Mz	(Nm)	470

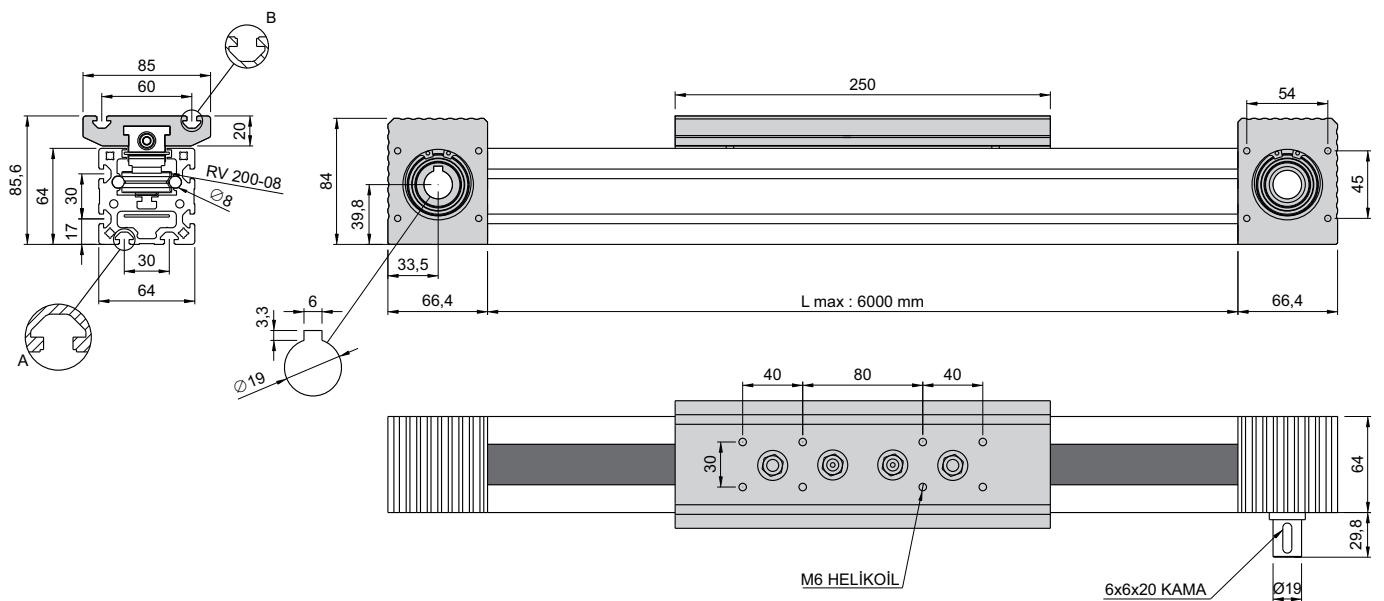
Product code : 5.3.03.064064.1.02.4.Strok

Technical Specifications

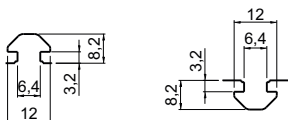
Body	:	64x64 Profile (Aluminum 6063)
Movement Speed	:	8 mt/sn
Wedge	:	(M8x52,3) Straight and Eccentric
Movement Distance Per Tour	:	130 mm
Timing Belt	:	5M-30 Çeliktelli poliüretan
Timing Pulley	:	Z26-5M-30F
Induction Shaft	:	Ø8 Krom Kaplı (0,2-0,33µm) indüksiyonlu
Bearing	:	RV 200-08 (M8xØ10xF6.6) Straight and Eccentric
Belt Tensile Force	:	2000 N
Timing Belt Pitch	:	5 mm
Positioning Accuracy	:	0,1 mm
Basic Weight With Zero Strok	:	4,95 kg
Weight 1000mm Stroke	:	9,75 kg
Automation Control System	:	400 / 750 Watt Omron Servo + PLC + Pano

Note: Depending on the operating sensitivity, Asynchronous, Step, Induction, etc. It can be driven by motors.

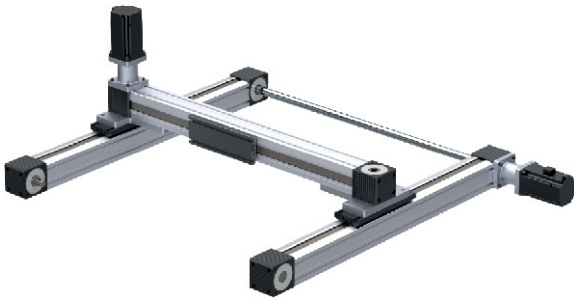
Technical Details



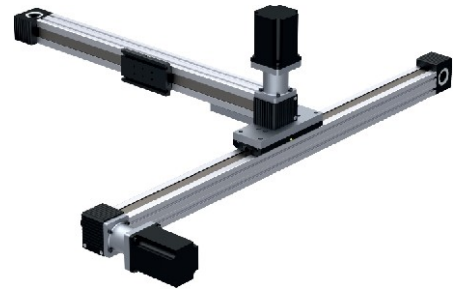
A (M6 CHANNEL DETAIL) B (M6 CHANNEL DETAIL)



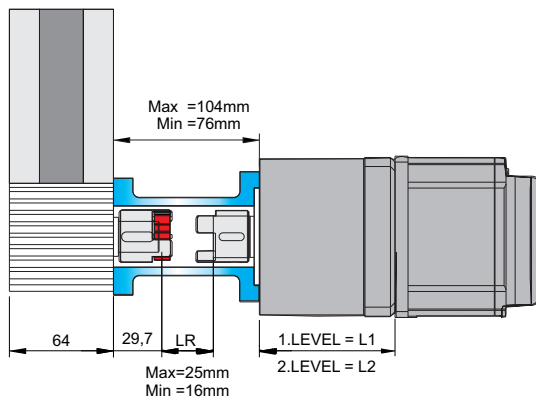
Applications



Reducer Connection Detail



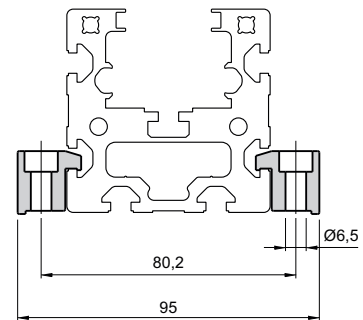
Connection Dimensions



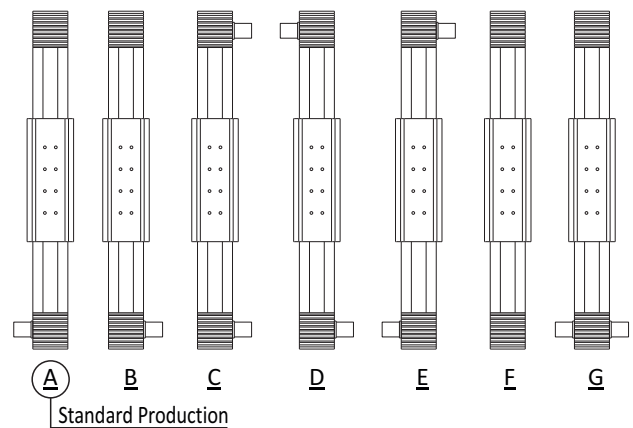
SESAME REDUCER TYPE	L1	L2
PEC 70 (400W For use)	64 mm	92 mm
PEC 90 (750W -1kW - For use)	75 mm	115 mm

Planetary Gearbox Cycle Rates

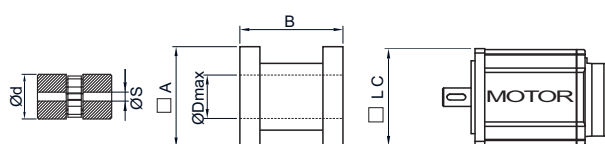
1.LEVEL : 3-4-5-7-10
 2.LEVEL : 15-20-25-30-35-40-50-70-100
 Maximum Tork PEC 70 : 79 Nm
 Maximum Tork PEC 90 : 171 Nm
 Maximum Transfer : 6000 rpm



Drive Direction Options



Coupling & Flange Selection



Types of Acupulation

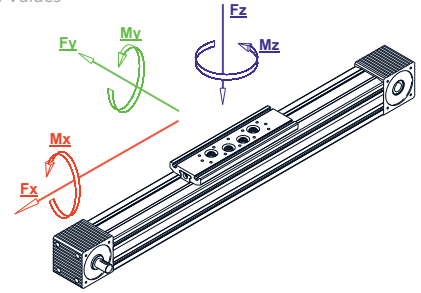


KAPLiN	Ød	ØS	FLANŞ	A	B	ØDmax	LC
JM 40	40	8 - 22	85x 85	65 - 85	80 - 90	47	65 - 85
JM 55	55	8 - 28	95 x 95	80 - 95	94 - 104	60	70 - 95



Product code : 5.3.03.080080.1.02.4.Strok

Upload Values



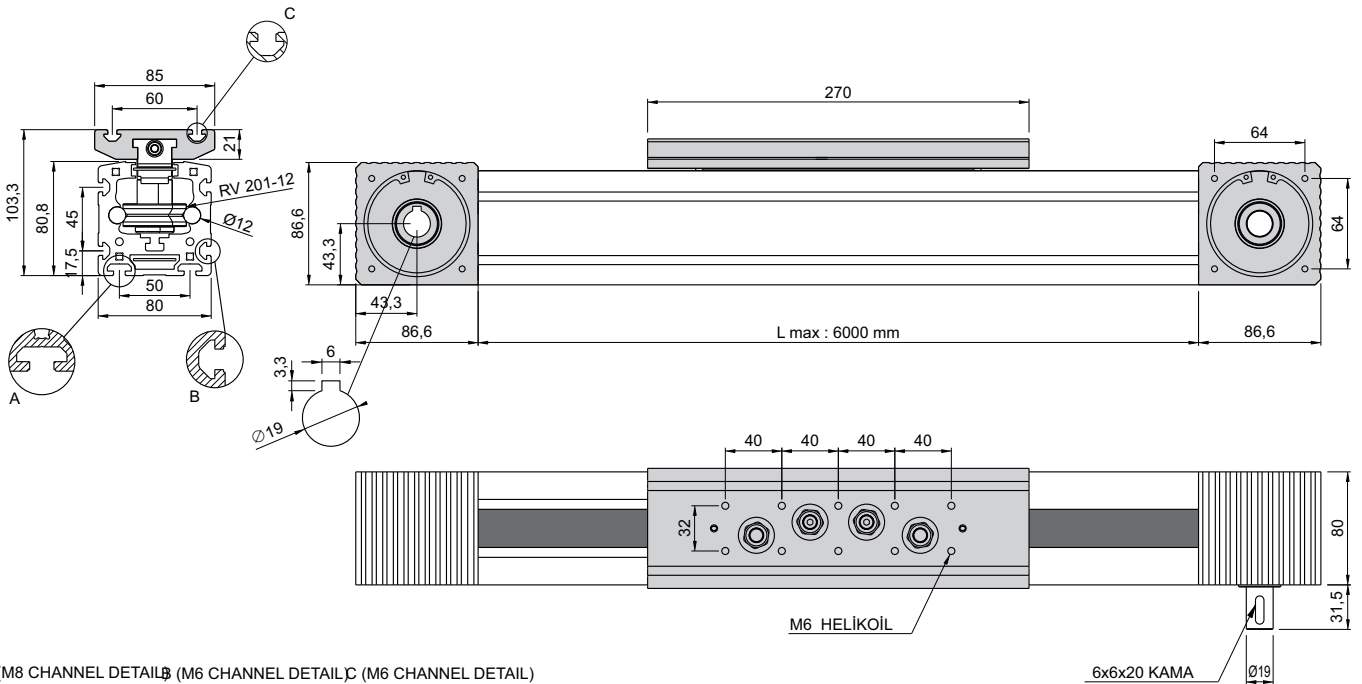
Load		Dynamic
■ Fx	(N)	1650
■ Fy	(N)	1320
■ Fz	(N)	1440
Moment		
■ Mx	(Nm)	650
■ My	(Nm)	720
■ Mz	(Nm)	680

Technical Specifications

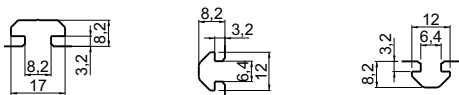
Body	:	80x80 Profile (Aluminum 6063)
Movement Speed	:	8 mt/sn
Wedge	:	(M10x71) Straight and Eccentric
Movement Distance Per Tour	:	200 mm Triger Kayışlı
Timing Belt	:	5M-30 Steel Wire Polyurethane
Timing Pulley	:	Z40-5M-30F
Induction Shaft	:	Ø12 Krom Kaplı (0,2-0,33µm) indüksiyonlu
Bearing	:	RV201-12(M10xØ12xF25) Straight and Eccentric
Belt Tensile Force	:	2000 N
Timing Belt Pitch	:	5 mm
Positioning Accuracy	:	0,1 mm
Basic Weight With Zero Strok	:	8,14 kg
Weight 1000mm Stroke	:	17,30 kg
Automation Control System	:	400 / 750 Watt Omron Servo + PLC + Pano

Note: Depending on the operating sensitivity, Asynchronous, Step, Induction, etc. It can be driven by motors.

Technical Details



A (M8 CHANNEL DETAIL) B (M6 CHANNEL DETAIL) C (M6 CHANNEL DETAIL)

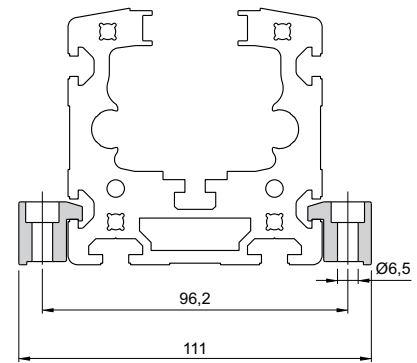
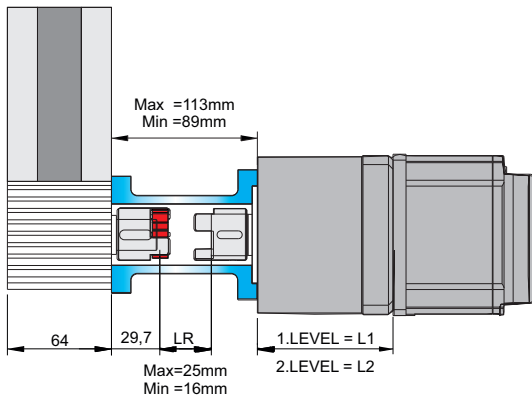


Connection Dimensions



Reducer Connection Detail

Connection Dimensions



SESAME REDUCER TYPE	L1	L2
PEC 70 (400W For use)	64 mm	92 mm
PEC 90 (750W -1kW - For use)	75 mm	115 mm
PEC 120 (1W -1.5kW - For use)	88 mm	136 mm

Planetary Gearbox Cycle Rates

1.LEVEL : 3-4-5-7-10

2.LEVEL : 15-20-25-30-40-50-70

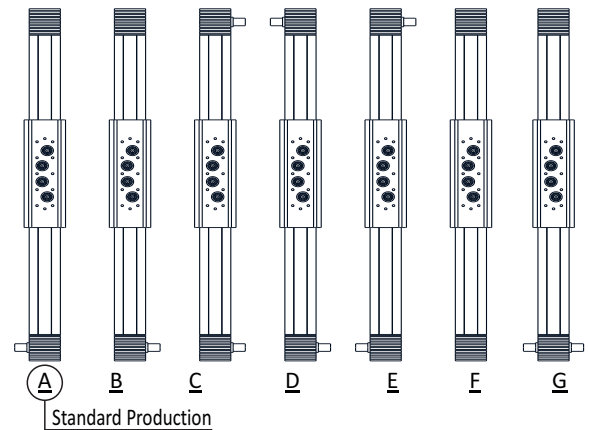
Maximum Tork PEC 70 : 79 Nm

Maximum Tork PEC 90 : 171 Nm

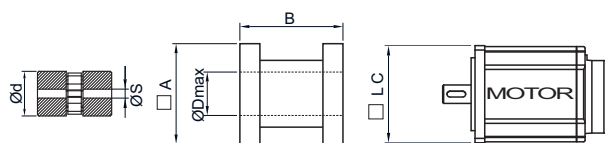
Maximum Tork PEC 120 : 509 Nm

Maximum Tork : 6000 rpm

Drive direction options

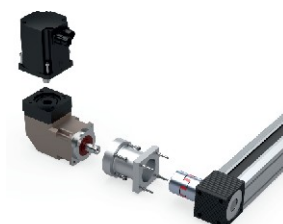


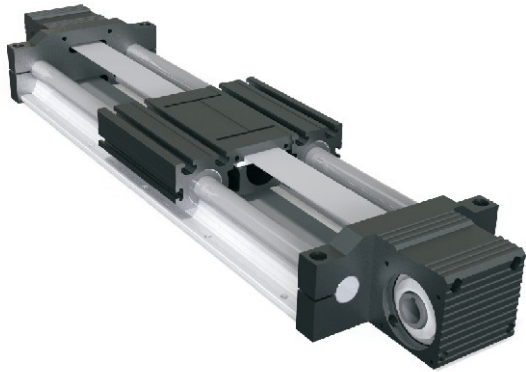
Coupling & Flange Selection



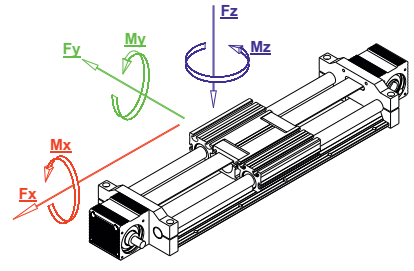
KAPLİN	Ød	ØS	FLANŞ	A	B	ØDmax	LC
JM 40	40	8 - 22	85x 85	65 - 85	80 - 90	47	65 - 85
JM 55	55	8 - 28	95 x 95	80 - 95	94 - 104	60	70 - 95
JM 65	65	10 - 38	120 x 120	85 - 120	90 - 100	65	85 - 120

Types of Acupulation





Upload Values



Load		Dynamic
■ Fx	(N)	618
■ Fy	(N)	1744
■ Fz	(N)	2180
Moment		
■ Mx	(Nm)	228
■ My	(Nm)	195
■ Mz	(Nm)	204

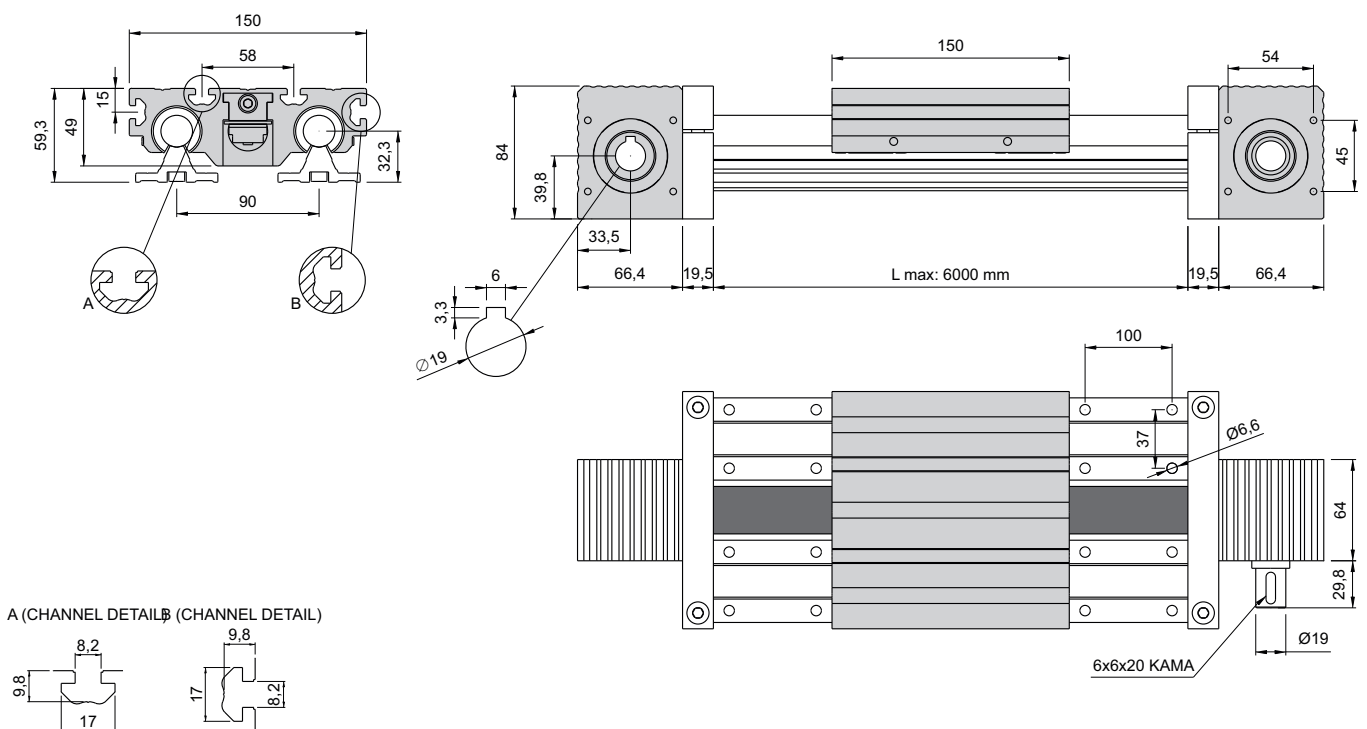
Product code : 5.3.06.150150.3.02.2.Strok

Technical Specifications

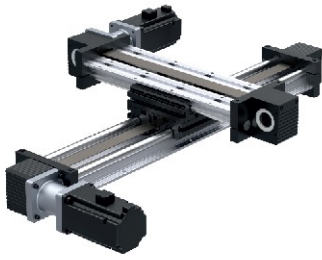
Body	:	Ø20 Mil Alt destek
Movement Speed	:	4 mt/sn
Movement Distance Per Tour	:	200 mm
Timing Belt	:	5M-30 Steel Wire Polyurethane
Timing Pulley	:	Z40-5M-30F
Induction Shaft	:	Ø20 İndüksiyonlu Krom Kaplı h7 mil / HRC 60-62
Bearing	:	LME 20 UU OP
Belt Tensile Force	:	2000 N
Timing Belt Pitch	:	5 mm
Positioning Accuracy	:	0,2 mm
Basic Weight With Zero Strok	:	5,4 kg
Weight 1000mm Stroke	:	8,7 kg
Automation Control System	:	400 / 750 / 1kw Omron Servo + PLC + Pano

Note: Depending on the operating sensitivity, Asynchronous, Step, Induction, etc. It can be driven by motors.

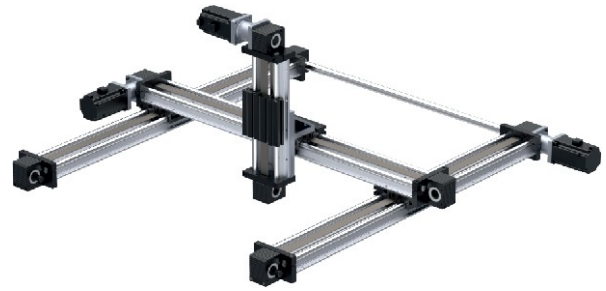
Technical Details



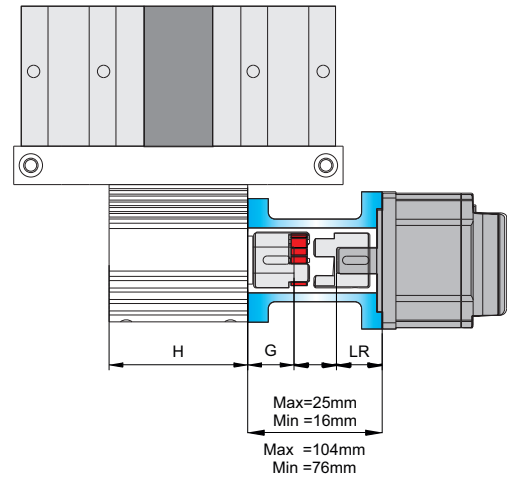
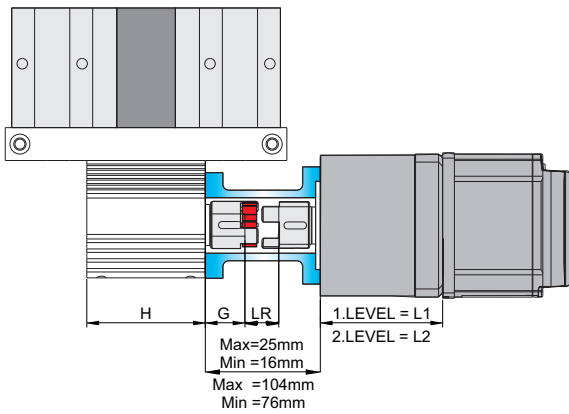
Applications



Reducer Connection Detail



Motor Connection Detail

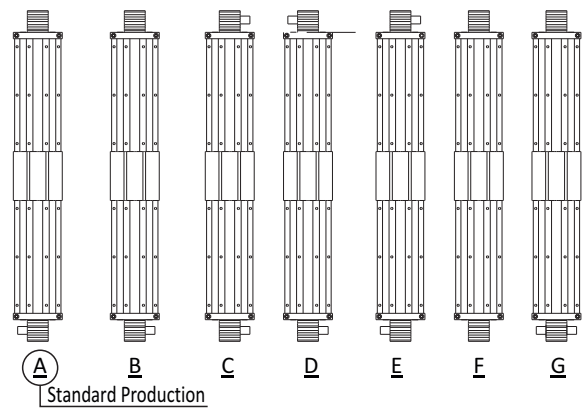


SESAME REDUCER TYPE	L1	L2
PEC 70 (400W For use)	64 mm	92 mm
PEC 90 (750W -1kW - For use)	75 mm	115 mm

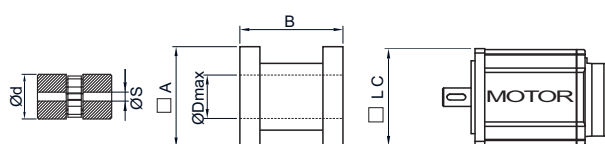
Planetary Gearbox Cycle Rates

1.LEVEL : 3-4-5-7-10
 2.LEVEL : 15-20-25-30-35-40-50-70-100
 Maximum Tork PEC 70 : 79 Nm
 Maximum Tork PEC 90 : 171 Nm
 Maximum Transfer : 6000 rpm

Drive Direction Options



Coupling & Flange Selection

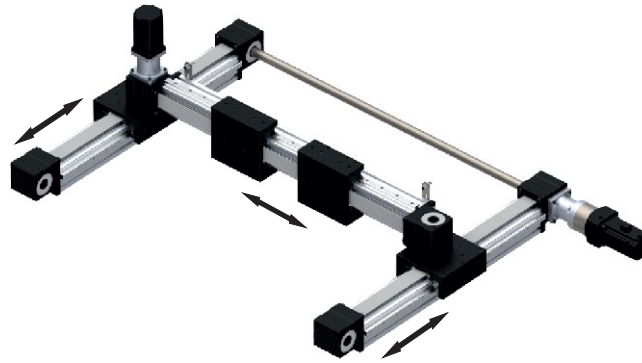


Types of Acupulation



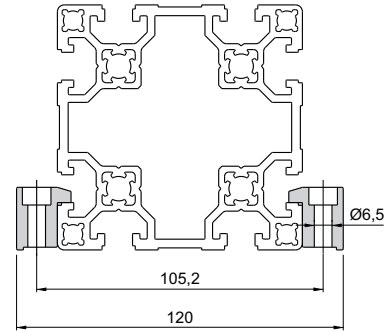
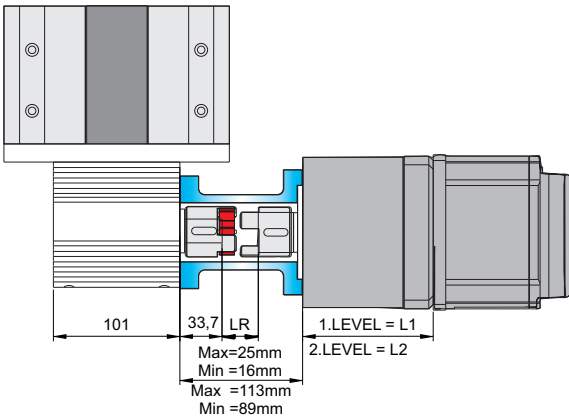
KAPLIN	Ød	ØS	FLANŞ	A	B	ØDmax	LC
JM 40	40	8 - 22	85x 85	65 - 85	80 - 90	47	65 - 85
JM 55	55	8 - 28	95 x 95	80 - 95	94 - 104	60	70 - 95

Applications



Reducer Connection Detail

Connection Dimensions

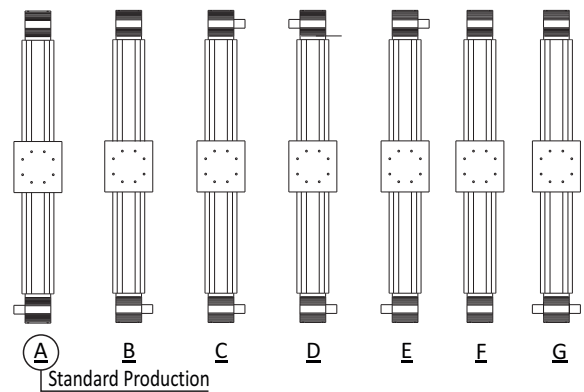


SESAME REDUCER TYPE	L1	L2
PEC 90 (750W -1kW - For use)	75 mm	115 mm
PEC 120 (1W -1.5kW - For use)	88 mm	136 mm

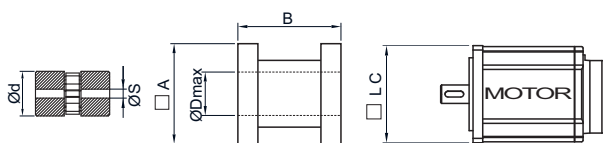
Planetary Gearbox Cycle Rates

1.LEVEL : 3-4-5-7-10
 2.LEVEL : 15-20-25-30-35-40-50-70-100
 Maximum Tork PEC 90 : 171 Nm
 Maximum Tork PEC 120 : 509 Nm
 Maximum Devir : 6000 rpm

Drive Direction Options



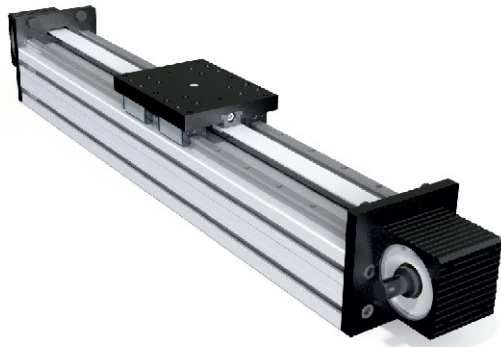
Coupling & Flange Selection



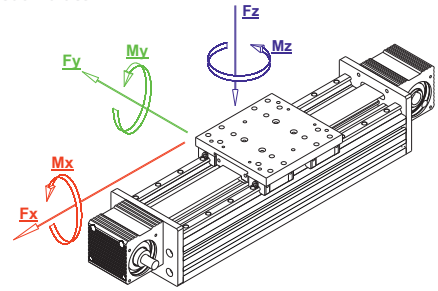
KAPLİN	Ød	ØS	FLANŞ	A	B	ØDmax	LC
JM 40	40	8 - 22	85x 85	65 - 85	80 - 90	47	65 - 85
JM 55	55	8 - 28	95 x 95	80 - 95	94 - 104	60	70 - 95
JM 65	65	10 - 38	120 x 120	85 - 120	90 - 100	65	85 - 120

Types of Acupulation





Upload Values



Load	Dynamic
■ Fx (N)	1350
■ Fy (N)	3215
■ Fz (N)	4560
Moment	
■ Mx (Nm)	690
■ My (Nm)	540
■ Mz (Nm)	540

Note: 4 Evaluated according to the car.

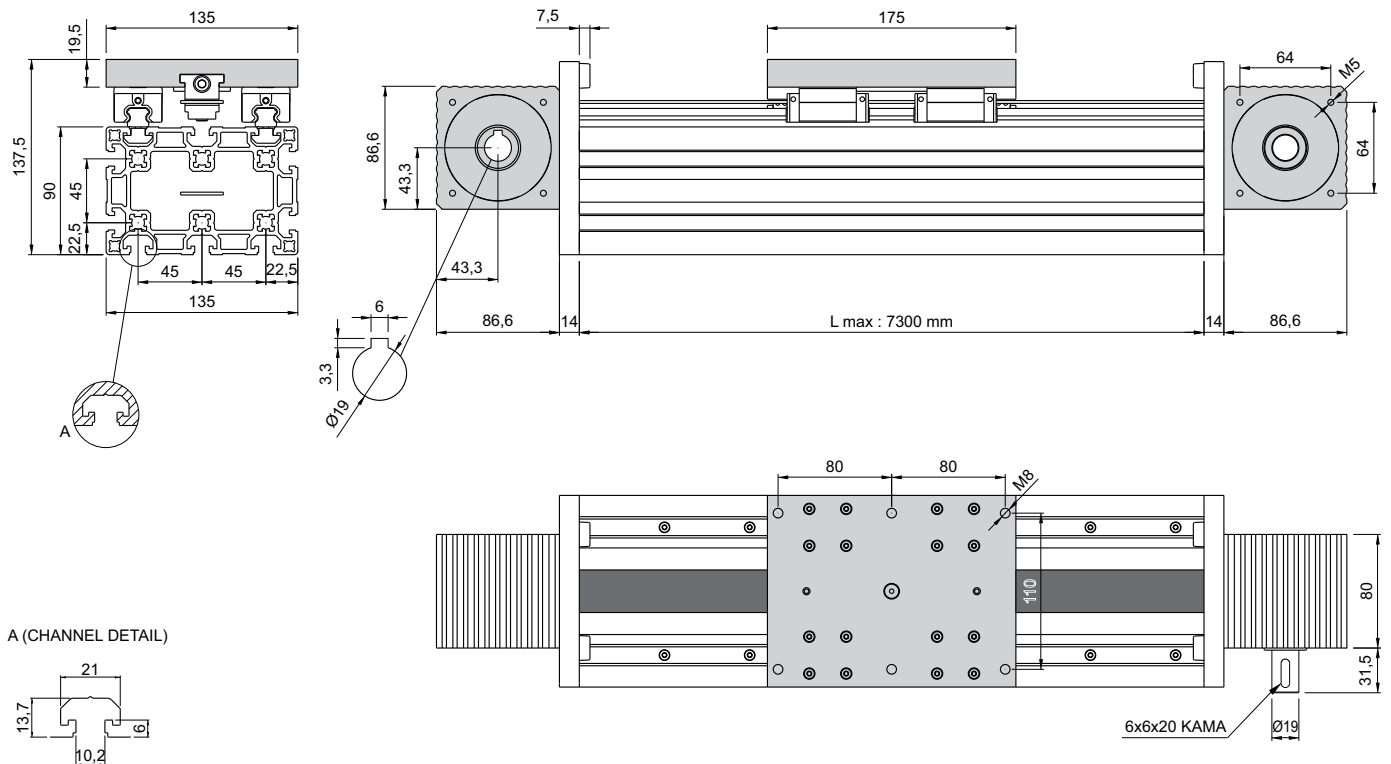
Ürün CODEu/Product code : 5.3.02.090135.2.02.2.Strok

Technical Specifications

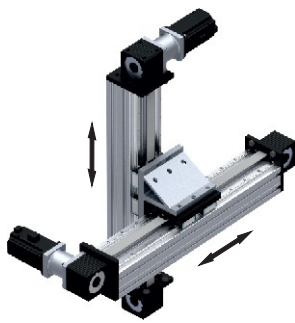
Body	:	90x135 Profile (Aluminum 6063)
Movement Speed	:	3 mt/sn
Movement Distance Per Tour	:	130mm
Timing Belt	:	5M-30F Steel Wire Polyurethane
Timing Pulley	:	5m-F30 Z=26
Linear Rail	:	15 lik Linear Rail (THK)-(DMS)
Linear block	:	15 lik Narrow Low Linear Car
Belt Tensile Force	:	2000 N
Timing Belt Pitch	:	5 mm
Positioning Accuracy	:	0,1 mm
Basic Weight With Zero Strok	:	8,91 kg
Weight 1000mm Stroke	:	21,37 kg
Automation Control System	:	400 / 750 / 1kw Omron Servo + PLC + Pano

Note: Depending on the operating sensitivity, Asynchronous, Step, Induction, etc. It can be driven by motors.

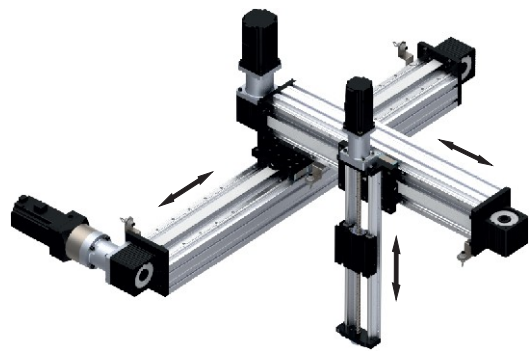
Technical Details



Applications

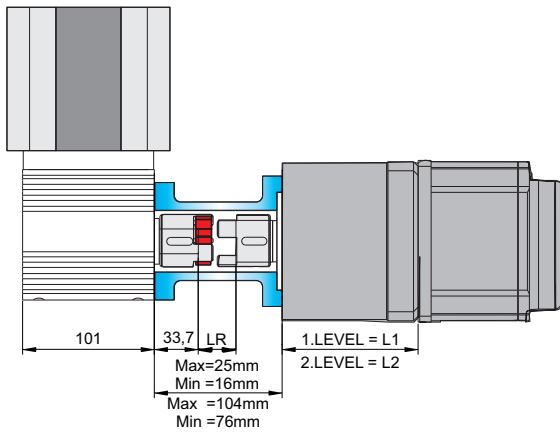


Reducer Connection Detail



Connection Dimensions

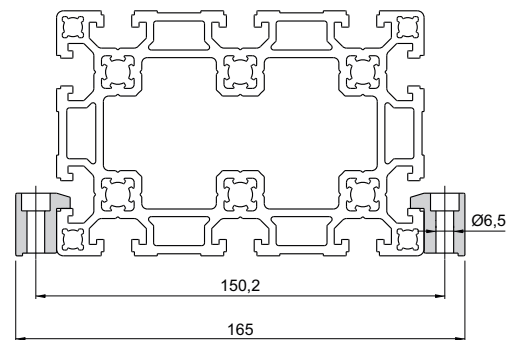
Timing Belt Driven Systems



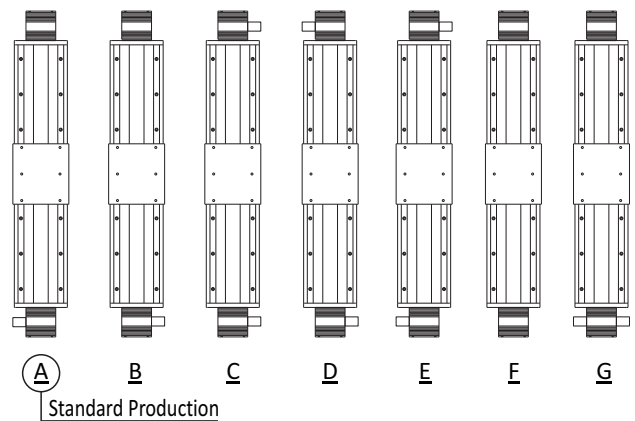
SESAME REDUCER TYPE	L1	L2
PEC 70 (400W For use)	64 mm	92 mm
PEC 90 (750W -1kW - For use)	75 mm	115 mm

Planetary Gearbox Cycle Rates

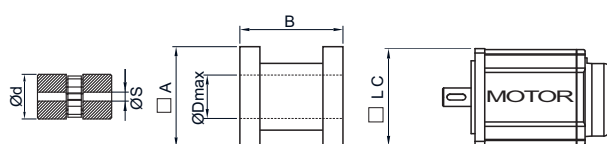
1.LEVEL : 3-4-5-7-10
 2.LEVEL : 15-20-25-30-35-40-50-70-100
 Maximum Tork PEC 70 : 79 Nm
 Maximum Tork PEC 90 : 171 Nm
 Maximum Transfer : 6000 rpm



Drive Direction Options

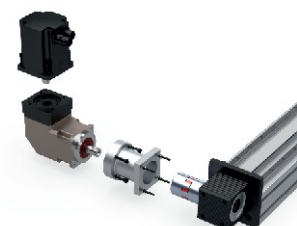


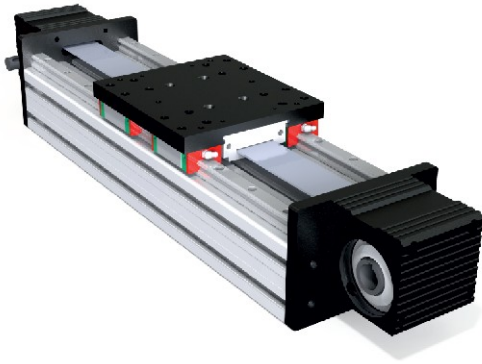
Coupling & Flange Selection



KAPLiN	Ød	ØS	FLANŞ	A	B	ØDmax	LC
JM 40	40	8 - 22	85x 85	65 - 85	80 - 90	47	65 - 85
JM 55	55	8 - 28	95 x 95	80 - 95	94 - 104	60	70 - 95

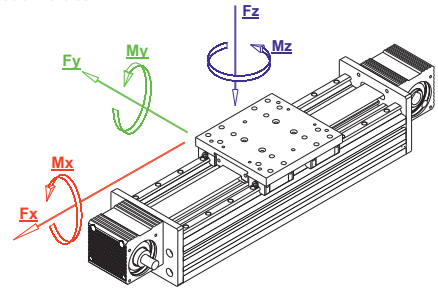
Types of Acupulation





Product code : 5.3.02.090180.2.03.2.Strok

Upload Values



Load	Dynamic
■ Fx (N)	1650
■ Fy (N)	4300
■ Fz (N)	12600
Moment	
■ Mx (Nm)	1447
■ My (Nm)	1613
■ Mz (Nm)	1613

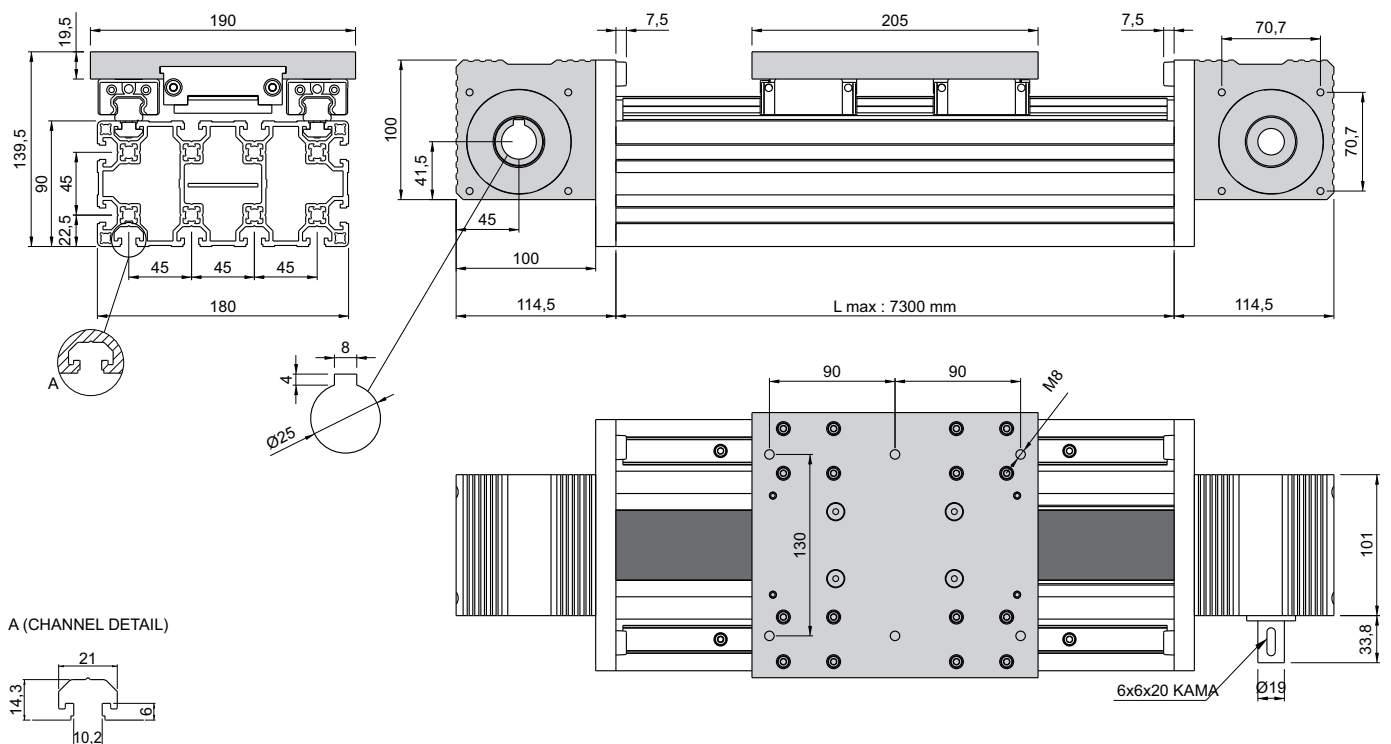
Note: 4 Evaluated according to the car.

Technical Specifications

Body	:	90x180 Profile (Aluminum 6063)
Max Speed	:	3 mt/sn
Movement Distance Per Tour	:	192mm
Timing Belt	:	8M-F50 Steel Wire Polyurethane
Timing Pulley	:	Z24-8M-50F
Linear Rail	:	20 lik Lineer Ray
Linear Block	:	20 lik Dar Lineer Araba
Belt Tensile Force	:	3000 N
Belt Pitch	:	8 mm
Positioning accuracy	:	0,1 mm
Basic Weight With Zero Strok	:	15,02 kg
Weight 1000mm Stroke	:	31,15 kg
Automation Control System	:	400 / 750 / 1kw Omron Servo + PLC + Pano

Note: Depending on the operating sensitivity, Asynchronous, Step, Induction, etc. It can be driven by motors.

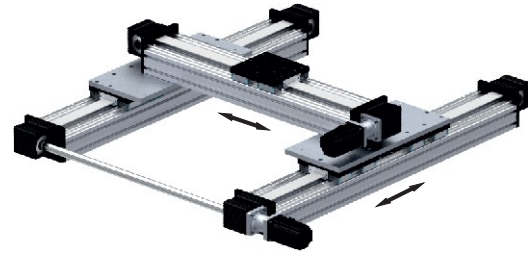
Technical Details



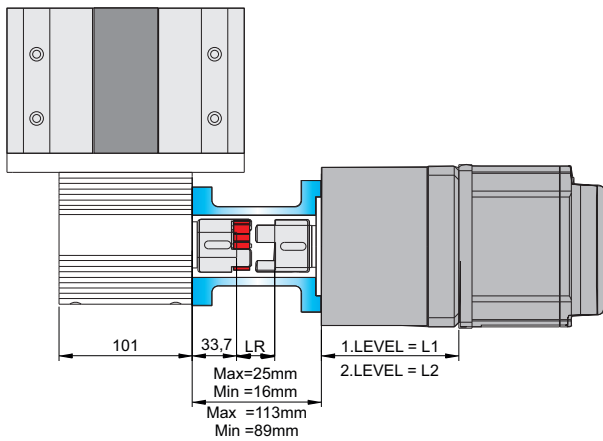
Applications



Reducer Connection Detail



Connection Dimensions

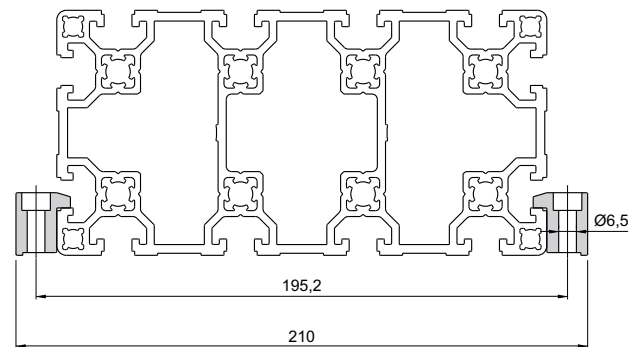


SESAME REDUCER TYPE	L1	L2
PEC 90 (750W -1kW - For use)	75 mm	115 mm
PEC 120 (1W -1.5kW - For use)	88 mm	136 mm

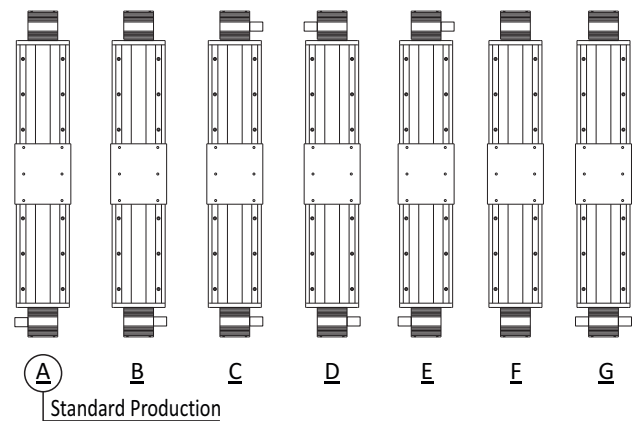
Planetary Gearbox Cycle Rates

1.LEVEL : 3-4-5-7-10
2.LEVEL : 15-20-25-30-35-40-50-70-100

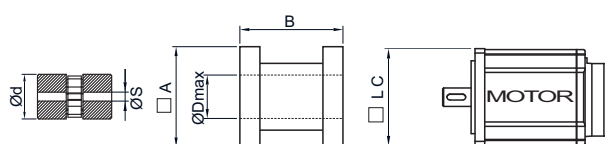
Maximum Tork PEC 90 : 171 Nm
Maximum Tork PEC 120 : 509 Nm
Maximum Devir : 6000 rpm



Drive Direction Options

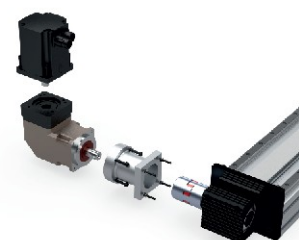


Coupling & Flange Selection



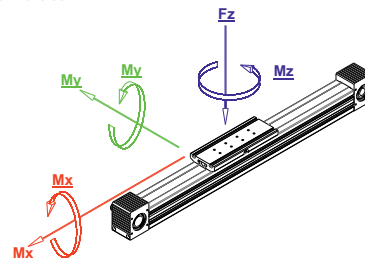
KAPLİN	Ød	ØS	FLANŞ	A	B	ØDmax	LC
JM 40	40	8 - 22	85x 85	65 - 85	80 - 90	47	65 - 85
JM 55	55	8 - 28	95 x 95	80 - 95	94 - 104	60	70 - 95
JM 65	65	10 - 38	120 x 120	85 - 120	90 - 100	65	85 - 120

Types of Acupulation





Upload Values



Load		Dynamic
■ Fx	(N)	2200
■ Fy	(N)	2460
■ Fz	(N)	4240
Moment		
■ Mx	(Nm)	385
■ My	(Nm)	415
■ Mz	(Nm)	540

Note: 2 Rated by car.

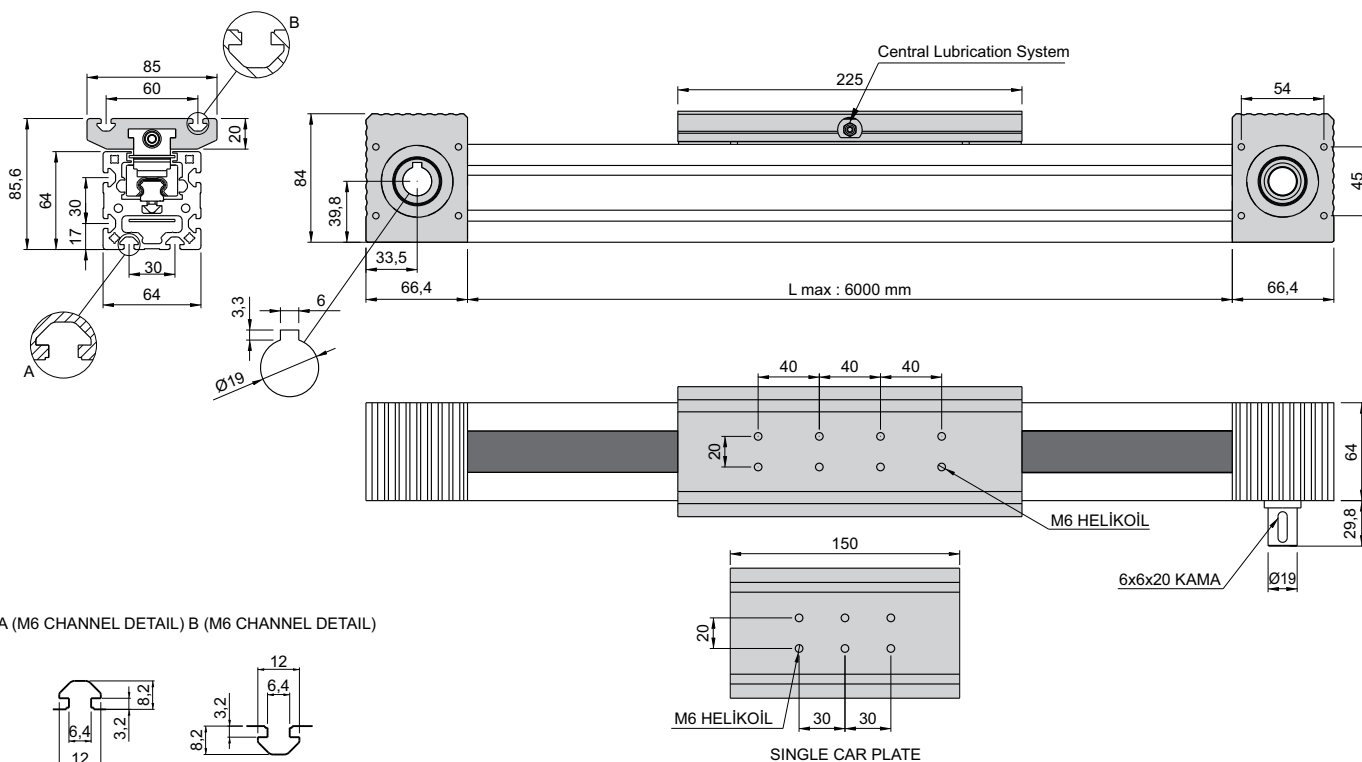
Product code : 5.3.03.064064.2.02.2.Strok

Technical Specifications

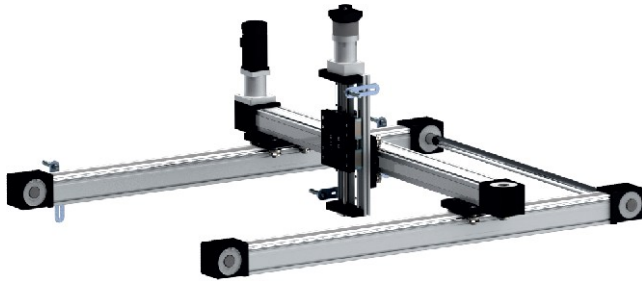
Body	:	64x64 Profile (Aluminum 6063)
Movement Speed	:	4 mt/sn
Movement Distance Per Tour	:	130mm
Timing Belt	:	5m-F30 Z=26
Timing Pulley	:	5M-30 Steel Wire Polyurethane
Linear Rail	:	15 lik Linear Rail
Linear block	:	15 lik Narrow Low Linear Car
Belt Tensile Force	:	2000 N
Timing Belt Pitch	:	5 mm
Positioning Accuracy	:	0,1 mm
Basic Weight With Zero Strok	:	4.6 kg
Weight 1000mm Stroke	:	10.7 kg
Automation Control System	:	400 / 750 / 1kw Omron Servo + PLC + Pano

Note: Depending on the operating sensitivity, Asynchronous, Step, Induction, etc. It can be driven by motors.

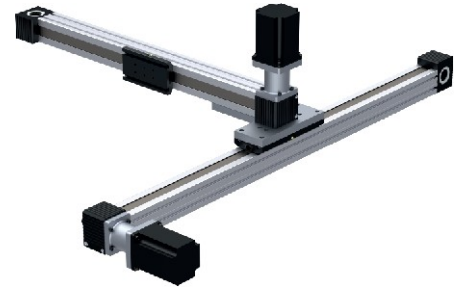
Technical Details



Applications

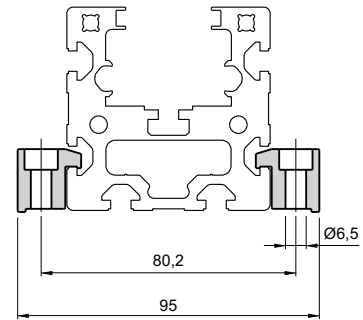
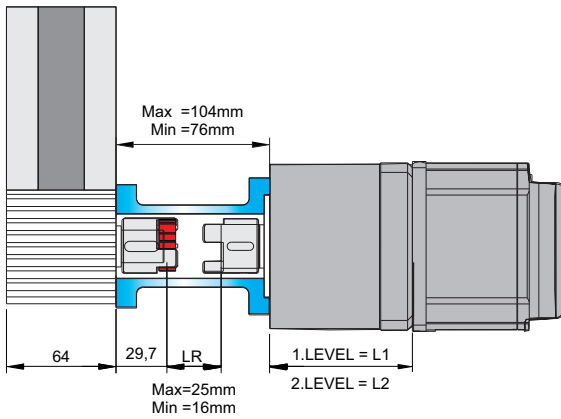


Reducer Connection Detail



Connection Dimensions

Timing Belt Driven Systems

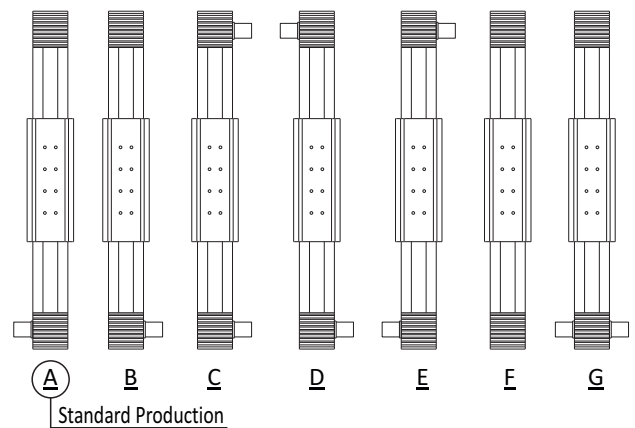


SESAME REDUCER TYPE	L1	L2
PEC 70 (400W For use)	64 mm	92 mm
PEC 90 (750W -1kW - For use)	75 mm	115 mm

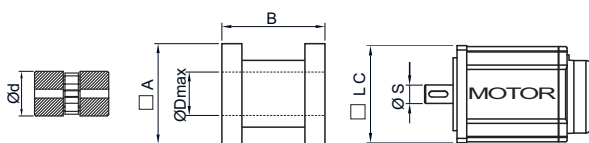
Planetary Gearbox Cycle Rates

1.LEVEL : 3-4-5-7-10
 2.LEVEL : 15-20-25-30-35-40-50-70-100
 Maximum Tork PEC 70 : 79 Nm
 Maximum Tork PEC 90 : 171 Nm
 Maximum Transfer : 6000 rpm

Drive Direction Options



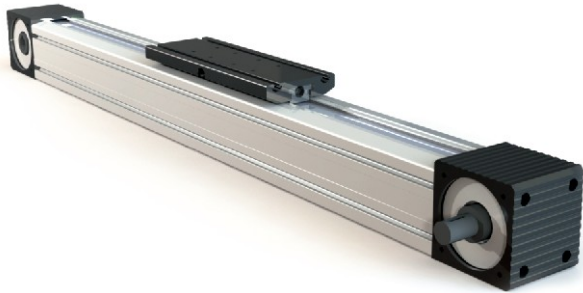
Coupling & Flange Selection



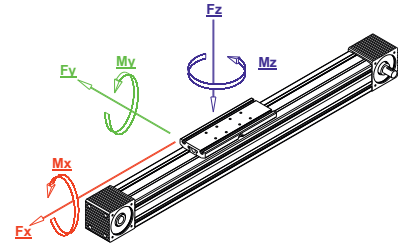
Types of Acupulation



KAPLIN	Ød	ØS	FLANŞ	A	B	ØDmax	LC
JM 40	40	8 - 22	85x 85	65 - 85	80 - 90	47	65 - 85
JM 55	55	8 - 28	95 x 95	80 - 95	94 - 104	60	70 - 95



Upload Values



Load		Dynamic
■ Fx	(N)	2400
■ Fy	(N)	2760
■ Fz	(N)	7260
Moment		
■ Mx	(Nm)	412
■ My	(Nm)	465
■ Mz	(Nm)	580

Note: 2 Evaluated according to the car.

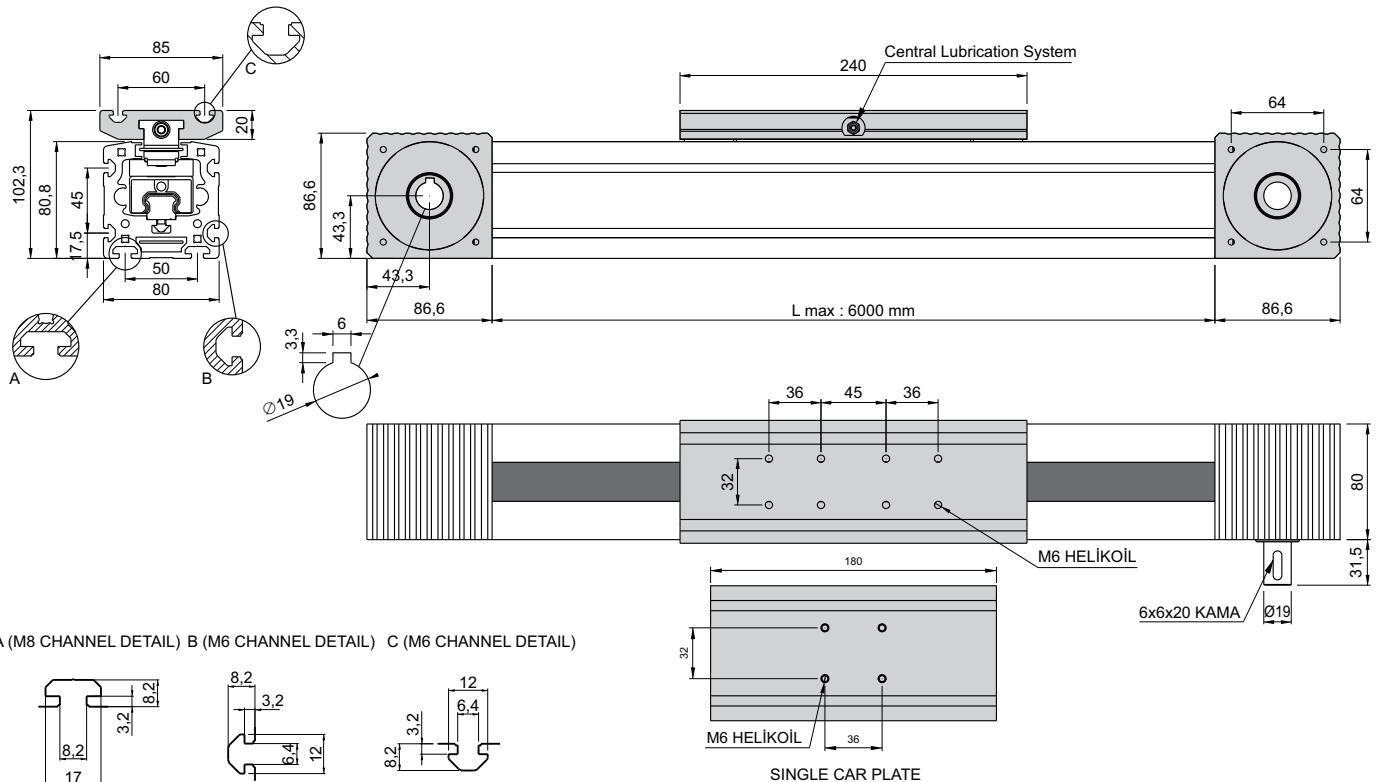
Product code : 5.3.03.080080.2.02.2.Strok

Technical Specifications

Body	:	80x80 Profile (Aluminum 6063)
Max Speed	:	5 mt/sn
Movement Distance Per Tour	:	200mm
Timing Belt	:	5M-F30 NFT diapered
Timing Pulley	:	5m-F30 Z=40
Linear Rail	:	20 lik Linear Ray
Linear Block	:	20 lik Narrow Low Linear Car
Belt Tensile Force	:	2000 N
Belt Pitch	:	5 mm
Positioning accuracy	:	0,1 mm
Basic Weight With Zero Strok	:	7,7 kg
Weight 1000mm Stroke	:	17,2 kg
Automation Control System	:	400 / 750 / 1kw Omron Servo + PLC + Pano

Note: Depending on the operating sensitivity, Asynchronous, Step, Induction, etc. It can be driven by motors.

Technical Details

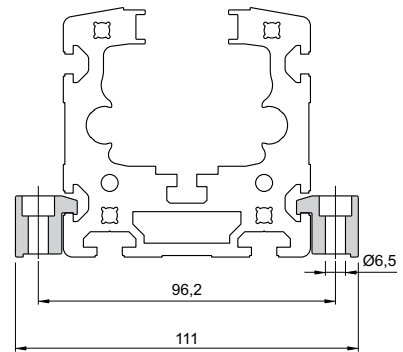
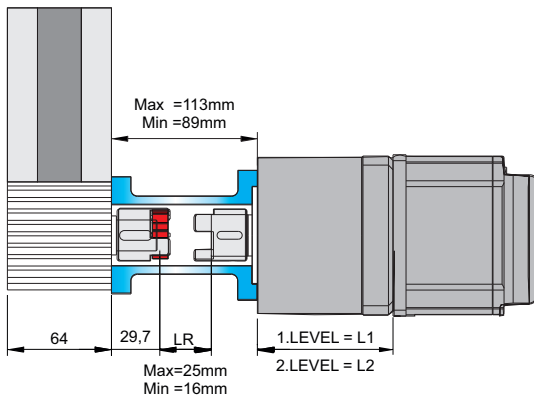


Applications



Reducer Connection Detail

Connection Dimensions

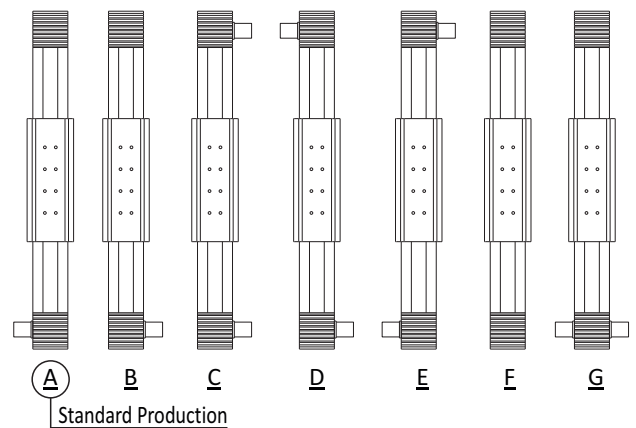


SESAME REDUCER TYPE	L1	L2
PEC 70 (400W For use)	64 mm	92 mm
PEC 90 (750W -1kW - For use)	75 mm	115 mm
PEC 120 (1W -1.5kW - For use)	88 mm	136 mm

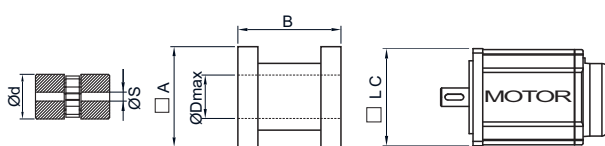
Planetary Gearbox Cycle Rates

- 1.LEVEL : 3-4-5-7-10
- 2.LEVEL : 15-20-25-30-35-40-50-70-100
- Maximum Tork PEC 70 : 79 Nm
- Maximum Tork PEC 90 : 171 Nm
- Maximum Tork PEC 120 : 509 Nm
- Maximum Devir : 6000 rpm

Drive Direction Options



Coupling & Flange Selection



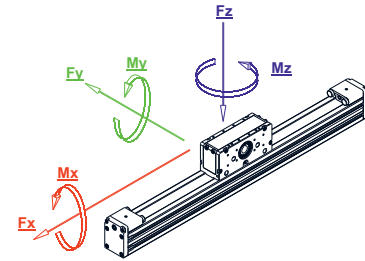
KAPLİN	Ød	ØS	FLANŞ	A	B	ØDmax	LC
JM 40	40	8 - 22	85x 85	65 - 85	80 - 90	47	65 - 85
JM 55	55	8 - 28	95 x 95	80 - 95	94 - 104	60	70 - 95
JM 65	65	10 - 38	120 x 120	85 - 120	90 - 100	65	85 - 120

Types of Acupulation





Upload Values



Yük/Load		Dinamik/Dynamic
■ Fx	(N)	2200
■ Fy	(N)	2460
■ Fz	(N)	2000
Moment		
■ Mx	(Nm)	385
■ My	(Nm)	300
■ Mz	(Nm)	540

Note: 2 Rated by car.

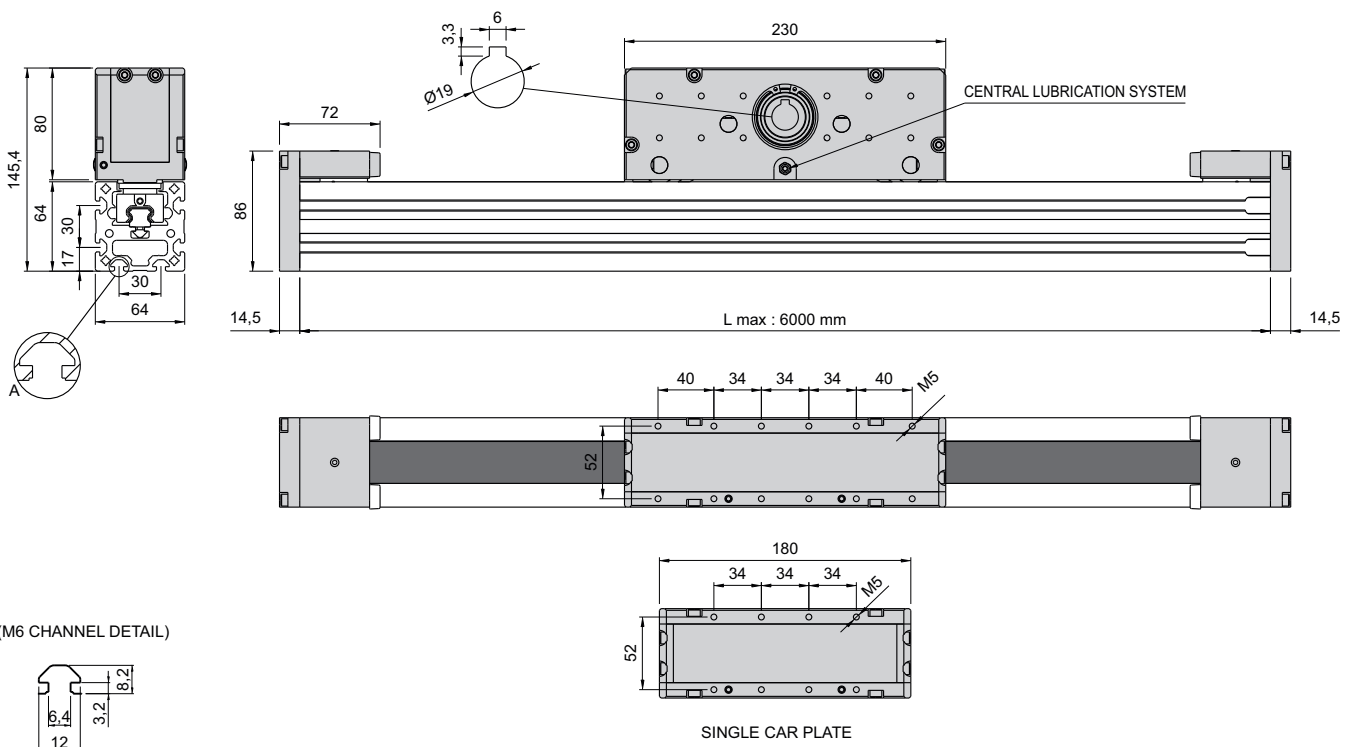
Product code : 5.3.03.064064.2.05.2.Strok

Technical Specifications

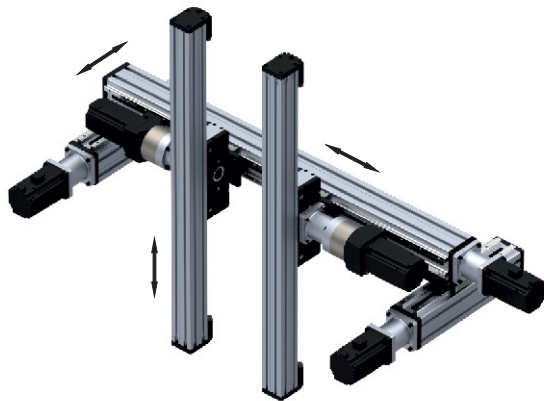
Body	:	64x64 Profile (Aluminum 6063)
Movement Speed	:	3 mt/sn
Movement Distance Per Tour	:	130mm
Timing Belt	:	5M-30 Steel Wire Polyurethane
Timing Pulley	:	Z26-5M-30F
Linear Rail	:	15 lik Linear Ray
Linear block	:	15 lik Narrow Low Linear Car
Belt Tensile Force	:	2000 N
Timing Belt Pitch	:	5 mm
Positioning Accuracy	:	0,1 mm
Basic Weight With Zero Strok	:	4.6 kg
Weight 1000mm Stroke	:	10.7 kg
Automation Control System	:	400 / 750 / 1kw Omron Servo + PLC + Pano

Note: Depending on the operating sensitivity, Asynchronous, Step, Induction, etc. It can be driven by motors.

Technical Details



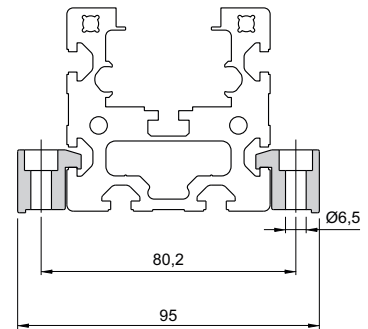
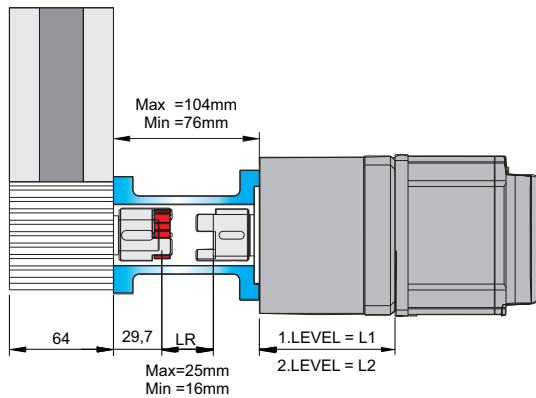
Applications



Reducer Connection Detail



Connection Dimensions

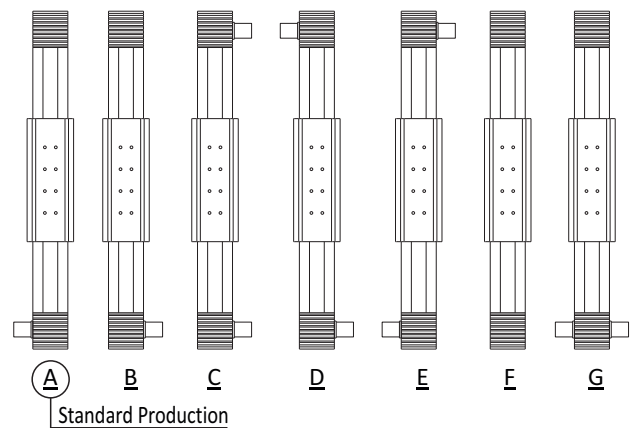


SESAME REDUCER TYPE	L1	L2
PEC 70 (400W For use)	64 mm	92 mm
PEC 90 (750W -1kW - For use)	75 mm	115 mm

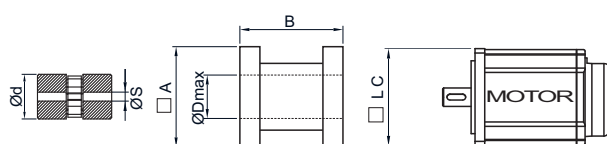
Planetary Gearbox Cycle Rates

1.LEVEL : 3-4-5-7-10
 2.LEVEL : 15-20-25-30-35-40-50-70-100
 Maximum Tork PEC 70 : 79 Nm
 Maximum Tork PEC 90 : 171 Nm
 Maximum Transfer : 6000 rpm

Drive Direction Options

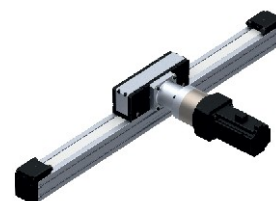


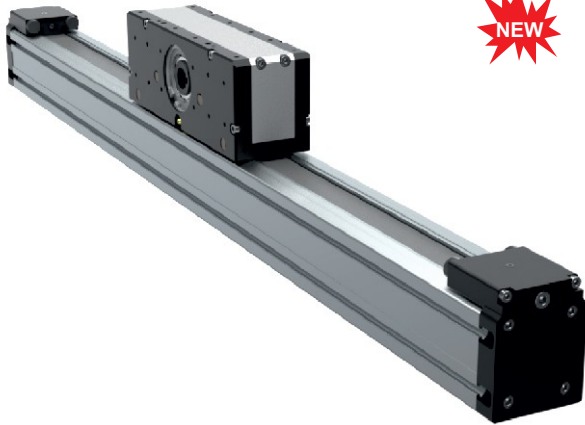
Coupling & Flange Selection



KAPLiN	Ød	ØS	FLANŞ	A	B	ØDmax	LC
JM 40	40	8 - 22	85x 85	65 - 85	80 - 90	47	65 - 85
JM 55	55	8 - 28	95 x 95	80 - 95	94 - 104	60	70 - 95

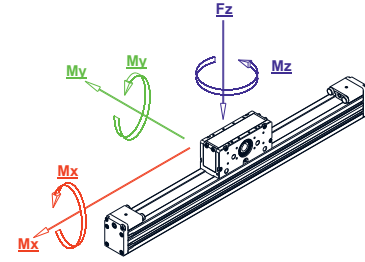
Types of Acupulation





NEW

Upload Values



Load		Dynamic
■ Fx	(N)	2400
■ Fy	(N)	2760
■ Fz	(N)	7220
Moment		
■ Mx	(Nm)	415
■ My	(Nm)	480
■ Mz	(Nm)	570

Note: 2 Rated by car.

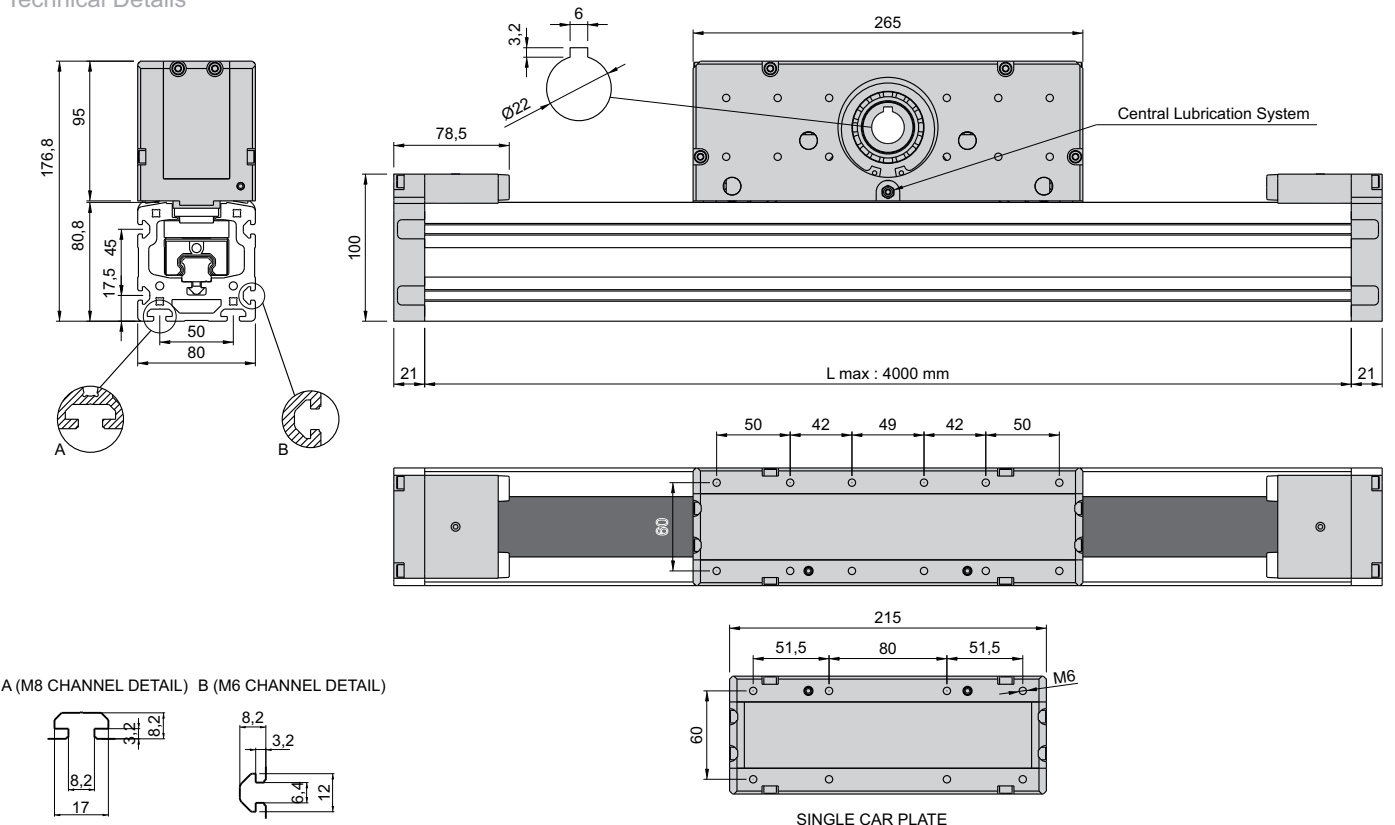
Product code : 5.3.03.080080.2.05.2.Strok

Technical Specifications

Body	:	80x80 Profile (Aluminum 6063)
Movement Speed	:	3 mt/sn
Movement Distance Per Tour	:	130mm
Timing Belt	:	5M-30 Steel Wire Polyurethane
Timing Pulley	:	Z26-5M-30F
Linear Rail	:	20 lik LineAr Rail
Linear block	:	20 lik Narrow Low Linear Car
Belt Tensile Force	:	2000 N
Timing Belt Pitch	:	5 mm
Positioning Accuracy	:	0,1 mm
Basic Weight With Zero Strok	:	9,1 kg
Weight 1000mm Stroke	:	18,5 kg
Automation Control System	:	400 / 750 / 1kw Omron Servo + PLC + Pano

Note: Depending on the operating sensitivity, Asynchronous, Step, Induction, etc. It can be driven by motors.

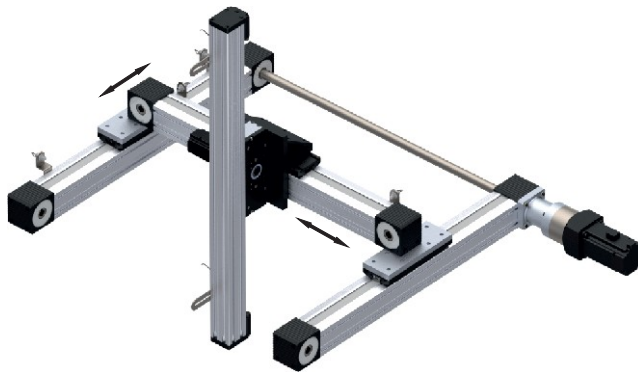
Technical Details



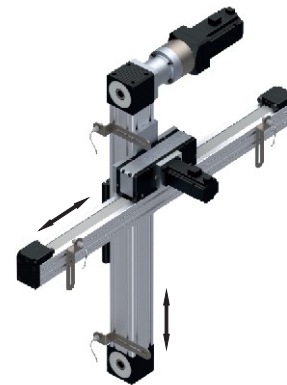
A (M8 CHANNEL DETAIL) B (M6 CHANNEL DETAIL)

SINGLE CAR PLATE

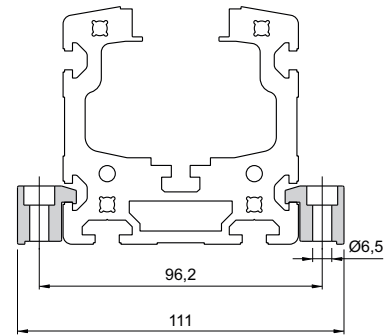
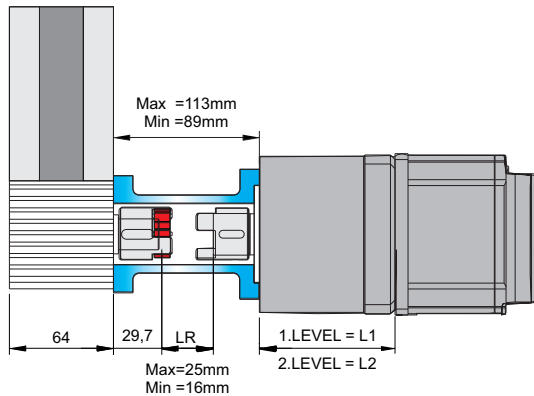
Applications



Reducer Connection Detail



Connection Dimensions

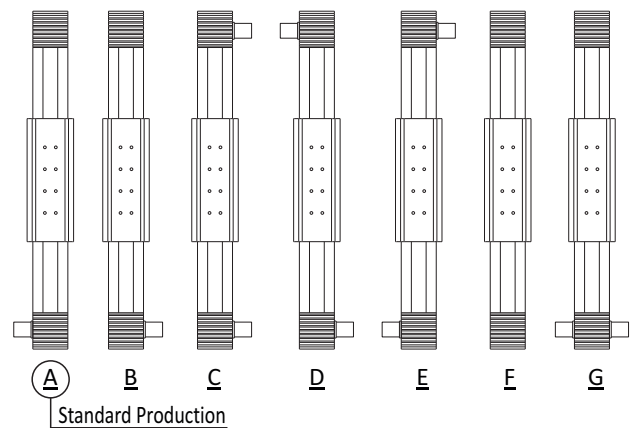


SESAME REDUCER TYPE	L1	L2
PEC 70 (400W For use)	64 mm	92 mm
PEC 90 (750W -1kW - For use)	75 mm	115 mm
PEC 120 (1W -1.5kW - For use)	88 mm	136 mm

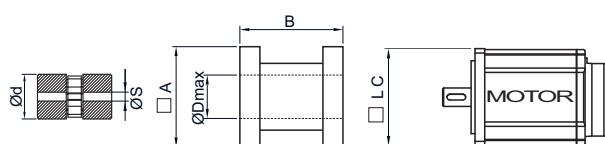
Planetary Gearbox Cycle Rates

1.LEVEL : 3-4-5-7-10
 2.LEVEL : 15-20-25-30-35-40-50-70-100
 Maximum Tork PEC 70 : 79 Nm
 Maximum Tork PEC 90 : 171 Nm
 Maximum Tork PEC 120 : 509 Nm
 Maximum Tork : 6000 rpm

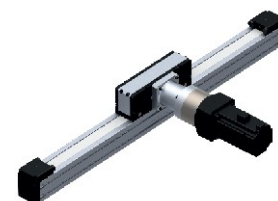
Drive Direction Options



Coupling & Flange Selection



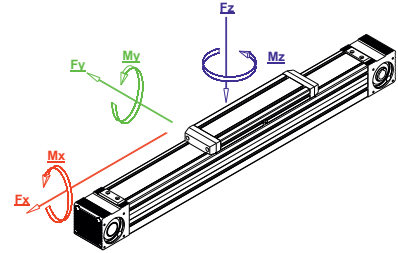
Types of Acupulation



KAPLİN	Ød	ØS	FLANŞ	A	B	ØDmax	LC
JM 40	40	8 - 22	85x 85	65 - 85	80 - 90	47	65 - 85
JM 55	55	8 - 28	95 x 95	80 - 95	94 - 104	60	70 - 95
JM 65	65	10 - 38	120 x 120	85 - 120	90 - 100	65	85 - 120



Upload Values



Load		Dynamic
■ Fx	(N)	3600
■ Fy	(N)	3180
■ Fz	(N)	10870
Moment		
■ Mx	(Nm)	697
■ My	(Nm)	780
■ Mz	(Nm)	710

Note: 2 Evaluated according to the car.

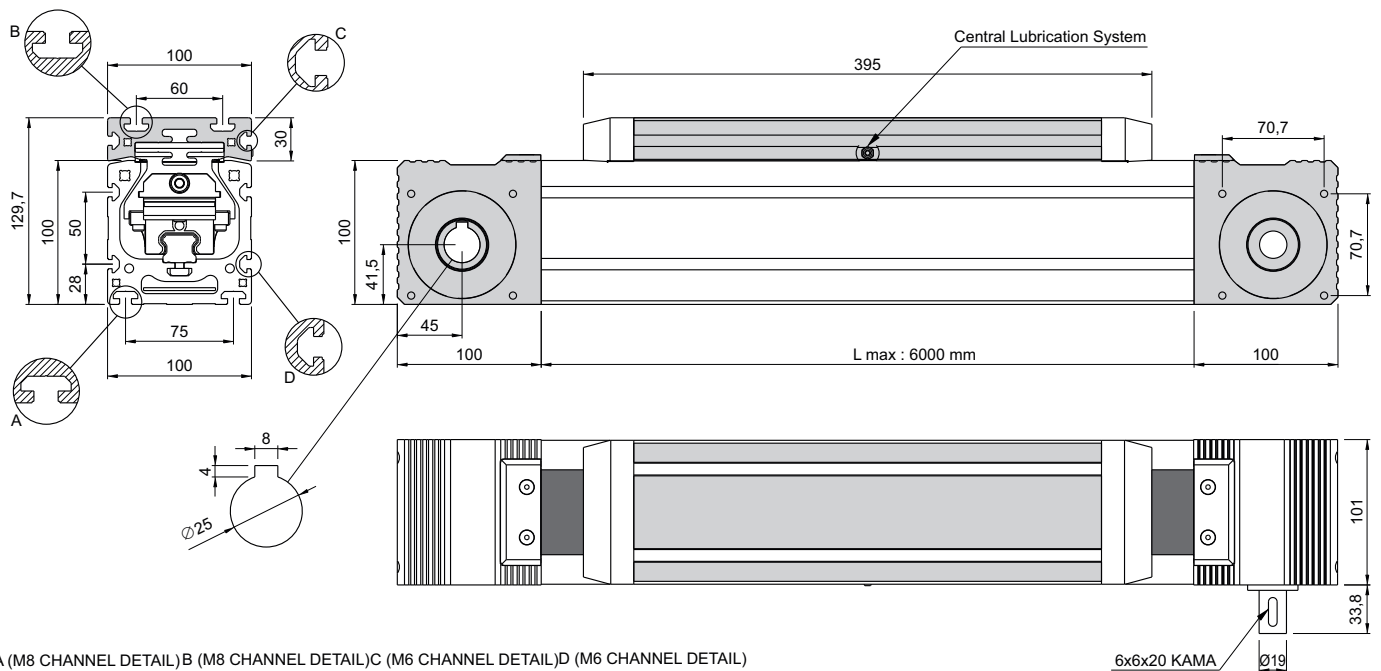
Product code : 5.3.03.100100.2.03.2.Strok

Technical Specifications

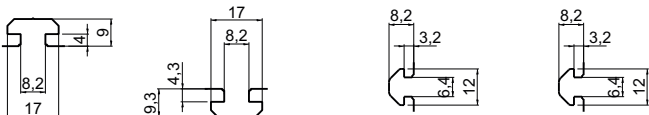
Body	:	100x100 Profile (Aluminum 6063)
Movement Speed	:	4 mt/sn
Movement Distance Per Tour	:	192mm
Timing Belt	:	8M-50 Steel Wire Polyurethane
Timing Pulley	:	8m-F50 Z=24
Linear Rail	:	25 lik Linear Rail
Linear block	:	25 lik Wide High Linear Car
Belt Tensile Force	:	3000 N
Timing Belt Pitch	:	8 mm
Protection	:	0,3x60 mm Steel Sheet
Positioning Accuracy	:	0,1 mm
Basic Weight With Zero Strok	:	13,65 kg
Weight 1000mm Stroke	:	24,70 kg
Automation Control System	:	400 / 750 / 1kw Omron Servo + PLC + Pano

Note: Depending on the operating sensitivity, Asynchronous, Step, Induction, etc. It can be driven by motors.

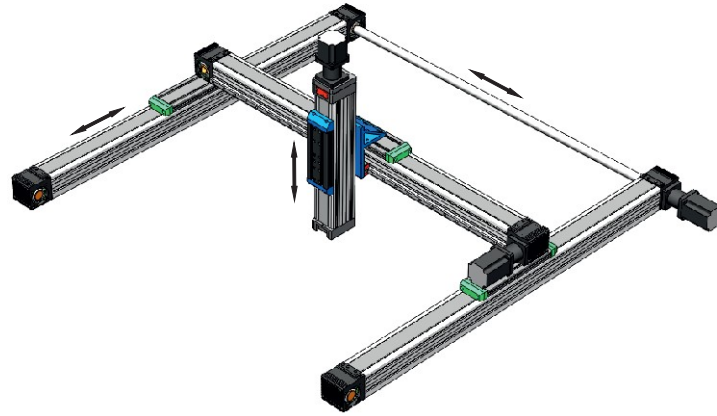
Technical Details



A (M8 CHANNEL DETAIL) B (M8 CHANNEL DETAIL) C (M6 CHANNEL DETAIL) D (M6 CHANNEL DETAIL)

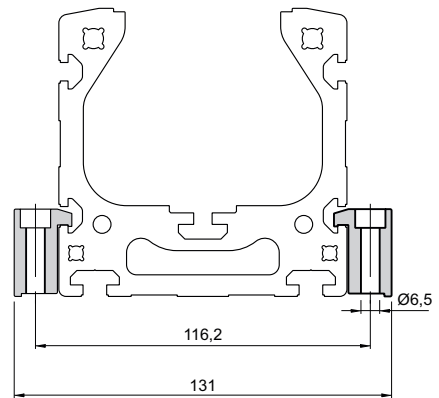
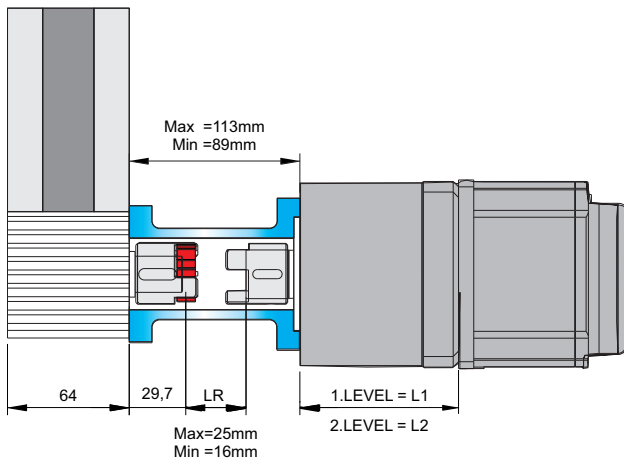


Applications



Reducer Connection Detail

Connection Dimensions

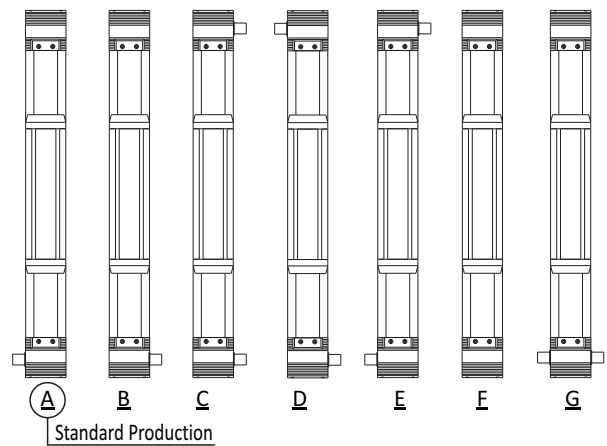


SESAME REDUCER TYPE	L1	L2
PEC 90 (750W -1kW - For use)	75 mm	115 mm
PEC 120 (1W -1.5kW - For use)	88 mm	136 mm

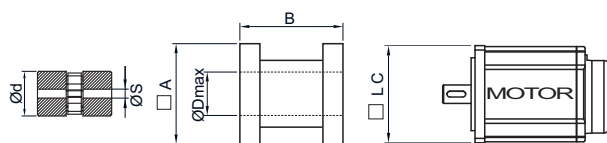
Planetary Gearbox Cycle Rates

1.LEVEL : 3-4-5-7-10
 2.LEVEL : 15-20-25-30-35-40-50-70-100
 Maximum Tork PEC 90 : 171 Nm
 Maximum Tork PEC 120 : 509 Nm
 Maximum Transfer : 6000 rpm

Drive Direction Options



Coupling & Flange Selection



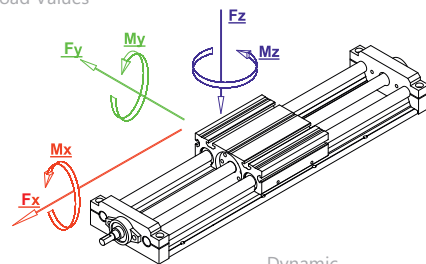
KAPLİN	Ød	ØS	FLANŞ	A	B	ØDmax	LC
JM 55	55	8 - 28	95 x 95	80 - 95	94 - 104	60	70 - 95
JM 65	65	10 - 38	120 x 120	85 - 120	90 - 100	65	85 - 120

Types of Acupulation





Upload Values



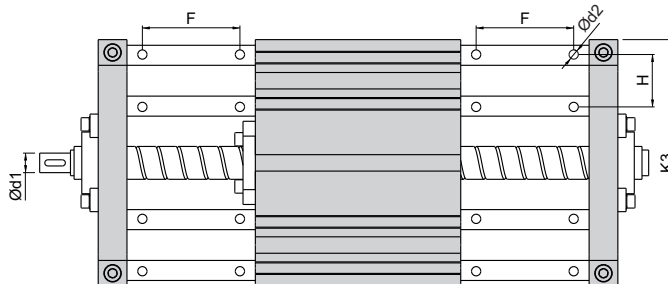
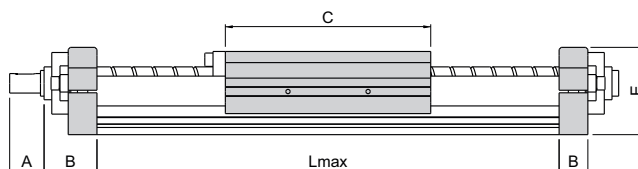
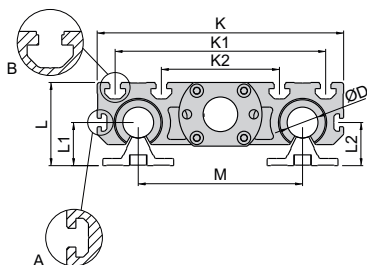
		Dynamic				
Load		Dkvm 12	Dkvm 16	Dkvm 20	Dkvm 25	Dkvm 30
■	Fx (N)	360	505	618	713	912
■	Fy (N)	850	1205	1744	2323	2950
■	Fz (N)	1215	1400	2180	2904	3450
Moment		Dkvm 12	Dkvm 16	Dkvm 20	Dkvm 25	Dkvm 30
■	Mx (Nm)	100	167	228	360	410
■	My (Nm)	80	126	195	234	290
■	Mz (Nm)	110	146	204	224	280

Technical Specifications

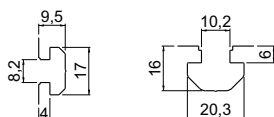
Body	; Ø12 - 16 - 20 - 25 - 30 Shaft Lower support Profile (Aluminum 6063)
Movement Speed	; 0,09 - 0,12 - 0,38 - 0,13 - 0,52 - 0,17 - 0,34 - 0,85 - 0,46 mt/sn
Movement Distance Per Tour (pitch)	; 5 mm - 10 mm - 16 mm - 20 mm - 25mm
Ball Screw	; Ø12-05 - 16-05 - 16-16 - 20-05 - 20-20 - 25-05 - 25-10 - 25-25 - 32-10 Hatve
Screw Nut	; Ø12-05 - 16-05 - 16-16 - 20-05 - 20-20 - 25-05 - 25-10 - 25-25 - 32-10 FSU TIP
Linear Bearing	; Ø12 - 16 - 20 - 25 - 30 UU OP
Induction Shaft	; Ø12 - 16 - 20 - 25 - 30 Chrome Plated Induction Shaft 60-62 HRC
Positioning Accuracy	; 0,2 mm
Basic Weight With Zero Strok	; Ø12-1,86kg Ø16-2,56kg Ø20-4,86kg Ø25-7,60kg Ø30-13,29kg
Weight 1000mm Stroke	; Ø12-5,90kg Ø16-7,93kg Ø20-14,73kg Ø25-21,81kg Ø30-34,40kg
Automation Control System	; 400 / 750 / 1kw Omron Servo + PLC + Pano

Note: Depending on the operating sensitivity, Asynchronous, Step, Induction, etc. It can be driven by motors.

Technical Details

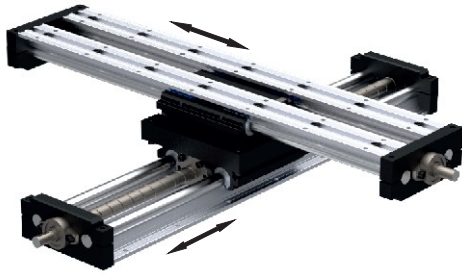


A (CHANNEL DETAIL) B (CHANNEL DETAIL)

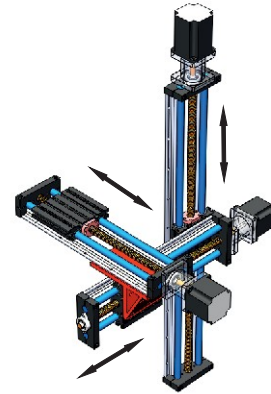


CODE	STOCK NAME	Ball Screw	ØD	Ød1	A	B	C	E	F	Ød2	H	K	K1	K2	K3	L	L1	L2	M	L max
5.2.05.110110.3.02.2.Strok	DKVM 12	12-05 & 12-10	12	10	42,5	14,5	110	44	75	4,5	29	110	-	60	115	49,5	22	38	75	1000
5.2.05.130130.3.02.2.Strok	DKVM 16	16-05	16	10	44,5	19	130	49,5	100	5,5	33	130	-	70	134	54	26	39	85	1500
5.2.05.130130.3.04.2.Strok		16-16																		
5.2.05.150150.3.05.2.Strok	DKVM 20	20-05	20	15	45	19	150	64	100	6,5	37	150	-	58	150	59	32	44	90	2000
5.2.05.150150.3.07.2.Strok		20-20																		
5.2.05.175175.3.08.2.Strok	DKVM 25	25-05	25	15	50	19,5	175	72	120	6,5	42	180	-	90	185	72	36	57	120	2500
5.2.05.175175.3.09.2.Strok		25-10																		
5.2.05.175175.3.10.2.Strok		25-25																		
5.2.05.200240.3.11.2.Strok	DKVM 30	32-05	30	19	57	28	200	85	150	9	51	240	205	115	240	81	42	42	160	3000
5.2.05.200240.3.12.2.Strok		32-10																		

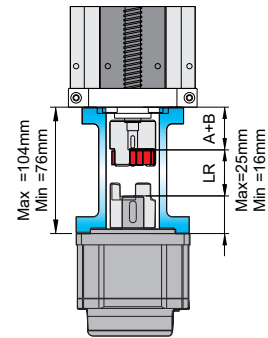
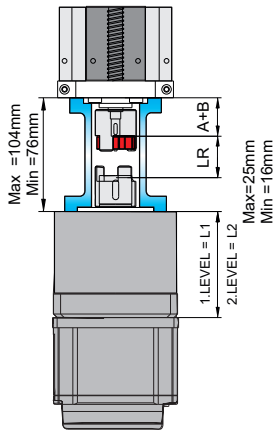
Applications



Reducer Connection Detail



Motor Connection Detail

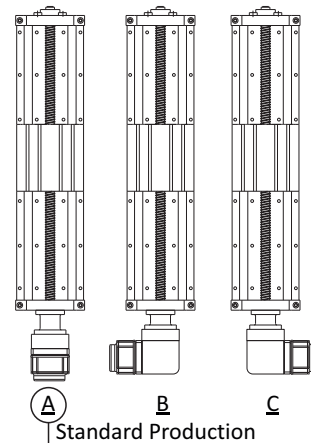


SESAME REDUCER TYPE	L1	L2
PEC 70 (400W For use)	64 mm	92 mm
PEC 90 (750W -1kW - For use)	75 mm	115 mm
PEC 120 (1W -1.5kW - For use)	88 mm	136 mm

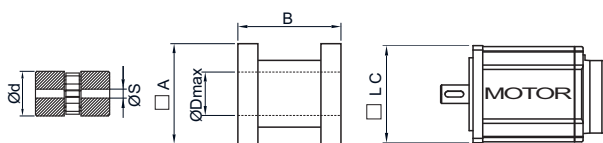
Planetary Gearbox Cycle Rates

- 1.LEVEL : 3-4-5-7-10
- 2.LEVEL : 15-20-25-30-35-40-50-70-100
- Maximum Tork PEC 70 : 79 Nm
- Maximum Tork PEC 90 : 171 Nm
- Maximum Tork PEC 120 : 509 Nm
- Maximum Tork : 6000 rpm

Drive Direction Options



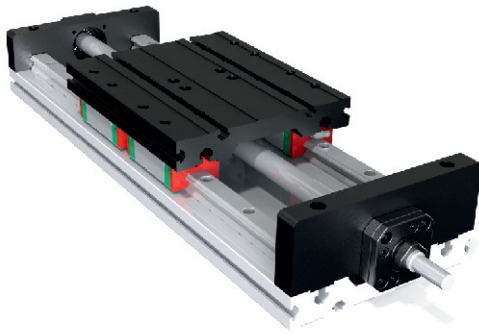
Coupling & Flange Selection



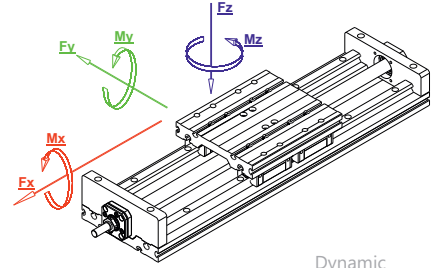
KAPLiN	Ød	ØS	FLANŞ	A	B	ØDmax	LC
JM 40	40	8 - 22	85x 85	65 - 85	80 - 90	47	65 - 85
JM 55	55	8 - 28	95 x 95	80 - 95	94 - 104	60	70 - 95
JM 65	65	10 - 38	120 x 120	85 - 120	90 - 100	65	85 - 120

Types of Acupulation





Upload Values



		Dynamic	
Load		DKZM 15	DKZM 20
■ Fx	(N)	2020	3680
■ Fy	(N)	2080	4400
■ Fz	(N)	3020	5760
Moment			
■ Mx	(Nm)	410	650
■ My	(Nm)	290	320
■ Mz	(Nm)	440	690

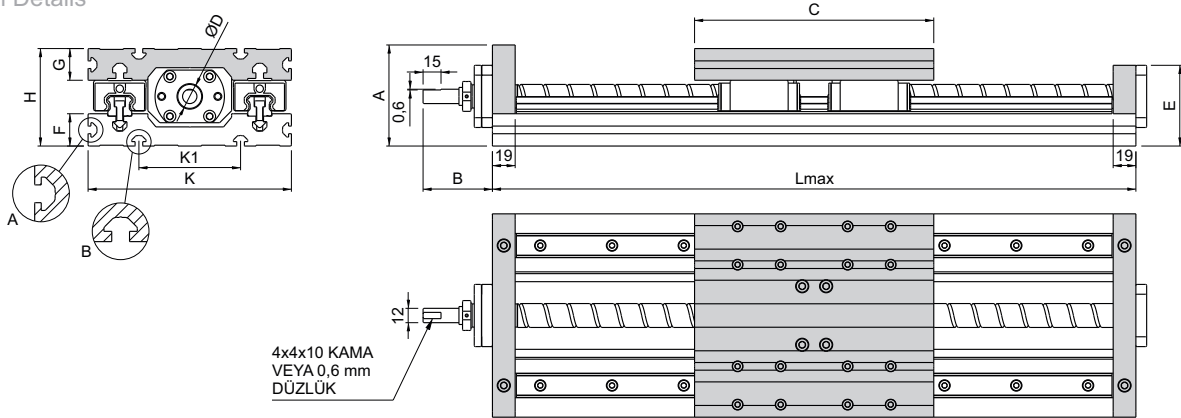
Note: 4 Evaluated according to the car.

Ball Screw Driven Systems

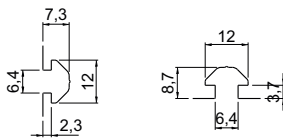
Technical Specifications

Body	:	22x140 - 27x170 Profile Aluminum(6063)
Movement Speed	:	0,12 - 0,38 - 0,13 - 0,52 mt/sn
Movement Distance Per Tour (pitch)	:	5 mm - 16mm - 20 mm
Ball Screw	:	Ø16-05 - 16-16 - 20-05 - 20-20 Hatve
Screw Nut	:	Ø16-05 - 16-16 - 20-05 - 20-20 FSU TİP
Linear Bearing	:	15 -20 Linear Ray
Induction Shaft	:	15 - 20 Yüksek Lineer Araba
Positioning Accuracy	:	0,01 mm
Basic Weight With Zero Strok	:	15-3,11kg 20-5,54kg
Weight 1000mm Stroke	:	15-12,60kg 20-22,39kg
Automation Control System	:	400 / 750 / 1kw Omron Servo + PLC + Pano

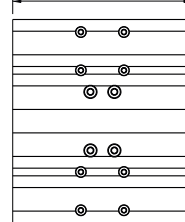
Technical Details



A (CHANNEL DETAIL) B (CHANNEL DETAIL)



DKZM15 : 120 / DKZM20 : 150

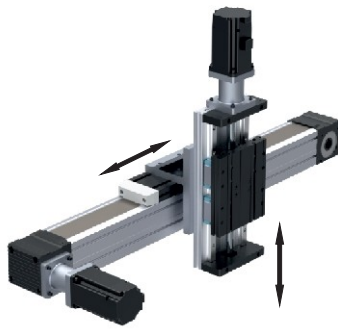


DKZM15 : 120 / DKZM20 : 150

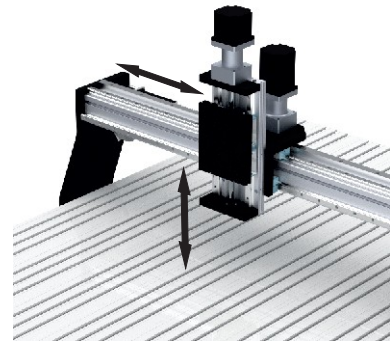


CODE	STOCK NAME	Ball Screw	A	B	C	ØD	Ød1	E	F	G	H	K	K1	L max
5.2.07.022140.2.02.1.Strok	DKZM 15	16 - 05	77,5	49	150	16	12	57,5	22	21,5	70	140	70	2000
5.2.07.027170.2.05.1.Strok	DKZM 20	20 - 05	84,5	58	200	20	12	67,5	27	26,5	81,5	170	85	2500
5.2.07.022140.2.04.1.Strok	DKZM 15	16 - 16	77,5	49	150	16	12	57,5	22	21,5	70	140	70	2000
5.2.07.027170.2.07.1.Strok	DKZM 20	20 - 20	84,5	58	200	20	12	67,5	27	26,5	81,5	170	85	2500

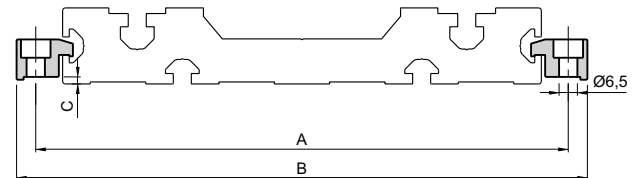
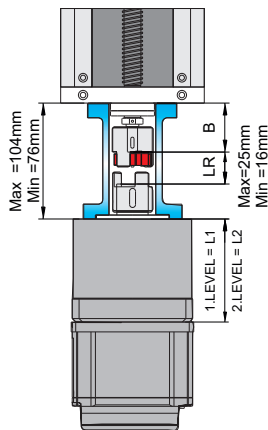
Applications



Reducer Connection Detail



Connection Dimensions



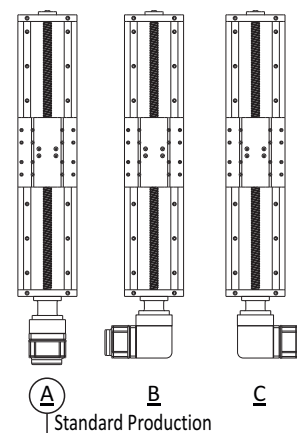
	A	B	C
DKZM15	160	1173	73,8
DKZM20	189	1202	72,5

SESAME REDUCER TYPE	L1	L2
PEC 70 (400W For use)	64 mm	92 mm
PEC 90 (750W -1kW - For use)	75 mm	115 mm
PEC 120 (1W -1.5kW - For use)	88 mm	136 mm

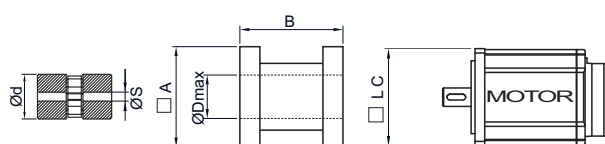
Planetary Gearbox Cycle Rates

- 1.LEVEL : 3-4-5-7-10
- 2.LEVEL : 15-20-25-30-35-40-50-70-100
- Maximum Tork PEC 70 : 79 Nm
- Maximum Tork PEC 90 : 171 Nm
- Maximum Tork PEC 120 : 509 Nm
- Maximum Tork : 6000 rpm

Drive Direction Options



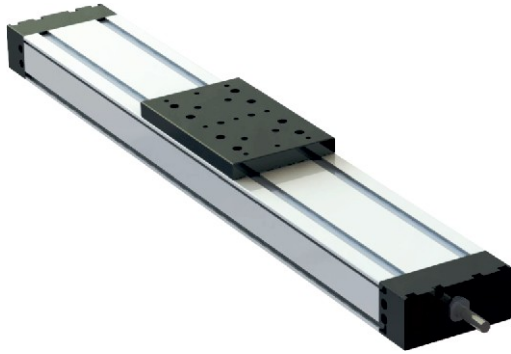
Coupling & Flange Selection



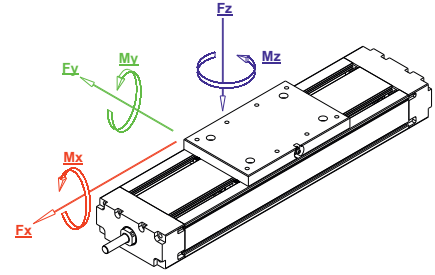
KAPLiN	Ød	ØS	FLANŞ	A	B	ØDmax	LC
JM 40	40	8 - 22	85x 85	65 - 85	80 - 90	47	65 - 85
JM 55	55	8 - 28	95 x 95	80 - 95	94 - 104	60	70 - 95
JM 65	65	10 - 38	120 x 120	85 - 120	90 - 100	65	85 - 120

Types of Acupulation





Upload Values



Load		Dynamic
■ Fx	(N)	8600
■ Fy	(N)	5400
■ Fz	(N)	9200
Moment		
■ Mx	(Nm)	510
■ My	(Nm)	1120
■ Mz	(Nm)	2350

Note: 4 Evaluated according to the car.

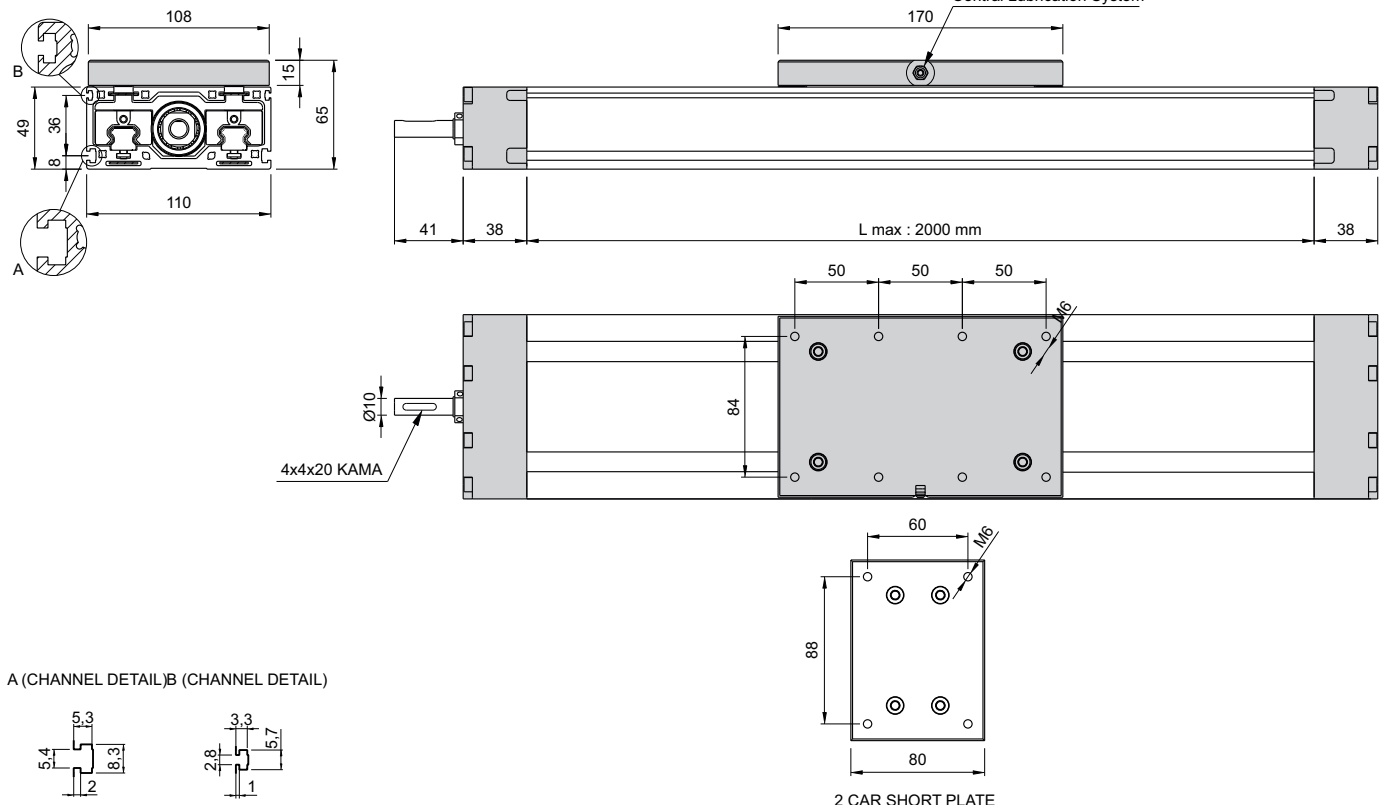
Product code : 5.2.03.050110.2.02.2.Strok

Technical Specifications

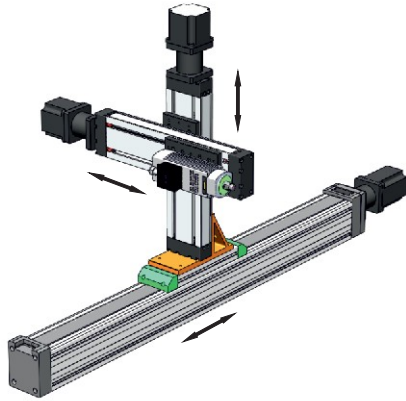
Body	:	50x110 Profile (Aluminum 6063)
Movement Speed	:	0,12 mt/sn
Movement Distance Per Tour (pitch)	:	5 mm
Ball Screw	:	Ø16-05
Screw Nut	:	SCI 16-05
Linear Rail	:	15 lik Linear Rail
Linear Block	:	15 lik Narrow Low Linear Car
Positioning Accuracy	:	0,01mm
Basic Weight With Zero Strok	:	2,51 kg
Weight 1000mm Stroke	:	11 kg
Automation Control System	:	400 / 750 / 1kw Omron Servo + PLC + Pano

Note: Depending on the operating sensitivity, Asynchronous, Step, Induction, etc. It can be driven by motors.

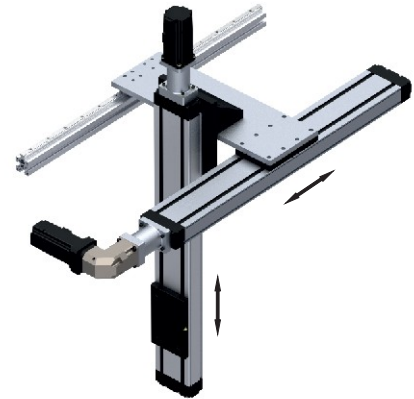
Technical Details



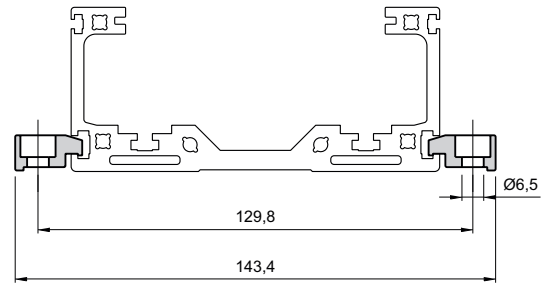
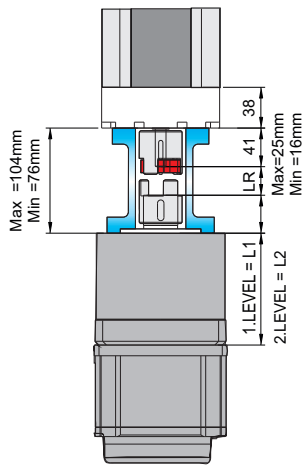
Applications



Reducer Connection Detail



Connection Dimensions

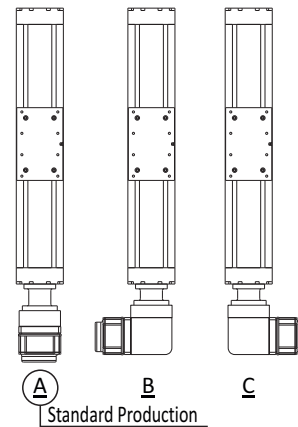


SESAME REDUCER TYPE	L1	L2
PEC 70 (400W For use)	64 mm	92 mm
PEC 90 (750W -1kW - For use)	75 mm	115 mm

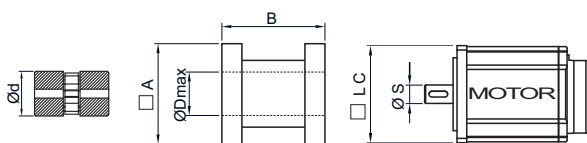
Planetary Gearbox Cycle Rates

1.LEVEL : 3-4-5-7-10
 2.LEVEL : 15-20-25-30-35-40-50-70-100
 Maximum Tork PEC 70 : 79 Nm
 Maximum Tork PEC 90 : 171 Nm
 Maximum Tork : 6000 rpm

Drive Direction Options



Coupling & Flange Selection



Types of Acupulation

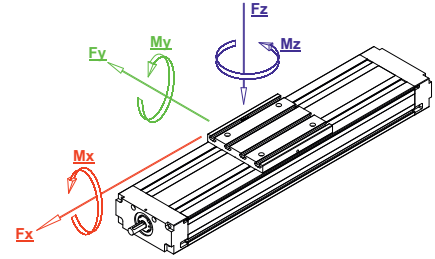


KAPLIN	Ød	ØS	FLANŞ	A	B	ØDmax	LC
JM 40	40	8 - 22	85x 85	65 - 85	80 - 90	47	65 - 85
JM 55	55	8 - 28	95 x 95	80 - 95	94 - 104	60	70 - 95



Product code : 5.2.03.065145.2.08.2.Strok

Upload Values



Load		Dynamic
■ Fx	(N)	9800
■ Fy	(N)	6200
■ Fz	(N)	13500
Moment		
■ Mx	(Nm)	620
■ My	(Nm)	1340
■ Mz	(Nm)	1340

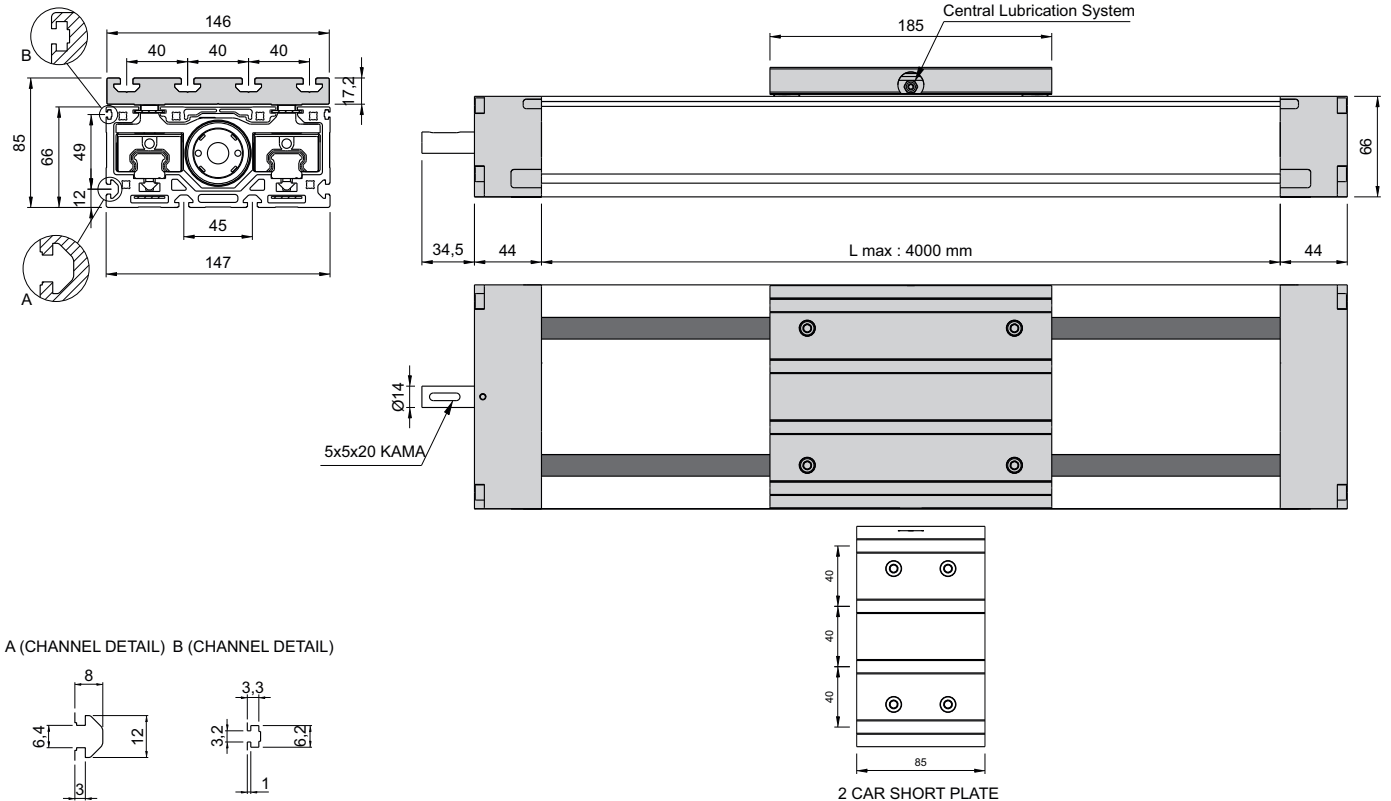
Note: 4 Evaluated according to the car.

Technical Specifications

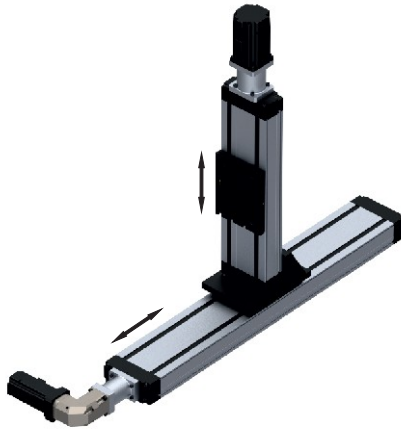
Body	:	66x145 Profile (Aluminum 6063)
Movement Speed	:	0,13 - 0,17 - 0,52 mt/sn
Movement Distance Per Tour (pitch)	:	5mm - 20 mm
Ball Screw	:	Ø20-05 / Ø25-05 / Ø20-20
Screw Nut	:	SCI 25-05 / FSU 20-20
Linear Rail	:	20 lik Lineer Ray
Linear Block	:	20 lik Dar Yüksek Lineer Araba
Positioning Accuracy	:	0,01 mm
Basic Weight With Zero Strok	:	4,42 kg
Weight 1000mm Stroke	:	17,24 kg
Automation Control System	:	400 / 750 / 1kw Omron Servo + PLC + Pano

Not: Çalışma hassasiyetine göre Asenkron, Step, İndüksiyon vb. motorlarla tahrik edilebilmektedir.

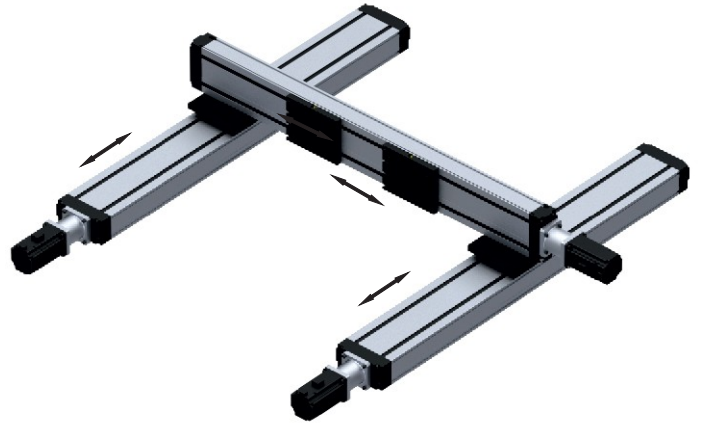
Technical Details



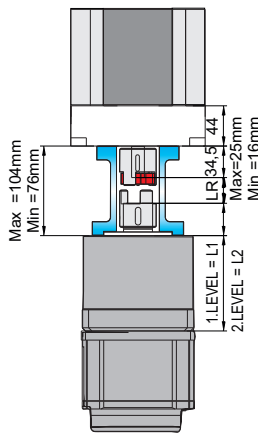
Applications



Reducer Connection Detail



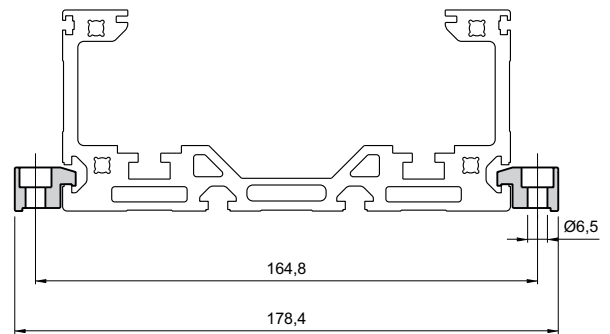
Connection Dimensions



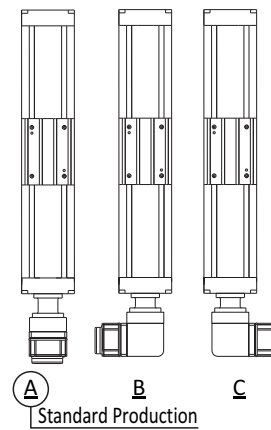
SESAME REDUCER TYPE	L1	L2
PEC 70 (400W For use)	64 mm	92 mm
PEC 90 (750W -1kW - For use)	75 mm	115 mm

Planetary Gearbox Cycle Rates

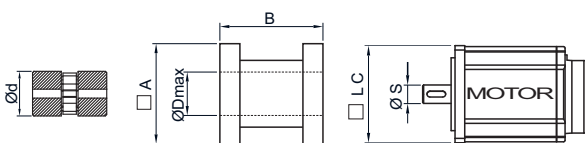
1.LEVEL : 3-4-5-7-10
 2.LEVEL : 15-20-25-30-35-40-50-70-100
 Maximum Tork PEC 70 : 79 Nm
 Maximum Tork PEC 90 : 171 Nm
 Maximum Tork : 6000 rpm



Drive Direction Options



Coupling & Flange Selection



KAPLIN	Ød	ØS	FLANŞ	A	B	ØDmax	LC
JM 40	40	8 - 22	85x 85	65 - 85	80 - 90	47	65 - 85
JM 55	55	8 - 28	95 x 95	80 - 95	94 - 104	60	70 - 95

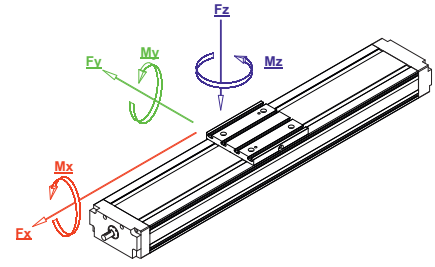
Types of Acupulation





Product code : 5.2.03.080160.2.09.2.Strok

Upload Values



Load		Dynamic
■ Fx	(N)	12300
■ Fy	(N)	9600
■ Fz	(N)	18700
Moment		
■ Mx	(Nm)	840
■ My	(Nm)	1870
■ Mz	(Nm)	3200

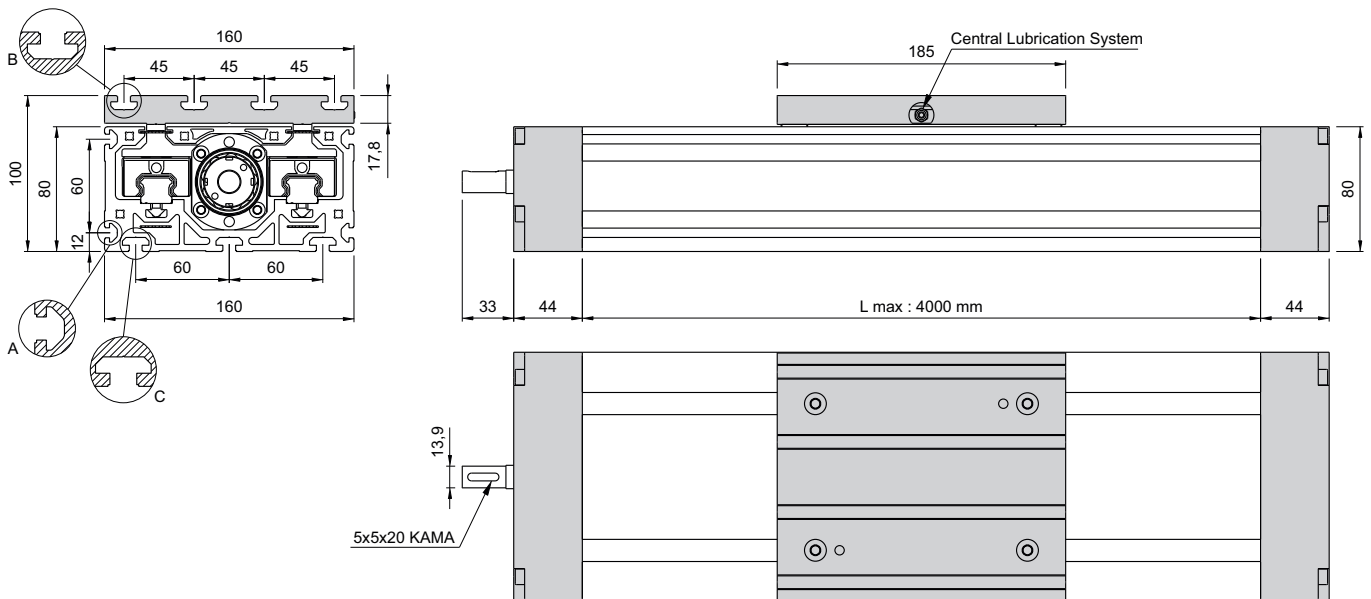
Note: 4 Evaluated according to the car.

Technical Specifications

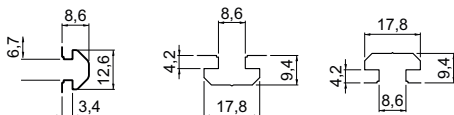
Body	:	80x160 Profile (Aluminum 6063)
Movement Speed	:	0,17 - 0,34 - 0,52 - 0,85 mt/sn
Movement Distance Per Tour (pitch)	:	5mm - 10mm - 25mm
Rack and Pinion	:	Ø25-05 / Ø25-10 / Ø20-20 / Ø25-25
Pinion Gear	:	FSU 25-05 / FSU 20-20 / FSU 25-25
Linear Rail	:	20 lik Lineer Ray
Linear Block	:	20 lik Dar Yüksek Lineer Araba
Positioning Accuracy	:	0,01 mm
Basic Weight With Zero Strok	:	10,93 kg
Weight 1000mm Stroke	:	29,48 kg
Automation Control System	:	400 / 750 / 1kw Omron Servo + PLC + Pano

Not: Çalışma hassasiyetine göre Asenkron, Step, İndüksiyon vb. motorlarla tahrik edilebilmektedir.

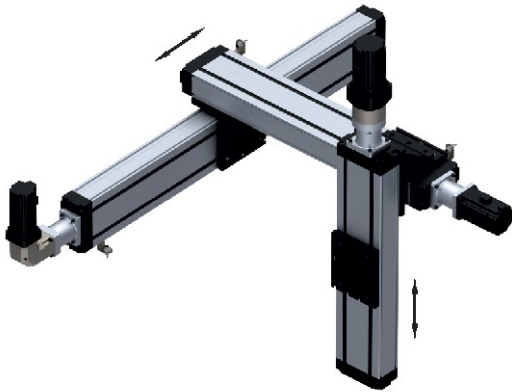
Technical Details



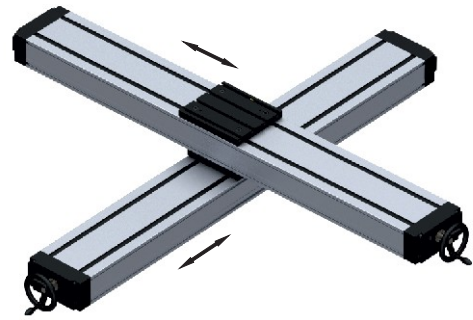
A (CHANNEL DETAIL) B (CHANNEL DETAIL) C (CHANNEL DETAIL)



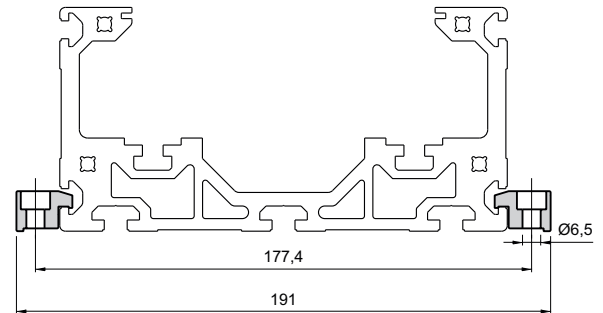
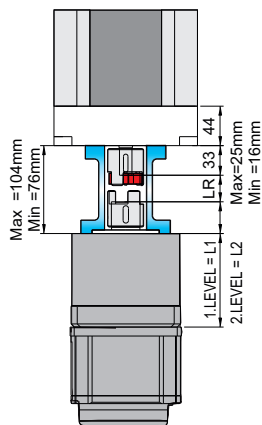
Applications



Reducer Connection Detail



Connection Dimensions

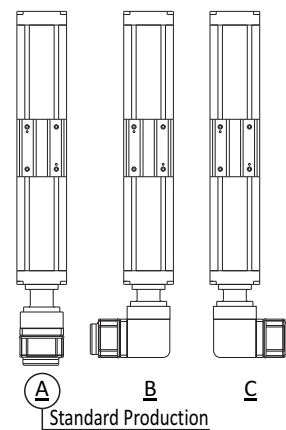


SESAME REDUCER TYPE	L1	L2
PEC 90 (750W -1kW - For use)	75 mm	115 mm
PEC 120 (1W -1.5kW - For use)	88 mm	136 mm

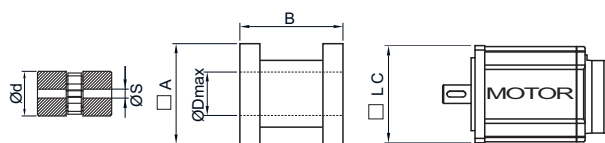
Planetary Gearbox Cycle Rates

- 1.LEVEL : 3-4-5-7-10
- 2.LEVEL : 15-20-25-30-35-40-50-70-100
- Maximum Tork PEC 90 : 171 Nm
- Maximum Tork PEC 120 : 509 Nm
- Maximum Tork : 6000 rpm

Drive Direction Options



Coupling & Flange Selection



KAPLiN	Ød	ØS	FLANŞ	A	B	ØDmax	LC
JM 40	40	8 - 22	85x 85	65 - 85	80 - 90	47	65 - 85
JM 55	55	8 - 28	95 x 95	80 - 95	94 - 104	60	70 - 95
JM 65	65	10 - 38	120 x 120	85 - 120	90 - 100	65	85 - 120

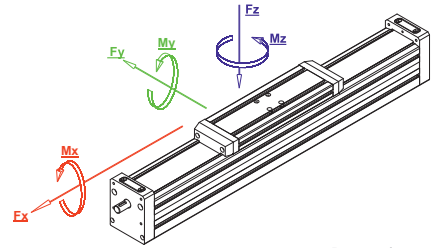
Types of Acupulation





Product code : 5.2.03.100100.2.08.2.Strok

Upload Values



Load		Ø25	Ø20
■ Fx	(N)	5500	4200
■ Fy	(N)	4700	3600
■ Fz	(N)	10870	8600
Moment			
■ Mx	(Nm)	5740	3360
■ My	(Nm)	6400	4200
■ Mz	(Nm)	8220	7600

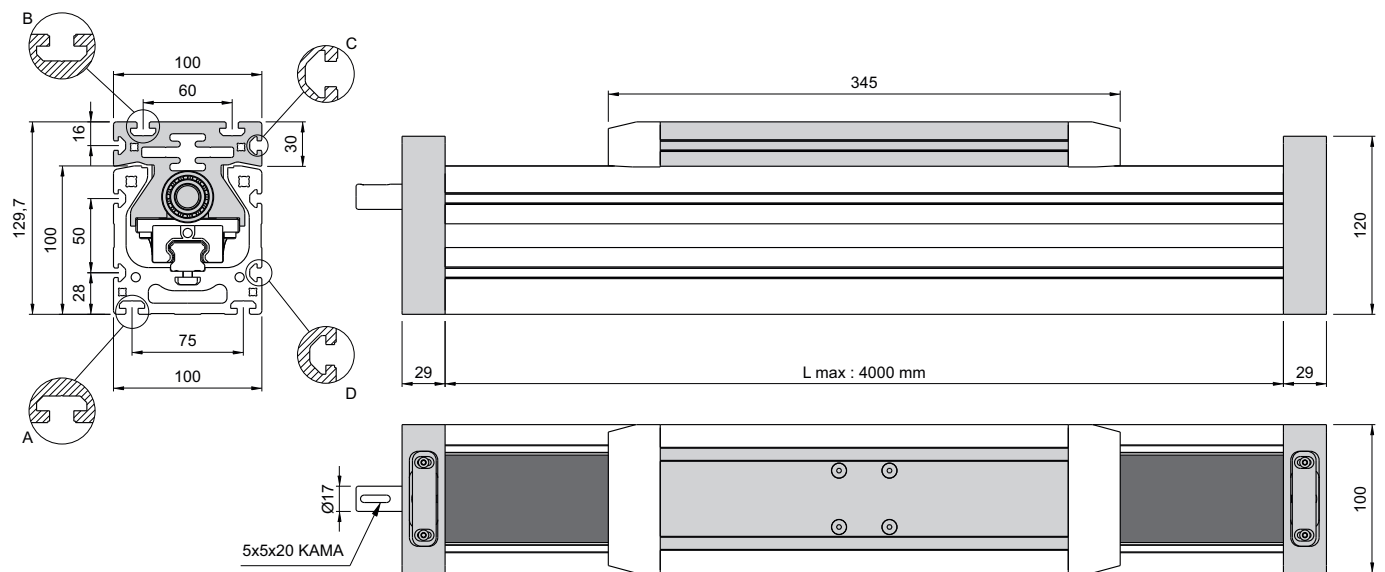
Note: 4 Evaluated according to the car.

Technical Specifications

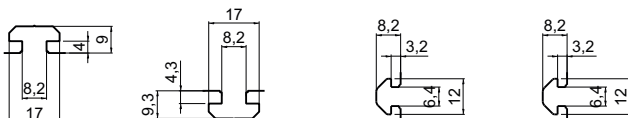
Body	:	100x100 Profile (Aluminum 6063)
Movement Speed	:	0,17 - 0,34 - 0,52 mt/sn
Movement Distance Per Tour (pitch)	:	5mm - 10mm - 20mm
Ball Screw	:	Ø25-05 / Ø25-10 / Ø20-20
Screw Nut	:	SCI 25-05 / FSU 20-20
Linear Rail	:	25 lik Linear Rail
Linear Block	:	25 lik Wide Linear Araba
Positioning Accuracy	:	0,01 mm
Basic Weight With Zero Strok	:	8,01 kg
Weight 1000mm Stroke	:	18,52 kg
Automation Control System	:	400 / 750 / 1kw Omron Servo + PLC + Pano

Note: Depending on the operating sensitivity, Asynchronous, Step, Induction, etc. It can be driven by motors.

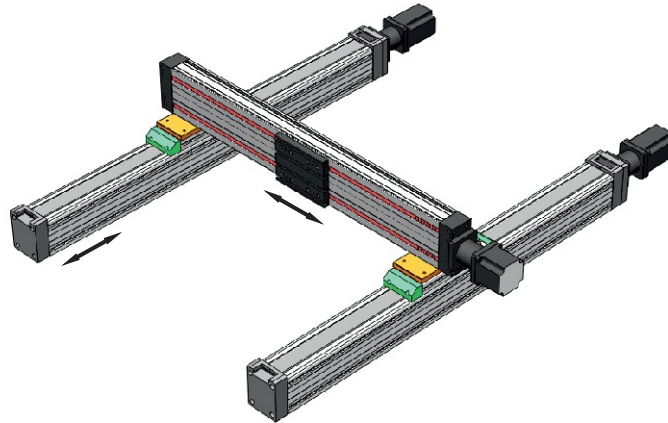
Technical Details



A (M8 CHANNEL DETAIL) B (M8 CHANNEL DETAIL) C (M6 CHANNEL DETAIL) D (M6 CHANNEL DETAIL)

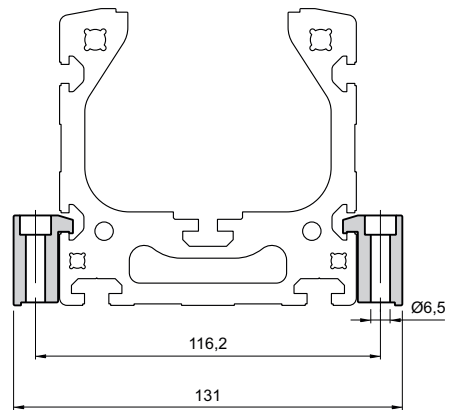
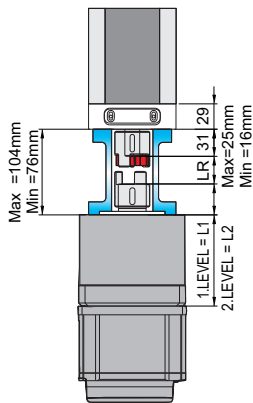


Applications



Reducer Connection Detail

Connection Dimensions

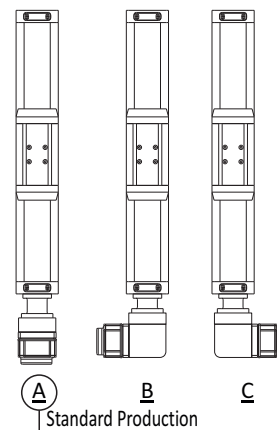


SESAME REDUCER TYPE	L1	L2
PEC 90 (750W -1kW - For use)	75 mm	115 mm
PEC 120 (1W -1.5kW - For use)	88 mm	136 mm

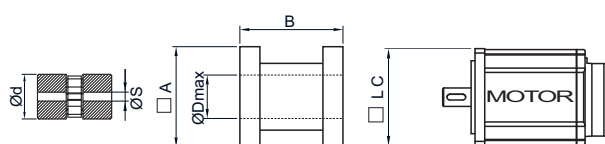
Planetary Gearbox Cycle Rates

1.LEVEL : 3-4-5-7-10
 2.LEVEL : 15-20-25-30-35-40-50-70-100
 Maximum Tork PEC 90 : 171 Nm
 Maximum Tork PEC 120 : 509 Nm
 Maximum Tork : 6000 rpm

Drive Direction Options

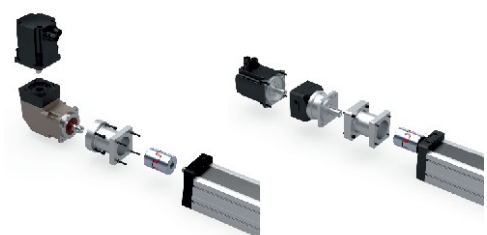


Coupling & Flange Selection



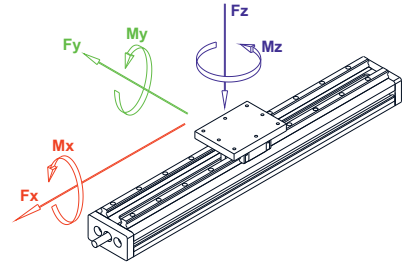
KAPLiN	Ød	ØS	FLANŞ	A	B	ØDmax	LC
JM 40	40	8 - 22	85x 85	65 - 85	80 - 90	47	65 - 85
JM 55	55	8 - 28	95 x 95	80 - 95	94 - 104	60	70 - 95
JM 65	65	10 - 38	120 x 120	85 - 120	90 - 100	65	85 - 120

Types of Acupulation





Upload Values



Load		Dynamic
■ Fx	(N)	725
■ Fy	(N)	878
■ Fz	(N)	1157
Moment		
■ Mx	(Nm)	110
■ My	(Nm)	70
■ Mz	(Nm)	75

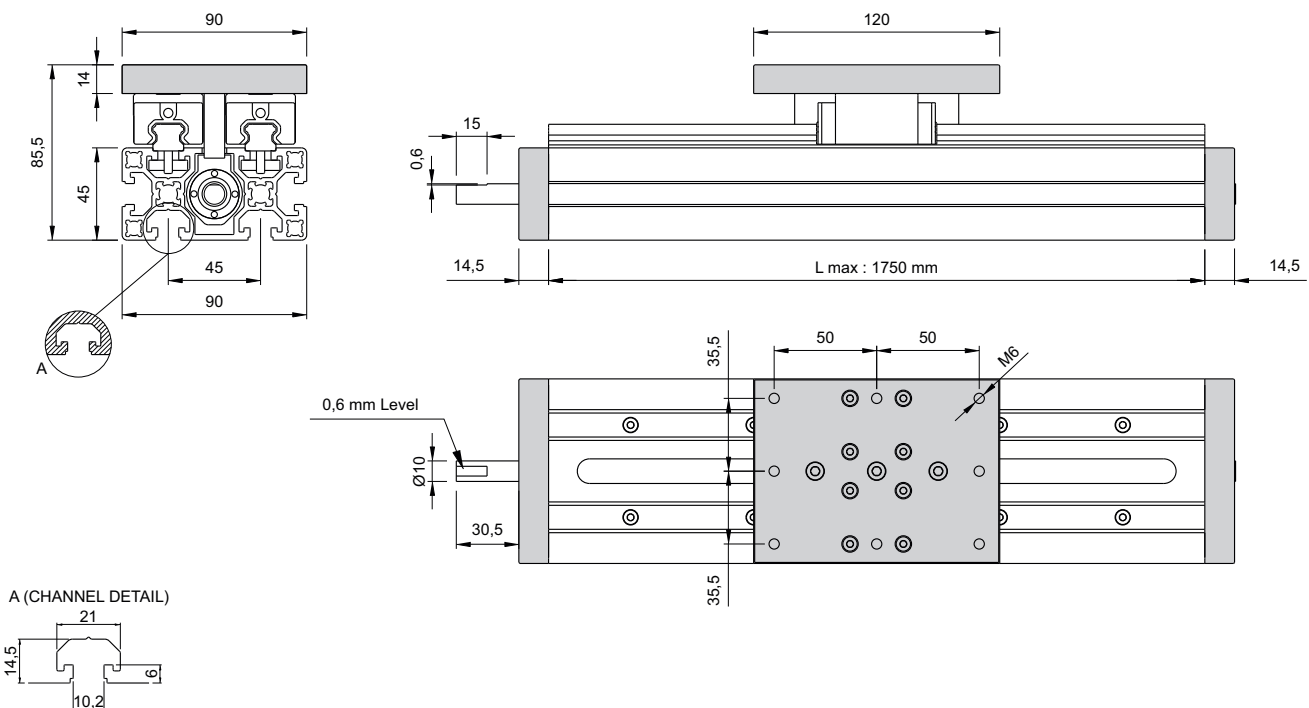
Product code : 5.2.04.045090.2.01.1.Strok

Technical Specifications

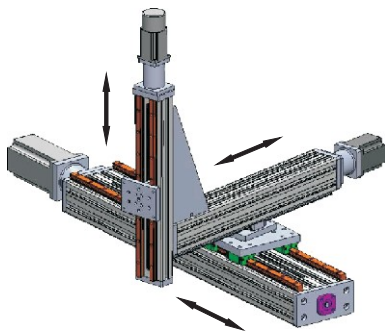
Body	:	45X90 (A) Profile (Aluminum 6063)
Movement Speed	:	0,1 mt/sn
Movement Distance Per Tour (pitch)	:	5 mm
Ball Screw	:	Ø12-05 (Hatve)
Screw Nut	:	RSY-12-05
Linear Rail	:	15 lik Linear Ray
Linear Block	:	15 lik Dar Lineer Araba
Positioning Accuracy	:	0,01 mm
Basic Weight With Zero Strok	:	1,96 kg
Weight 1000mm Stroke	:	9,27 kg
Automation Control System	:	400 / 750 / 1kw Omron Servo + PLC + Pano

Note: Depending on the operating sensitivity, Asynchronous, Step, Induction, etc. It can be driven by motors.

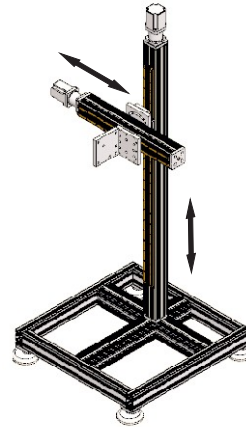
Technical Details



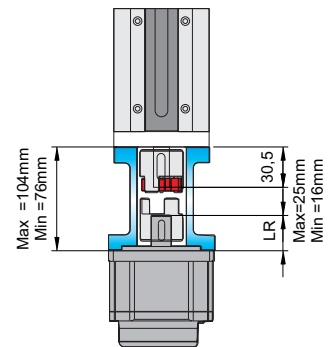
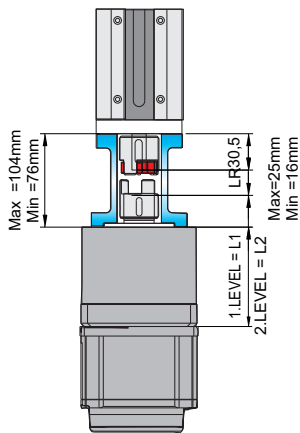
Applications



Reducer Connection Detail



Motor Connection Detail

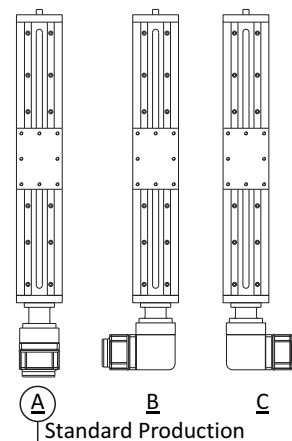


SESAME REDUCER TYPE	L1	L2
PEC 70 (400W For use)	64 mm	92 mm
PEC 90 (750W -1kW - For use)	75 mm	115 mm

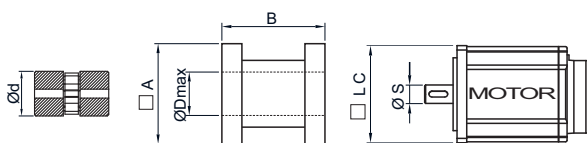
Planetary Gearbox Cycle Rates

1.LEVEL : 3-4-5-7-10
 2.LEVEL : 15-20-25-30-35-40-50-70-100
 Maximum Tork PEC 70 : 79 Nm
 Maximum Tork PEC 90 : 171 Nm
 Maximum Tork : 6000 rpm

Drive Direction Options

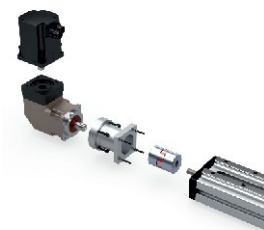


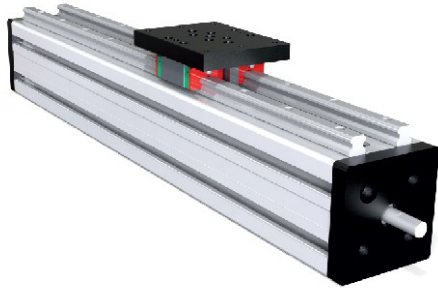
Coupling & Flange Selection



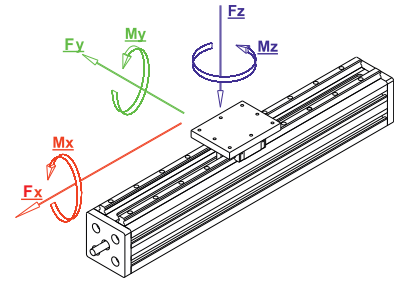
KAPLIN	Ød	ØS	FLANŞ	A	B	ØDmax	LC
JM 40	40	8 - 22	95 x 95	80 - 95	94 - 104	60	70 - 95
JM 55	55	8 - 28	85x 85	65 - 85	80 - 90	47	65 - 85

Types of Acupulation





Upload Values



Load		Dynamic
■ Fx	(N)	975
■ Fy	(N)	878
■ Fz	(N)	1157
Moment		
■ Mx	(Nm)	140
■ My	(Nm)	80
■ Mz	(Nm)	95

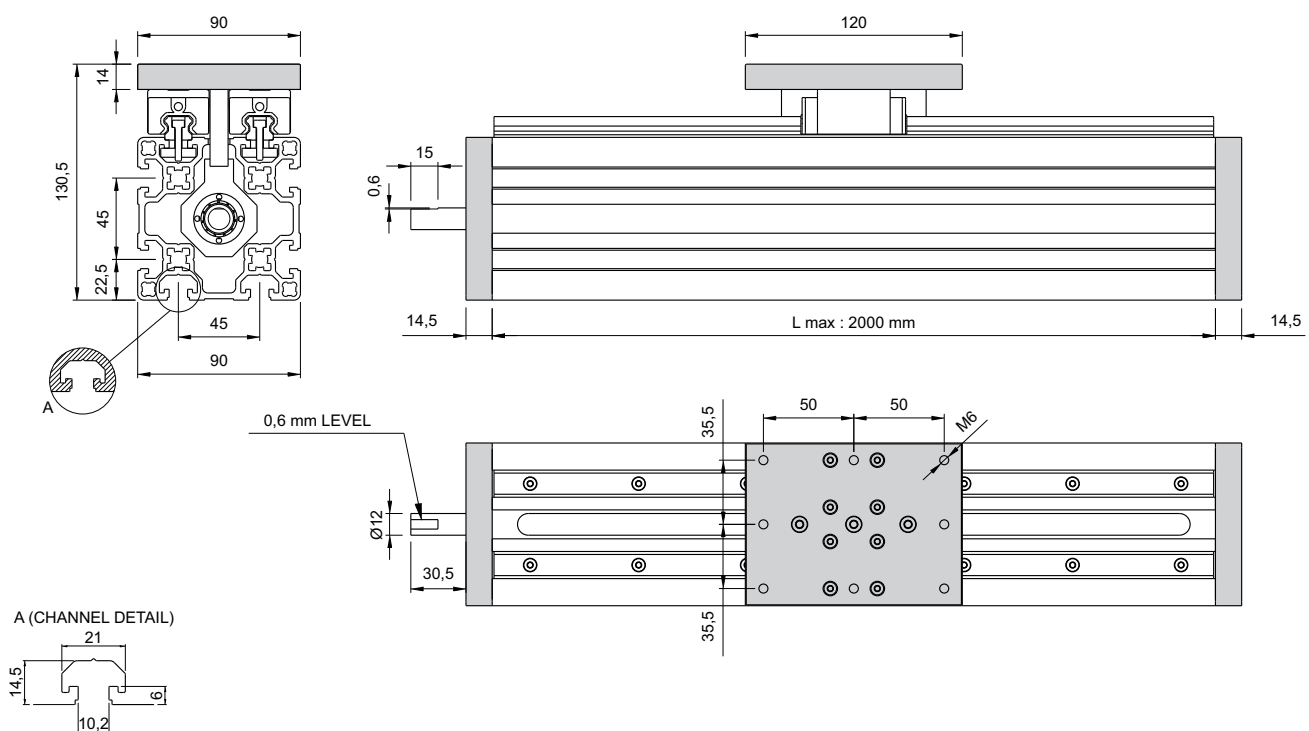
Product code : 5.2.04.090090.2.02.1.Strok

Technical Specifications

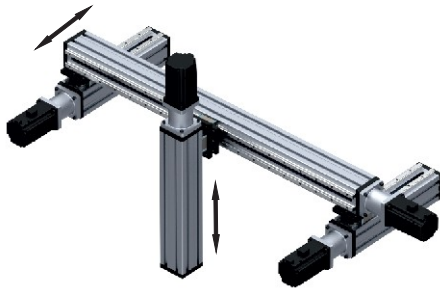
Body	:	90x90 (L) Profile (Aluminum 6063)
Movement Speed	:	0,12 mt/sn
Movement Distance Per Tour (pitch)	:	4mm / 5 mm
Ball Screw	:	Ø16-04 / Ø16-05 (Hatve)
Screw Nut	:	TRP16-04 / FSU 16-05
Linear Rail	:	15 lik Linear Rail
Linear Block	:	15 lik Narrow Low Linear Car
Positioning Accuracy	:	2,64 kg
Basic Weight With Zero Strok	:	11,87 kg
Weight 1000mm Stroke	:	400 / 750 / 1kw Omron Servo + PLC + Pano
Automation Control System	:	

Note: Depending on the operating sensitivity, Asynchronous, Step, Induction, etc. It can be driven by motors.

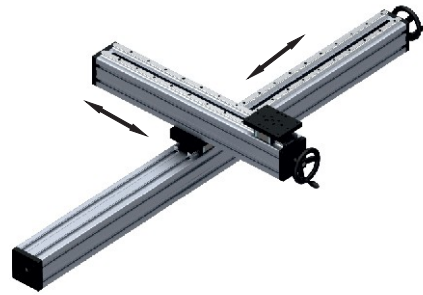
Technical Details



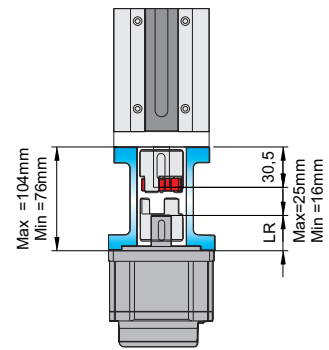
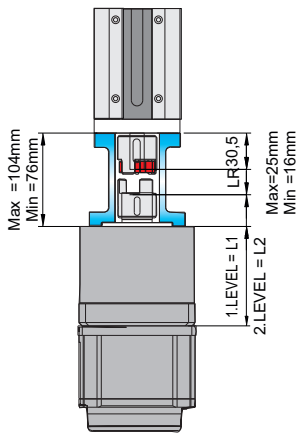
Applications



Reducer Connection Detail



Motor Connection Detail

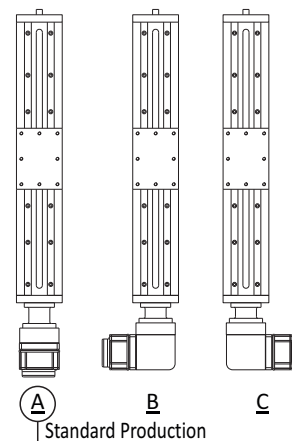


SESAME REDUCER TYPE	L1	L2
PEC 70 (400W For use)	64 mm	92 mm
PEC 90 (750W -1kW - For use)	75 mm	115 mm

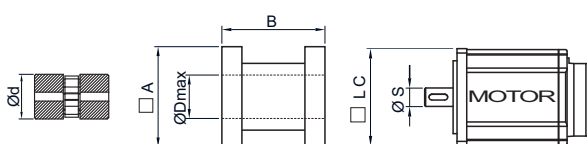
Planetary Gearbox Cycle Rates

1.LEVEL : 3-4-5-7-10
 2.LEVEL : 15-20-25-30-35-40-50-70-100
 Maximum Tork PEC 70 : 79 Nm
 Maximum Tork PEC 90 : 171 Nm
 Maximum Tork : 6000 rpm

Drive Direction Options



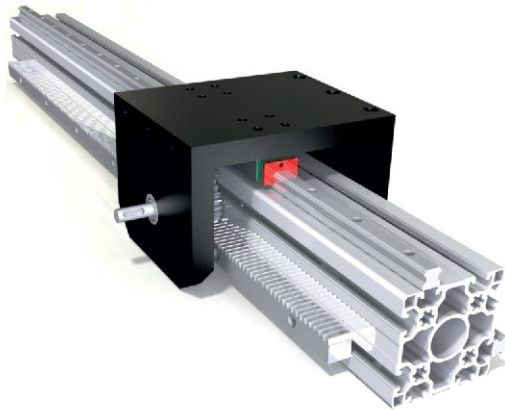
Coupling & Flange Selection



KAPLIN	Ød	ØS	FLANŞ	A	B	ØDmax	LC
JM 40	40	8 - 22	85x 85	65 - 85	80 - 90	47	65 - 85
JM 55	55	8 - 28	95 x 95	80 - 95	94 - 104	60	70 - 95

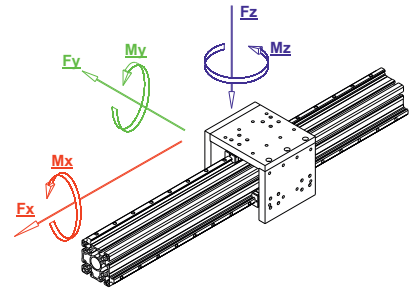
Types of Acupulation





Product code : 5.4.08.090090.2.03.2.Strok

Upload Values



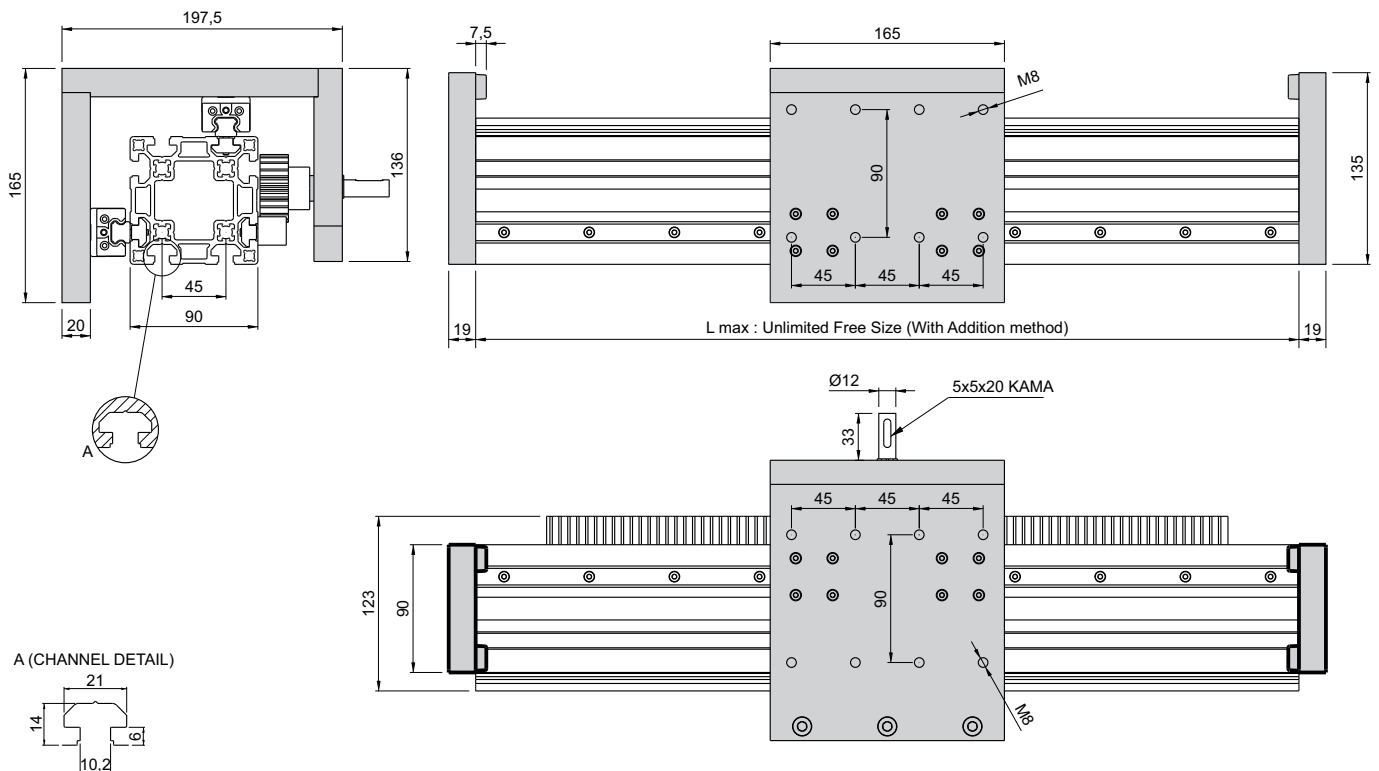
Load		Dynamic
■ Fx	(N)	1480
■ Fy	(N)	2125
■ Fz	(N)	2125
Moment		
■ Mx	(Nm)	230
■ My	(Nm)	1613
■ Mz	(Nm)	1613

Technical Specifications

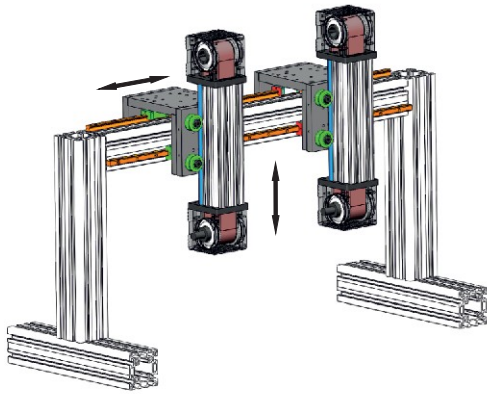
Body	:	90x90 Profile (Aluminum 6063)
Movement Speed	:	3 mt/sn
Movement Distance Per Tour (pitch)	:	138,16 mm
Rack and Pinion	:	Mod:2 Düz / Mod:2 Helisel
Pinion Gear	:	Mod:2 Z:22 Düz / Mod:2 Z:22 Helisel
Linear Rail	:	15 lik Linear ray
Linear Block	:	15 - Narrow Linear Block
Positioning Accuracy	:	0,2 mm
Basic Weight With Zero Strok	:	7,75 kg
Weight 1000mm Stroke	:	20,77 kg
Automation Control System	:	400 / 750 / 1kw Omron Servo + PLC + Pano

Not: Çalışma hassasiyetine göre Asenkron, Step, İndüksiyon vb. motorlarla tahrik edilebilmektedir.

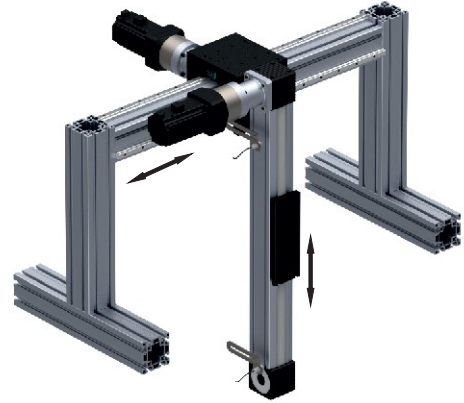
Technical Details



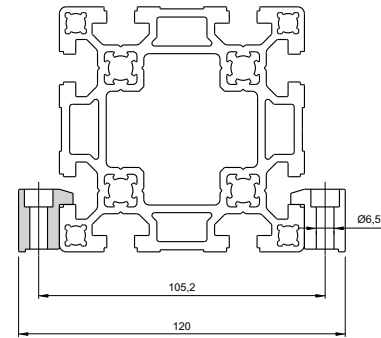
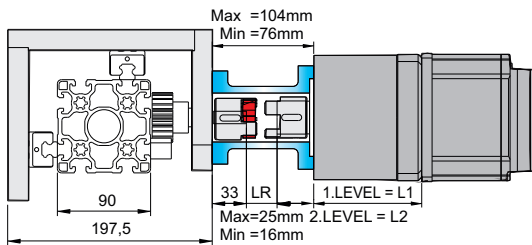
Applications



Reducer Connection Detail



Connection Dimensions

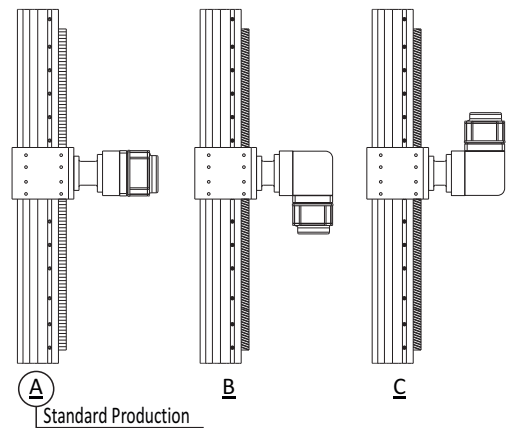


SESAME REDUCER TYPE	L1	L2
PEC 90 (750W -1kW - For use)	75 mm	115 mm
PEC 120 (1W -1.5kW - For use)	88 mm	136 mm

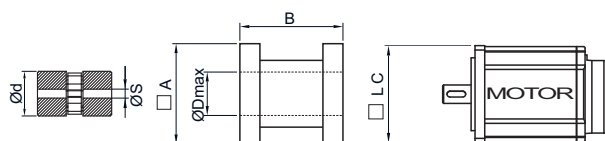
Planetary Gearbox Cycle Rates

- 1.LEVEL : 3-4-5-7-10
- 2.LEVEL : 15-20-25-30-35-40-50-70-100
- Maximum Tork PEC 90 : 171 Nm
- Maximum Tork PEC 120 : 509 Nm
- Maximum Tork : 6000 rpm

Drive Direction Options



Coupling & Flange Selection



KAPLiN	Ød	ØS	FLANŞ	A	B	ØDmax	LC
JM 40	40	8 - 22	85x 85	65 - 85	80 - 90	47	65 - 85
JM 55	55	8 - 28	95 x 95	80 - 95	94 - 104	60	70 - 95
JM 65	65	10 - 38	120 x 120	85 - 120	90 - 100	65	85 - 120

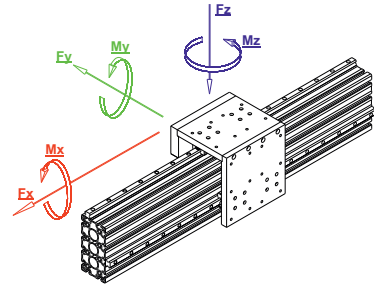
Types of Acupulation





Product code : 5.4.08.090180.2.03.2.Strok

Upload Values



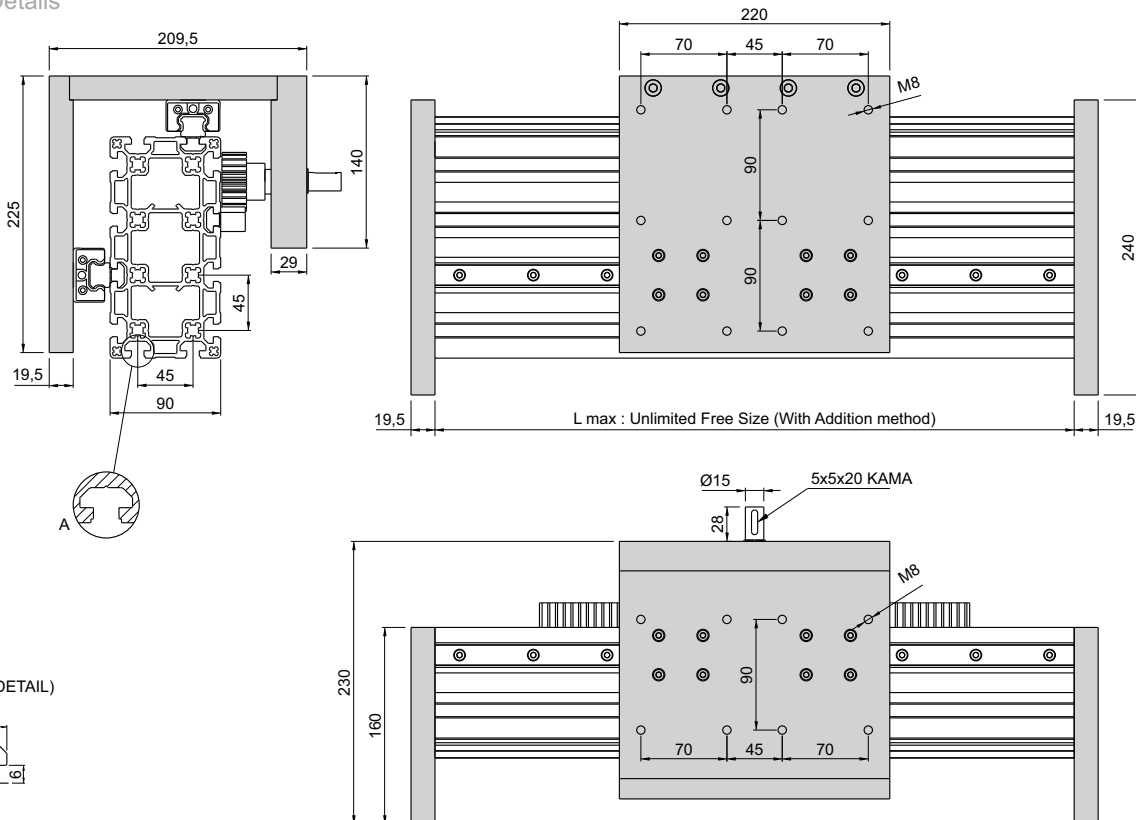
Load		Dynamic
■ Fx	(N)	1650
■ Fy	(N)	2450
■ Fz	(N)	3850
Moment		
■ Mx	(Nm)	390
■ My	(Nm)	1613
■ Mz	(Nm)	2470

Technical Specifications

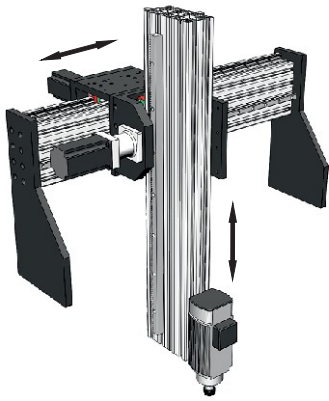
Body	:	90x180 Profile (Aluminum 6063)
Movement Speed	:	3 mt/sn
Movement Distance Per Tour (pitch)	:	138,16 mm
Rack and Pinion	:	Mod:2 Düz / Mod:2 Helisel
Pinion Gear	:	Mod:2 Z:22 Düz / Mod:2 Z:20 Helisel
Linear Rail	:	20 lik Linear rail
Linear Block	:	20 - Narrow Linear Car
Positioning Accuracy	:	0,2 mm
Basic Weight With Zero Strok	:	16,02 kg
Weight 1000mm Stroke	:	38,33 kg
Automation Control System	:	400 / 750 / 1kw Omron Servo + PLC + Pano

Note: Depending on the operating sensitivity, Asynchronous, Step, Induction, etc. It can be driven by motors.

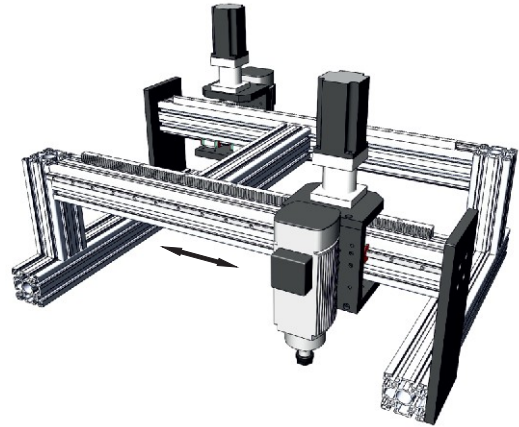
Technical Details



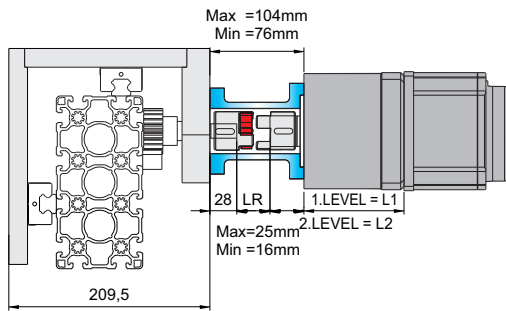
Applications



Reducer Connection Detail



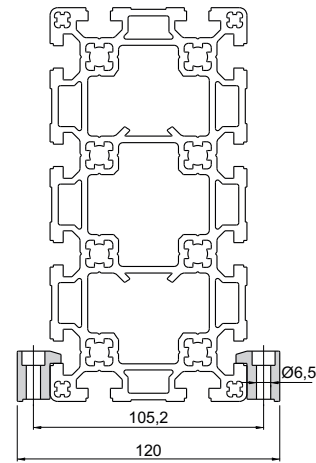
Connection Dimensions



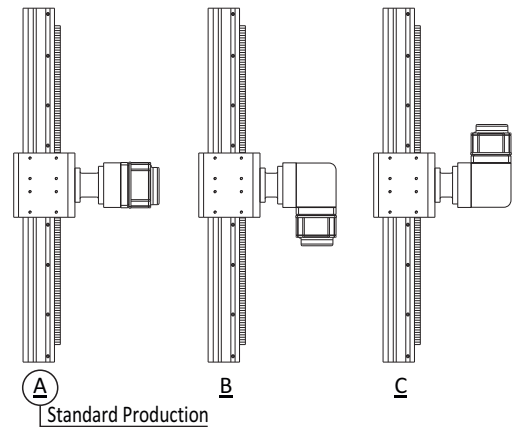
SESAME REDUCER TYPE	L1	L2
PEC 90 (750W -1kW - For use)	75 mm	115 mm
PEC 120 (1W -1.5kW - For use)	88 mm	136 mm

Planetary Gearbox Cycle Rates

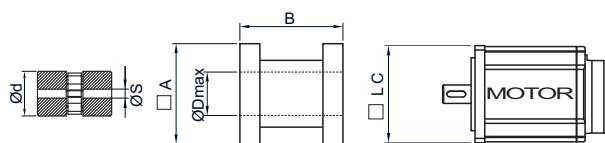
1.LEVEL : 3-4-5-7-10
 2.LEVEL : 15-20-25-30-35-40-50-70-100
 Maximum Tork PEC 90 : 171 Nm
 Maximum Tork PEC 120 : 509 Nm
 Maximum Tork : 6000 rpm



Drive Direction Options

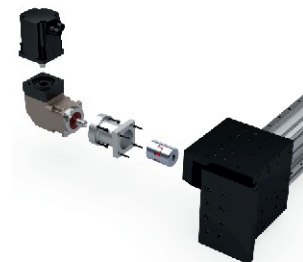


Coupling & Flange Selection



KAPLİN	Ød	ØS	FLANŞ	A	B	ØDmax	LC
JM 40	40	8 - 22	85x 85	65 - 85	80 - 90	47	65 - 85
JM 55	55	8 - 28	95 x 95	80 - 95	94 - 104	60	70 - 95
JM 65	65	10 - 38	120 x 120	85 - 120	90 - 100	65	85 - 120

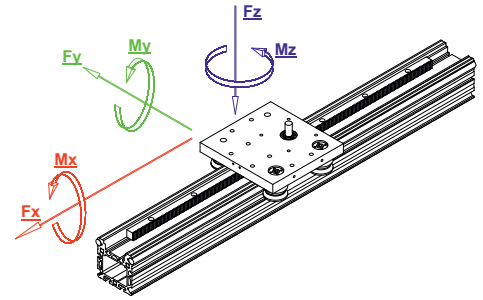
Types of Acupulation





Product code : 5.4.08.080080.1.01.2.Strok

Upload Values



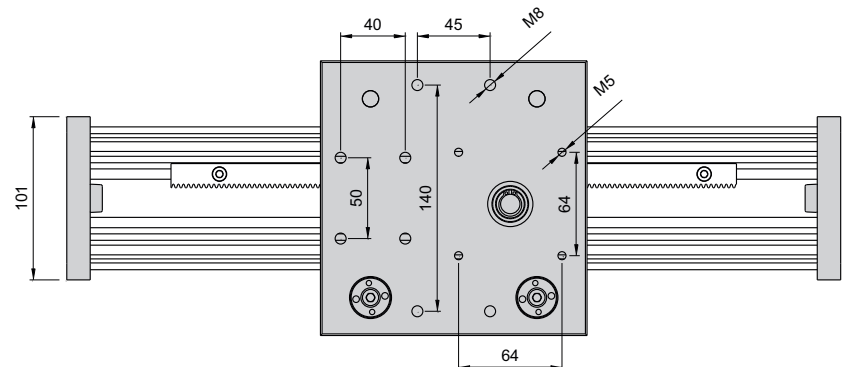
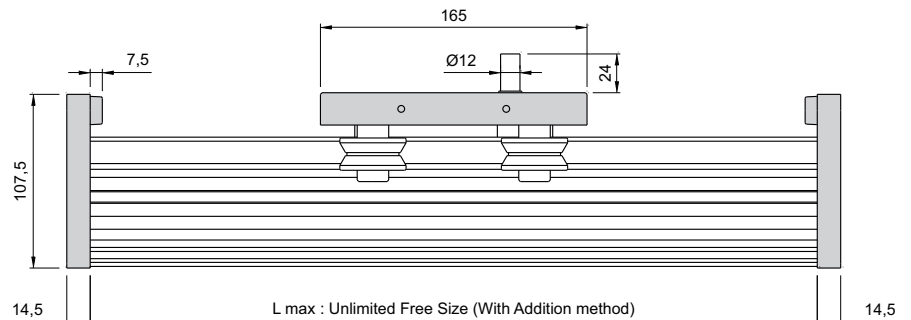
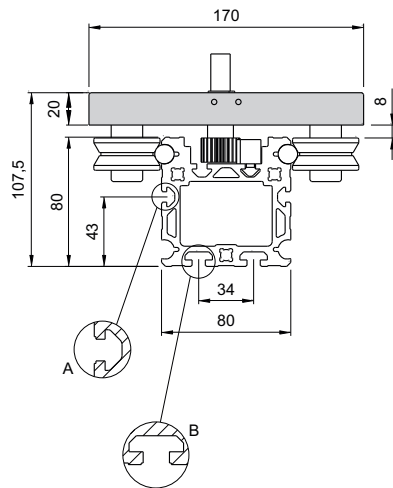
Load		Dynamic
■ Fx	(N)	780
■ Fy	(N)	2100
■ Fz	(N)	1880
Moment		
■ Mx	(Nm)	150
■ My	(Nm)	165
■ Mz	(Nm)	175

Technical Specifications

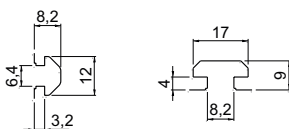
Body	: 80x80 Profile (Aluminum 6063)
Movement Speed	: 4 mt/sn
Movement Distance Per Tour (pitch)	: 69,08 mm
Rack and Pinion	: Mod:1 Düz
Pinion Gear	: Mod:1 Z:22 Düz
Linear Rail	: Ø12 Krom Kaplı (0.2 - 0,30 µm) İndüksiyonlu Mil 60-62 HRC h7
Linear Block	: RV 201-12 KDD
Positioning Accuracy	: 0,2 mm
Basic Weight With Zero Strok	: 4,78 kg
Weight 1000mm Stroke	: 13,84 kg
Automation Control System	: 400 / 750 / 1kw Omron Servo + PLC + Pano

Note: Depending on the operating sensitivity, Asynchronous, Step, Induction, etc. It can be driven by motors.

Technical Details



A (CHANNEL DETAIL) B (CHANNEL DETAIL)

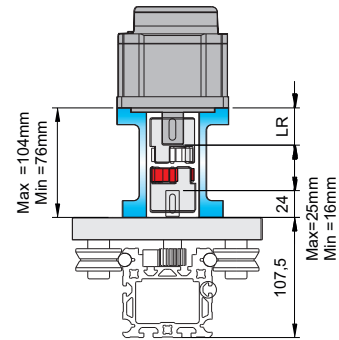
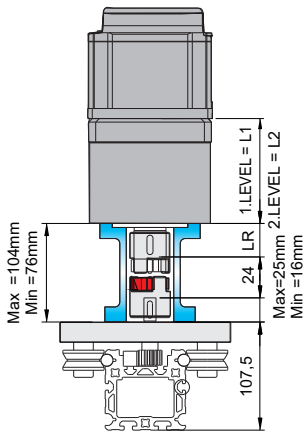


Applications



Reducer Connection Detail

Motor Connection Detail

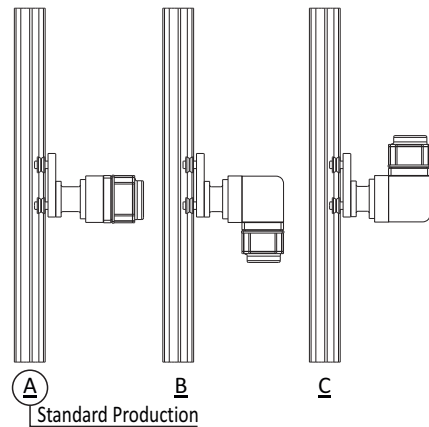


SESAME REDUCER TYPE	L1	L2
PEC 70 (400W For use)	64 mm	92 mm
PEC 90 (750W -1KW - For use)	75 mm	115 mm

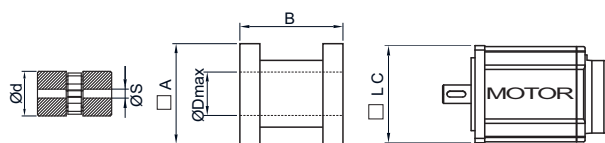
Planetary Gearbox Cycle Rates

1.LEVEL : 3-4-5-7-10
 2.LEVEL : 15-20-25-30-35-40-50-70-100
 Maximum Tork PEC 70 : 79 Nm
 Maximum Tork PEC 90 : 171 Nm
 Maximum Devir : 6000 rpm

Drive Direction Options



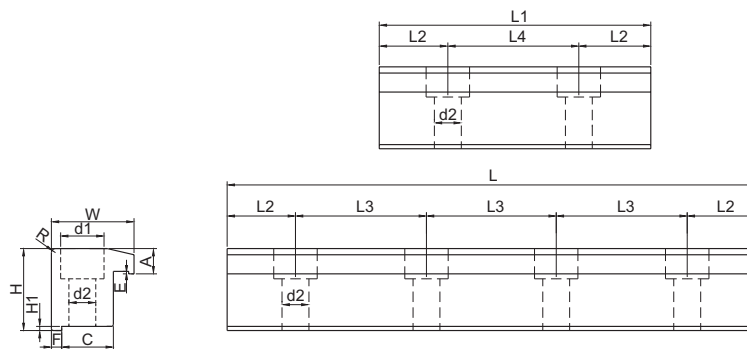
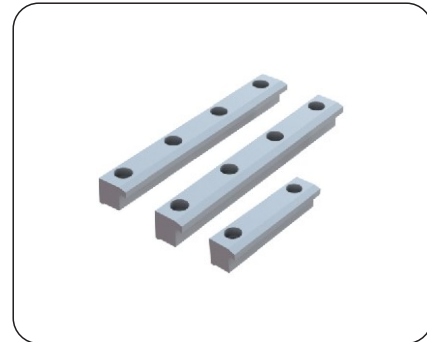
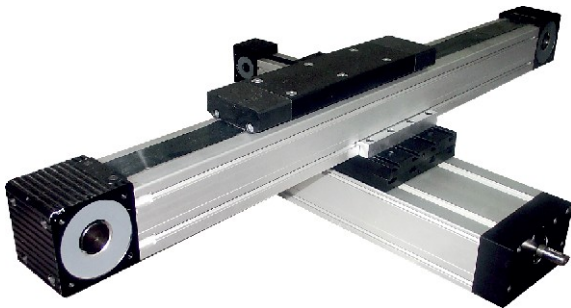
Coupling & Flange Selection



KAPLiN	Ød	ØS	FLANŞ	A	B	ØDmax	LC
JM 40	40	8 - 22	85x 85	65 - 85	80 - 90	47	65 - 85
JM 55	55	8 - 28	95 x 95	80 - 95	94 - 104	60	70 - 95

Types of Acupulation

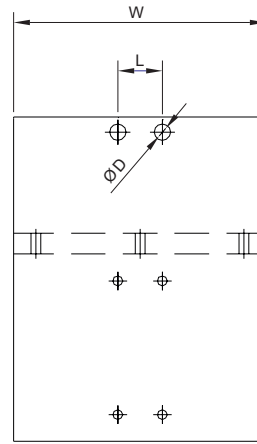
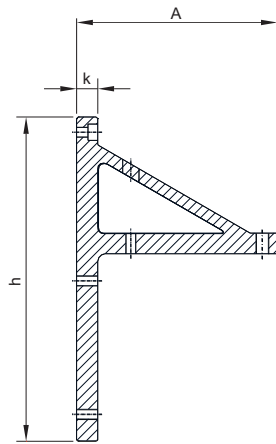
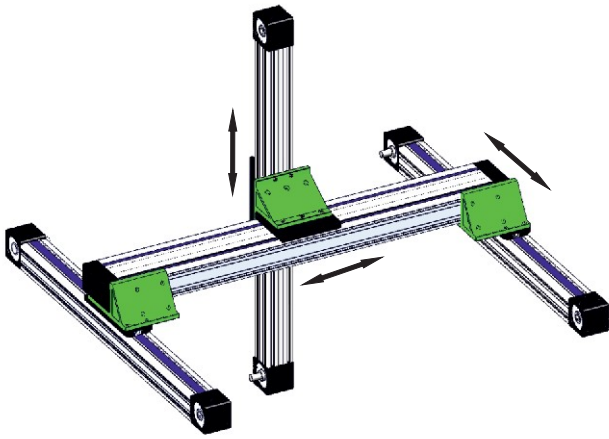




CODE	MODEL	H	H1	d2	d1	E	A	R	W	C	L	L1	L2	L3	L4	F
7.26.080064.000000.00.10	80 x 80 - 64 x 64 Module Connecting Part	19,8	1	6,5	10,5	0,5	6	0,5	20	12,5	160	-	12,5	45	60	2,5
7.26.100100.000000.00.10	100 x 100 Module Connecting Part	30,3	1	6,5	10,5	0,5	6	0,5	20	12,5	-	85	12,5	-	60	2,5
7.26.045045.000000.00.10	45 x 45 Module Connecting Part	22,9	1	6,5	10,5	-	5,5	0,5	20	12,5	-	85	12,5	-	60	2,5
7.26.080160.000000.00.10	80 x 160 Module Connecting Part	14,3	1	6,5	10,5	0,5	6	0,5	20	12,5	160	-	12,5	45	60	2,5
7.26.065145.000000.00.10	65 x 145 Module Connecting Part	14,5	1	6,5	10,5	0,5	6	0,5	20	12,5	145	-	12,5	40	-	2,5
7.26.050110.000000.00.10	50 x 110 Module Connecting Part	10,5	1	6,5	10,5	0,5	6	0,5	20	12,5	-	60	10	-	40	2,5

Using Area

It is a piece of equipment that provides a very practical connection to another module or plate by using the T-slots in the modules.



CODE	Bağlantı Yeri	h	ØD	k	W	A	L
7.26.080064.000000.01.10	80x80 - 64x64 Module Axis Connecting	218	8,5	18	170	110	30
7.26.080160.000000.01.10	80x80 - 80x160 Module Axis Connecting	218	8,5	18	210	110	60
7.26.100100.000000.01.10	100x100 - 100x100 Module bridge Axis Connecting	218	8,5	18	210	132	75
7.26.080160.080080.01.10	80x160 - 80x80 Module 3 Axis Connecting	218	6,5	18	170	140	60

Using Area

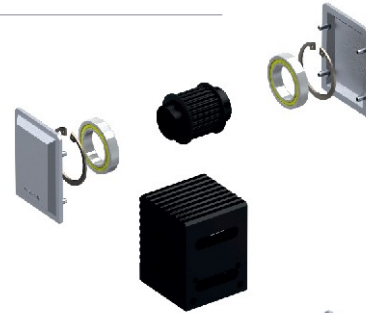
The 'two-axis connection piece' made of monobloc aluminum die-cast material enables the rigid connection of your modules in the square casting body and federated structure dampens vibrations. This system obtained by joining two separate plates with bolts; abor, time and costsavings.



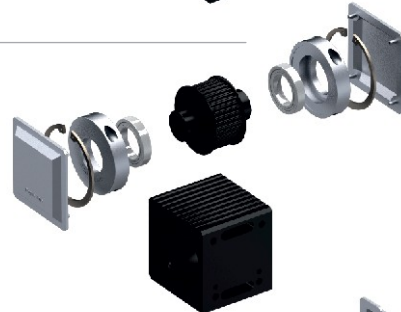
38x50 Covers



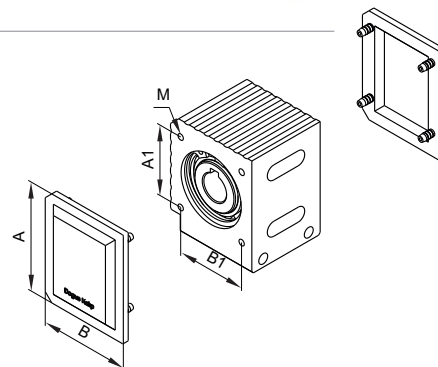
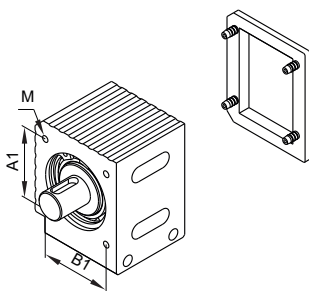
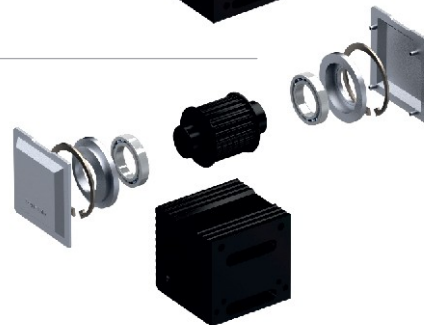
64x64 Covers



80x80 Covers



100x100 Covers



CODE	STOCK NAME	A	B	A1	B1	M
5.1.2.038050.4260.03	38x50 Triger Head with Hole	58	48	37,5	37,5	4
5.1.2.038050.4260.04	38x50 Triger Head Shaft	58	48	37,5	37,5	4
5.1.2.064064.0015.03	64x64 Triger Head with Hole	82,5	64	45	54	5
5.1.2.064064.0015.04	64x64 Triger Head Shaft	82,5	64	45	54	5
5.1.2.080080.0020.03	80x80 Triger Head With Drive Hole	84	84	64	64	5
5.1.2.080080.0020.04	80x80 Triger Head Drive Shaft	84	84	64	64	5
5.1.2.090180.0203.03	100x100 Triger Head with Hole	98	98	71	71	6
5.1.2.090180.0203.04	100x100 TTriger Head Shaft	98	98	71	71	6

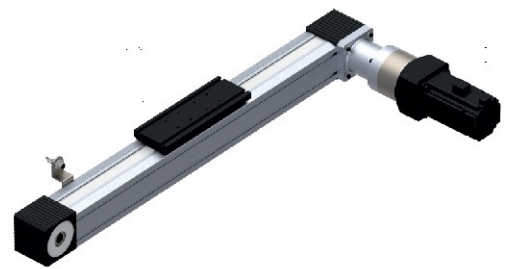
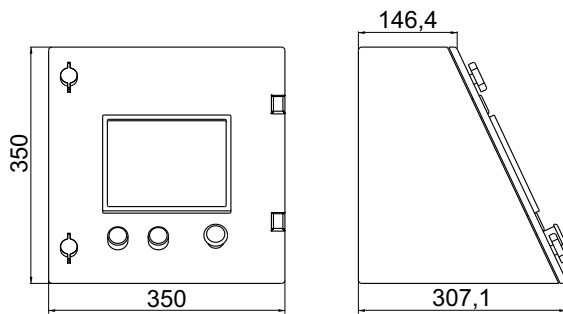
Module equipment

Technical Specifications



GENERAL FEATURES:

- 1- Fast completion of steps thanks to 3000rpm motors
- 2- Comfortable use with easy HMI interface
- 3- Waiting with temporal and contact between steps
- 4- Ability to process step intervals in a single axis system
- 5- Repeat the same operation in the desired amount thanks to the continuous operating mode
- 6- Ability to allow different combinations for each step
- 7- Efficient vibration-free movements thanks to highly capable servos

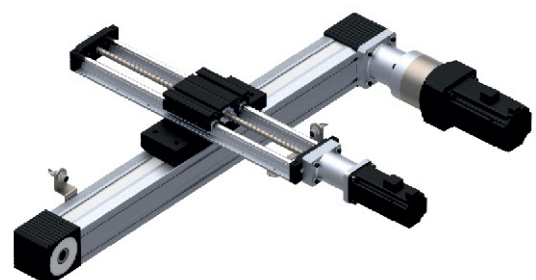
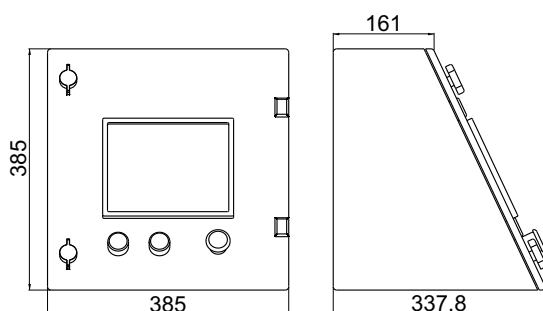


Technical Specifications

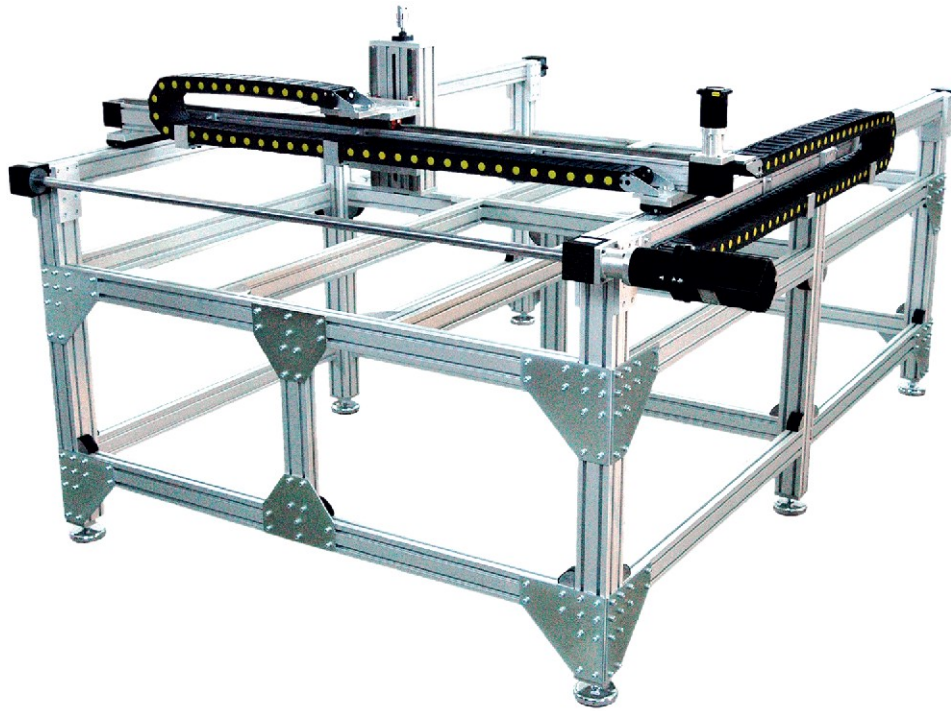


GENERAL FEATURES:

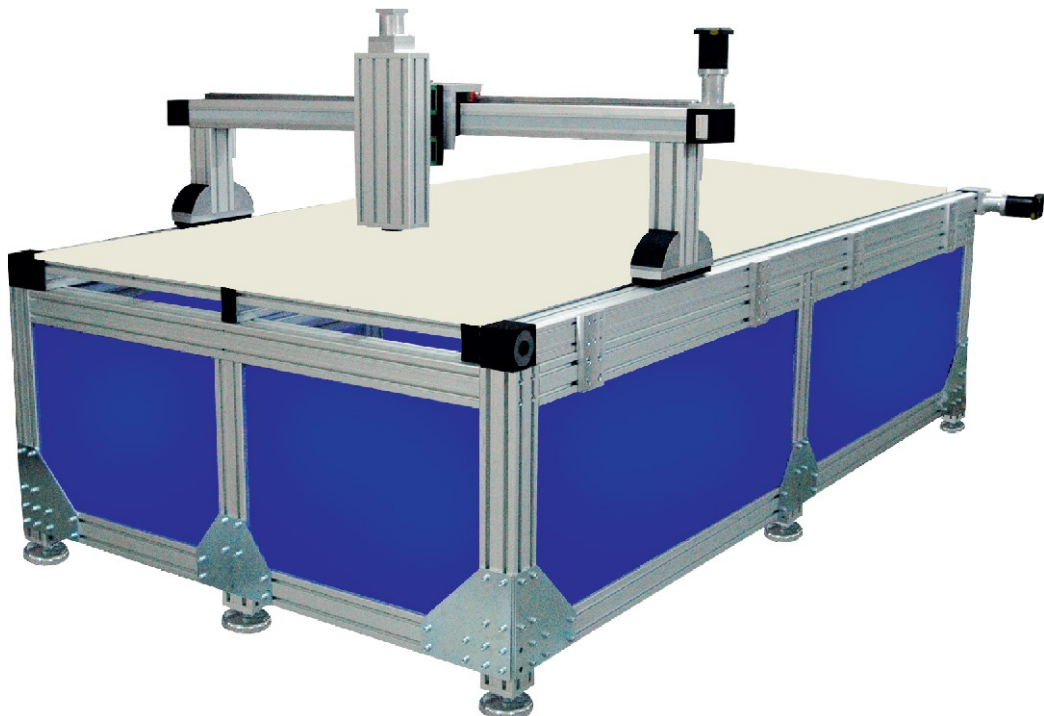
- 1- Fast completion of steps thanks to 3000rpm motors
- 2- Comfortable use with easy HMI interface
- 3- Waiting with temporal and contact between steps
- 4- Two-axis system able to operate in the desired step range
- 5- Repeat the same operation in the desired amount thanks to the continuous operating mode
- 6- Ability to allow different combinations for each step
- 7- Efficient vibration-free movements thanks to highly capable servos



3 Axial CNC Bench



Furniture-wood Processing CNC Machine Bench



S-CNC-RV1 / RV2 / RV3

GENERAL FEATURES:

- 1- Wood, plastic, plexiglass, aluminum, styrofoam, etc.
- 2- 15 Linear rail and 4 piece linear block
- 3- Ø16-05 ball bearing ball screw drive
- 4- Precision aluminum construction Body and module system
- 5- DKZM -15 z -axial module
- 6- Optional 3 axis motor coupling (servo/step)
- 7- 22,5x180 T slot nut aluminum tray



		Working places		
CODE	MODEL	X	Y	Z
5.9.1.1.0350.0350.0100	S-CNC-RV1	350 mm	350 mm	100 mm
5.9.1.1.0500.0350.0100	S-CNC-RV2	500 mm	350 mm	100 mm
5.9.1.1.0500.0530.0100	S-CNC-RV3	500 mm	530 mm	100 mm

S-CNC-LV1 / LV2 / LV3

GENERAL FEATURES:

- 1- Wood, plastic, plexiglass, aluminum, styrofoam, etc.
- 2- Ø16 hardened chrome shaft and 4 piece linear bearing
- 3- Ø16-05 ball bearing ball screw drive
- 4- Precision aluminum construction Body and module system
- 5- DKZM -16 Z-axial module
- 6- Optional 3 axis motor coupling (servo/step)
- 7- 15x120 T slot nut aluminum tray



		Working places		
CODE	MODEL	X	Y	Z
5.9.1.2.0350.0350.0100	S-CNC-LV1	350 mm	350 mm	100 mm
5.9.1.2.0500.0350.0100	S-CNC-LV2	500 mm	350 mm	100 mm
5.9.1.2.0500.0470.0100	S-CNC-LV3	500 mm	470 mm	100 mm

* Mechanical products are provided to your designs.

M-CNC-RV1 / RV2

GENERAL FEATURES:

- 1- Wood, plastic, plexiglass, aluminum, styrofoam, etc.
- 2- 20 Linear rail and 4 piece linear block
- 3- Ø25-10 ball bearing ball screw drive (X Axial)
- 4- Precision, rigid aluminum construction Body and module system
- 5- DKZM -15 z -axial module
- 6- Optional 3 axis motor coupling (servo/step)
- 7- 22,5x180 T slot nut aluminum tray

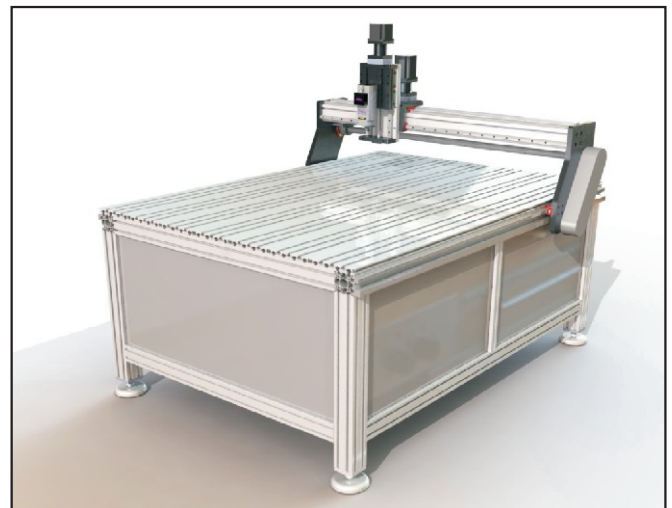


CODE	MODEL	Working places		
		X	Y	Z
5.9.2.1.1000.1000.0150	M-CNC-RV1	1000 mm	1000 mm	150 mm
5.9.2.1.1500.1000.0150	M-CNC-RV2	1500 mm	1000 mm	150 mm
5.9.2.1.2100.1000.0150	M-CNC-RV3	2100 mm	1000 mm	150 mm
5.9.2.1.2100.1500.0150	M-CNC-RV4	2100 mm	1540 mm	150 mm

M-CNC-KR1 / KR2

GENERAL FEATURES:

- 1- Wood, plastic, plexiglass, aluminum, styrofoam, etc.
- 2- Center-shaped chassis design for special applications (platina cut, laser cut, water jet cut)
- 3- 20 Linear rail and 4 piece linear block
- 4- Mod 1,5 gear rack / z 22 pinion (x/y axial)
- 5- DKZM -20 Z-Axial module
- 6- Precision, rigid aluminum construction Body and module system
- 7- Optional 3 axis motor coupling (servo/step)
- 8- Optional 22,5x180 T slot nut aluminum tray



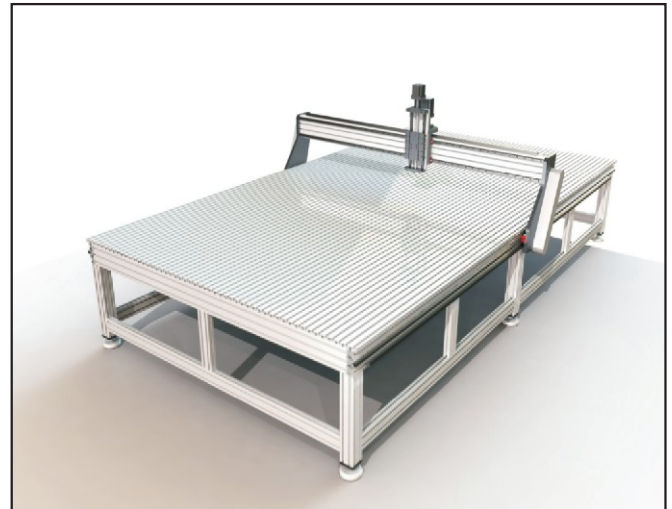
CODE	MODEL	Working places		
		X	Y	Z
5.9.2.2.1500.1000.0150	M-CNC-KR1	1500 mm	1045 mm	150 mm
5.9.2.2.2100.1000.0150	M-CNC-KR2	2100 mm	1000 mm	150 mm
5.9.2.2.2100.1500.0150	M-CNC-KR3	2100 mm	1585 mm	150 mm

* Mechanical products are provided to your designs.

L-CNC- KR1 / KR2

GENERAL FEATURES:

- 1- Wood, plastic, plexiglass, aluminum, styrofoam, etc.
- 2- 20 Linear rail and 4 piece linear block
- 3- Mod 2 rack / pinion (X-Y Axial)
- 4- Precision, rigid aluminum construction Body and module system
- 5- DKZM -20 Z -Axial module
- 6- Optional 3 axis motor coupling (servo/step)
- 7- 22,5x180 T slot nut aluminum tray

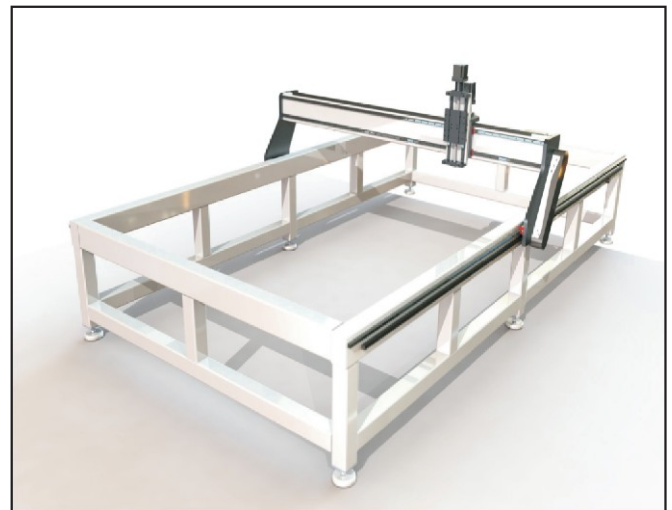


		Working places		
CODE	MODEL	X	Y	Z
5.9.3.1.3000.1500.0200	L-CNC-KR1	3000 mm	1560 mm	200 mm
5.9.3.1.4000.2100.0200	L-CNC-KR2	4000 mm	2100 mm	200 mm
5.9.3.1.6000.2100.0200	L-CNC-KR3	6000 mm	2100 mm	200 mm
5.9.3.1.6000.4000.0200	L-CNC-KR4	6000 mm	4080 mm	200 mm

L-CNC-CL1 / CL2

GENERAL FEATURES:

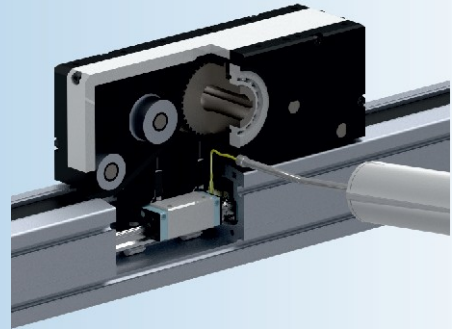
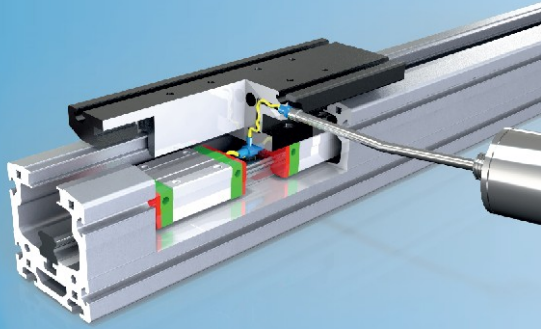
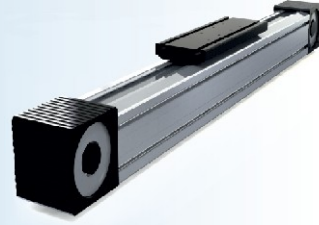
- 1- Wood, plastic, plexiglass, aluminum, styrofoam, etc.
- 2- Center-shaped chassis design for special applications (platina cut, laser cut, water jet cut)
- 3- Linear rail and 4 piece linear block
- 4- Rack / pinion gear drive
- 5- Robust and rigid steel construction Body
- 6- DKZM -20 Z-Axial module
- 7- Optional 3 axis motor coupling (servo/step)



		Working places		
CODE	MODEL	X	Y	Z
5.9.3.2.3000.1500.0200	L-CNC-CL1	3000 mm	1500 mm	200 mm
5.9.3.2.4000.2100.0200	L-CNC-CL2	4000 mm	2100 mm	200 mm
5.9.3.2.6000.2100.0200	L-CNC-CL3	6000 mm	2100 mm	200 mm
5.9.3.2.6000.4000.0200	L-CNC-CL4	6000 mm	4000 mm	200 mm

* Mechanical products are provided to your designs.

LUBRICATION IN TRIGER BELT SYSTEMS



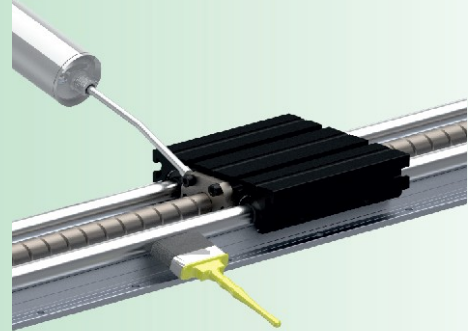
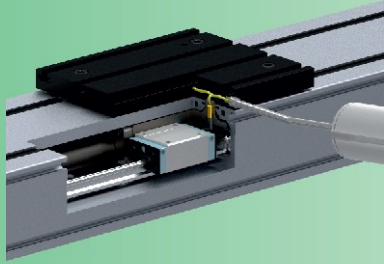
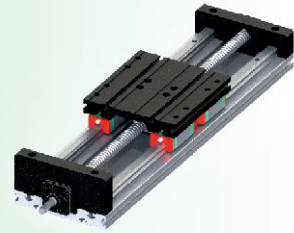
PERIODIC MAINTENANCE PLAN					
Daily Usage Time		Maintenance Period			
24 hours		1 per month			
24 hours		1 per in 2 months			
8 hours		1 per in 4 months			
Oils to be used in standard applications under the 1mt /sn		Oils to be used at high speed up to 1 mt/sn		Surface or induction shaft oil	
Greas	Supergres EP1	Greas	Supergres EP2	Liquid Oil	Vactra No2S
	Neogrease LH1		Neogrease LS2		Mobile DTE Oil Light

MAINTENANCE INSTRUCTIONS

- 1- Lubrication on the top plate of the modules lubrication is done by attaching a grease pump to the grease cup.
- 2- By lubricating the induction shafts with thin oil the module is moved back and forth and lubrication is provided.
- 3- With the help of the gress pump, the glazing of linear cars back and forth to the module by spraying grease movement is made.
- 4- Oil in the seal slot in shielded and felt systems tightened. Seal oil to induction shafts and bearing transfers.
- 5- The bolts seems on the module are in the maintenance plan. The gap is removed by tightening in the specified periods.

In order for the systems to operate at maximum efficiency for many years, the lubrication and maintenance instructions should be followed regularly as shown in the above tables.

LUBRICATION IN BALL SCREW SYSTEMS

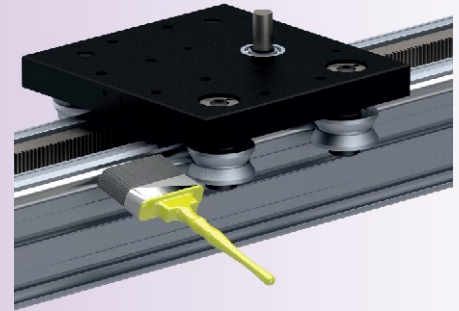
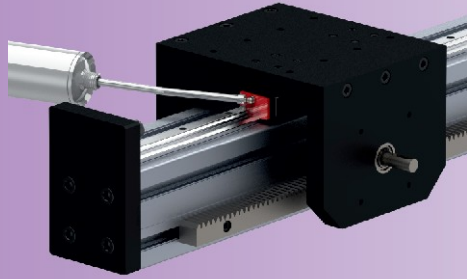
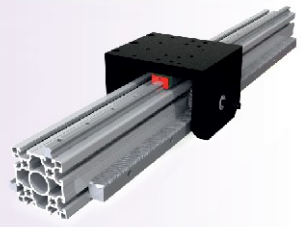


PERIODIC MAINTENANCE PLAN					
Daily Usage Time		Maintenance Period			
24 hours		1 per month			
24 hours		1 per in 2 months			
8 hours		1 per in 4 months			
Oils to be used in standard applications under the 1mt /sn		Oils to be used at high speed up to 1 mt/sn		Surface or induction shaft oil	
Greas	Supergres EP1	Greas	Supergres EP2	Liquid Oil	Vactra No2S
	Neogrease LH1		Neogrease LS2		Mobile DTE Oil Light

MAINTENANCE INSTRUCTIONS
1- Lubrication on the top plate of the modules lubrication is done by attaching a grease pump to the grease cup.
2- By lubricating the induction shafts with thin oil the module is moved back and forth and lubrication is provided.
3- With the help of the gress pump, the glazing of linear cars back and forth to the module by spraying grease movement is made.
4- Oil in the seal slot in shielded and felt systems tightened. Seal oil to induction shafts and bearing transfers.
5- The bolts seems on the module are in the maintenance plan. The gap is removed by tightening in the specified periods.

In order for the systems to operate at maximum efficiency for many years, the lubrication and maintenance instructions should be followed regularly as shown in the above tables.

LUBRICATION IN RACK SYSTEMS



PERIODIC MAINTENANCE PLAN					
Daily Usage Time		Maintenance Period			
24 hours		1 per month			
24 hours		1 per in 2 months			
8 hours		1 per in 4 months			
Oils to be used in standard applications under the 1mt /sn		Oils to be used at high speed up to 1 mt/sn		Surface or induction shaft oil	
Greases	Supergres EP1	Greases	Supergres EP2	Liquid Oil	Vactra No2S
	Neogrease LH1		Neogrease LS2		Mobile DTE Oil Light

MAINTENANCE INSTRUCTIONS

- 1- Lubrication on the top plate of the modules lubrication is done by attaching a grease pump to the grease cup.
- 2- By lubricating the induction shafts with thin oil the module is moved back and forth and lubrication is provided.
- 3- With the help of the gress pump, the glazing of linear cars back and forth to the module by spraying grease movement is made.
- 4- Oil in the seal slot in shielded and felt systems tightened. Seal oil to induction shafts and bearing transfers.
- 5- The bolts seems on the module are in the maintenance plan. The gap is removed by tightening in the specified periods.

In order for the systems to operate at maximum efficiency for many years, the lubrication and maintenance instructions should be followed regularly as shown in the above tables.

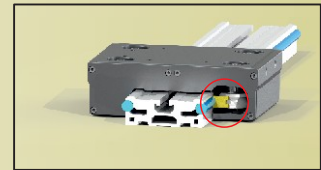
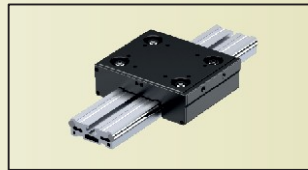
PROTECTION AND TRANSPORT IN LINEAR MOTION SYSTEMS

Bellow applicaiton



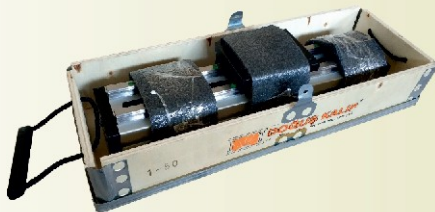
Thanks to the bellows applications, linear motion systems are protected at the maximum level and require less maintenance. The bellows type is determined according to the type of application and the environment conditions of the application. Thank to the bellows the life of linear system is extended. Please see page 2 module selection table for modules that can be applied bellows application.

Felt closed application



Thanksto these sealed closed systems, the bearing and blocks part of the manual systems are protected against external factors. This systems is easier to maintain and usage life will be longer.

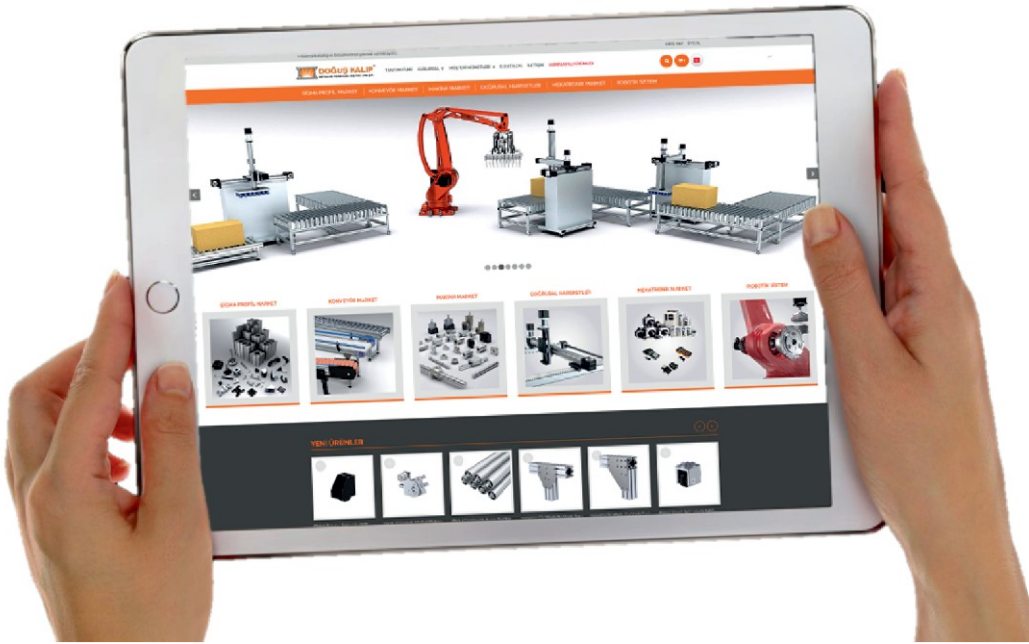
Transport boxes



We ship our modules in crates produced in product-specific dimensions for the production of safe transfer of our modules in national and international shipping.



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